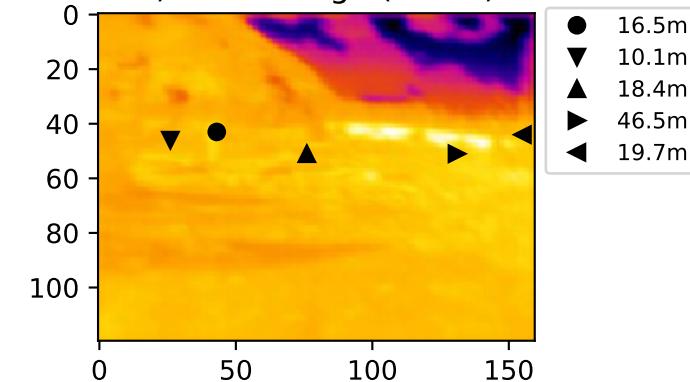
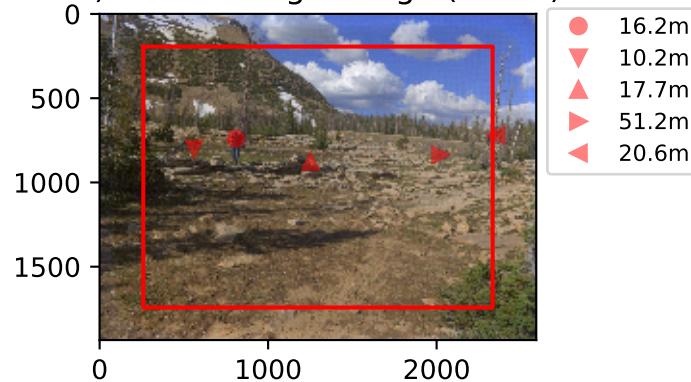


1562390202\_933097: Single person, trees.

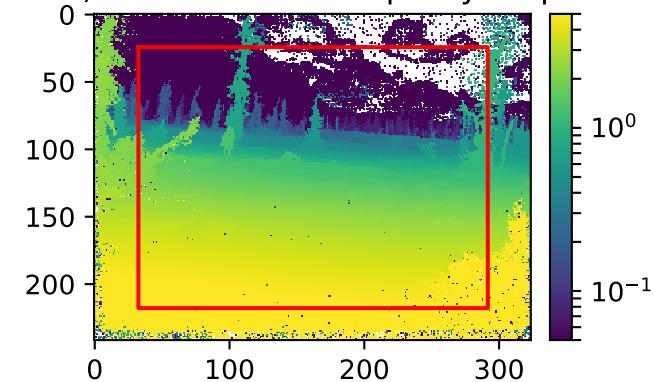
a) LWIR image (1 of 4)



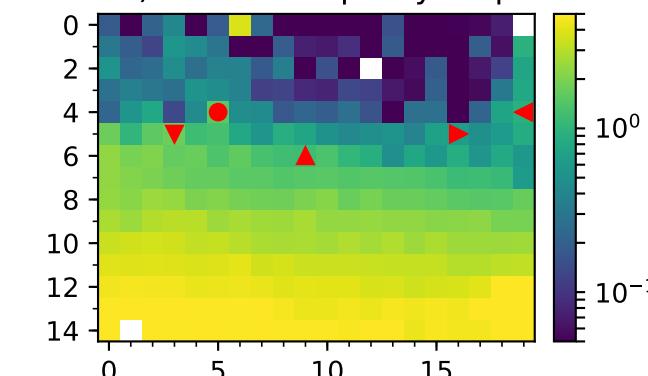
b) Visible range image (1 of 4)



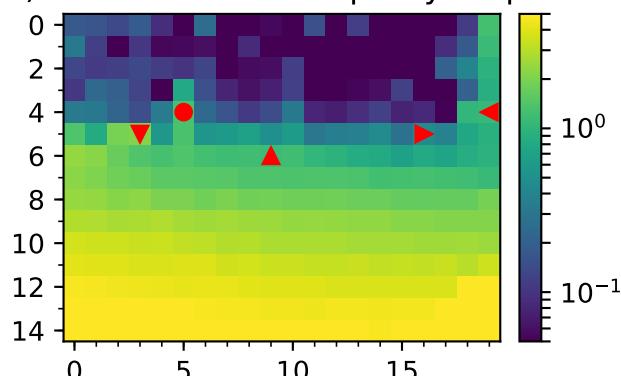
c) Hi-res camera disparity map



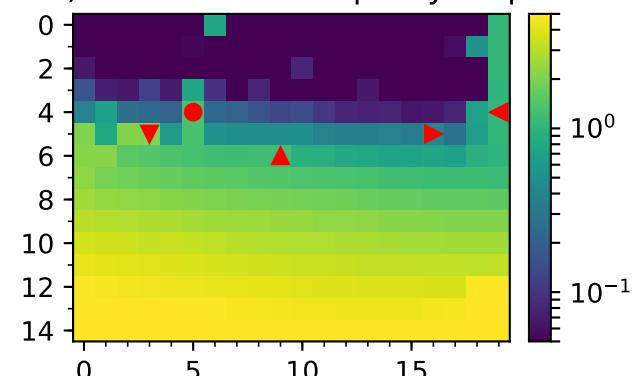
d) Non-NN disparity map



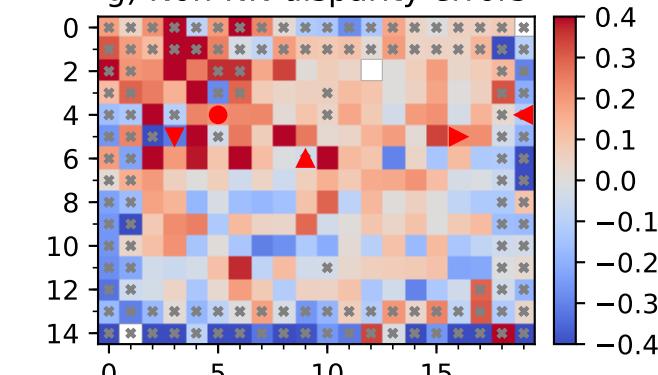
e) Neural network disparity output



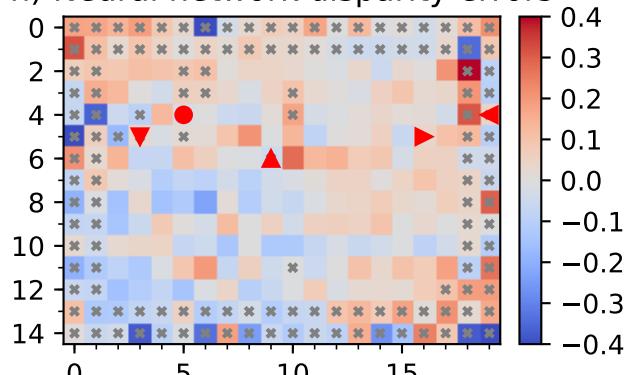
f) Ground truth disparity map



g) Non-NN disparity errors

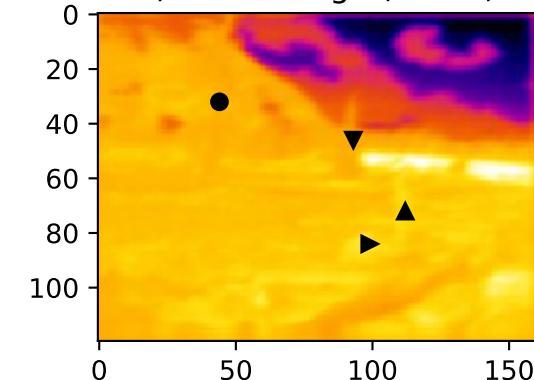


h) Neural network disparity errors

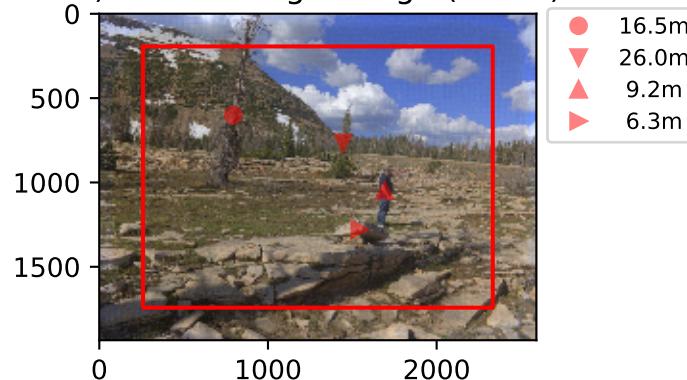


1562390225\_269784: Single person, trees.

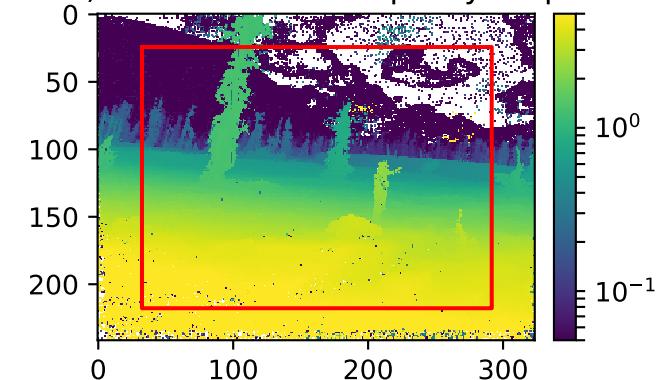
a) LWIR image (1 of 4)



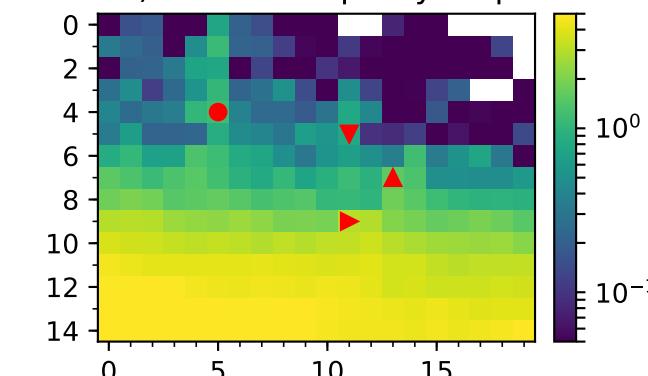
b) Visible range image (1 of 4)



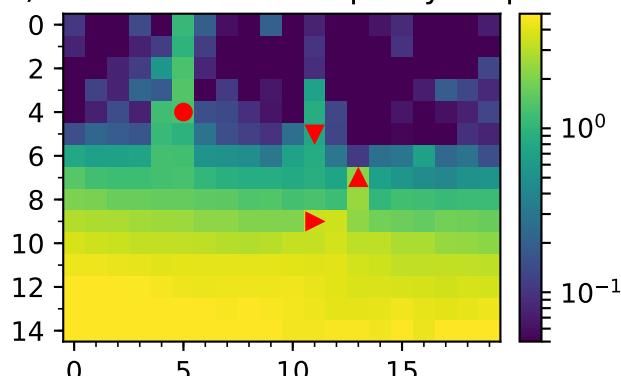
c) Hi-res camera disparity map



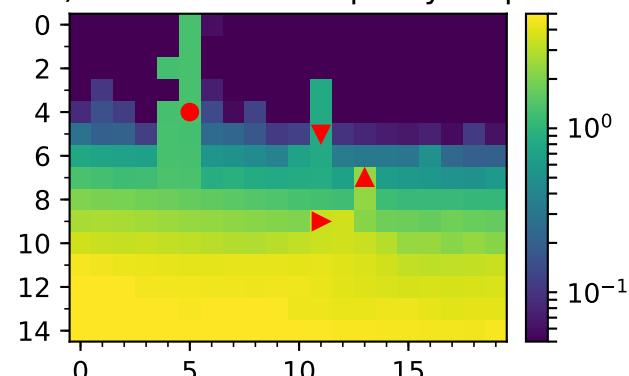
d) Non-NN disparity map



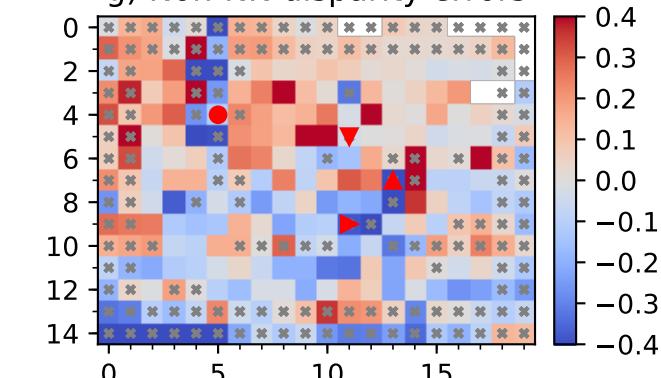
e) Neural network disparity output



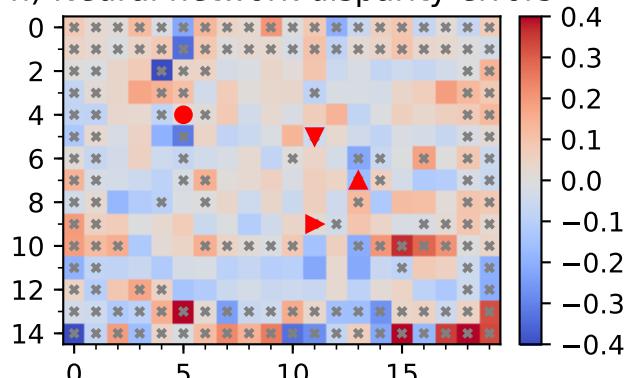
f) Ground truth disparity map



g) Non-NN disparity errors

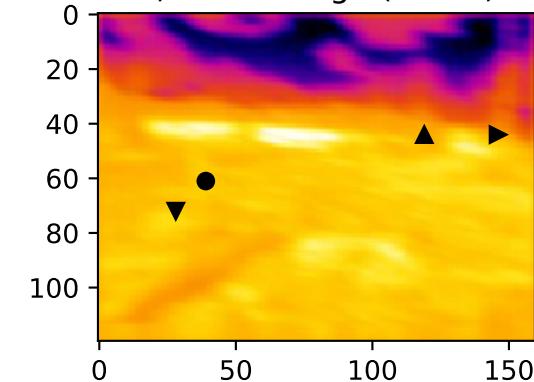


h) Neural network disparity errors

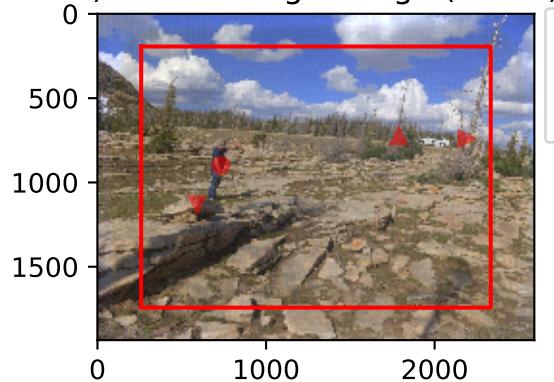


1562390225\_839538: Single person. Horizontal motion blur.

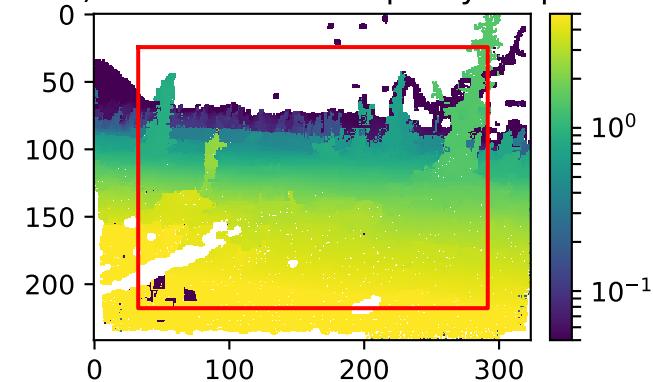
a) LWIR image (1 of 4)



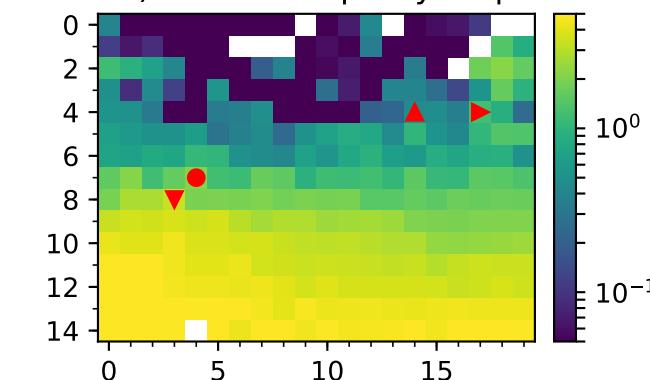
b) Visible range image (1 of 4)



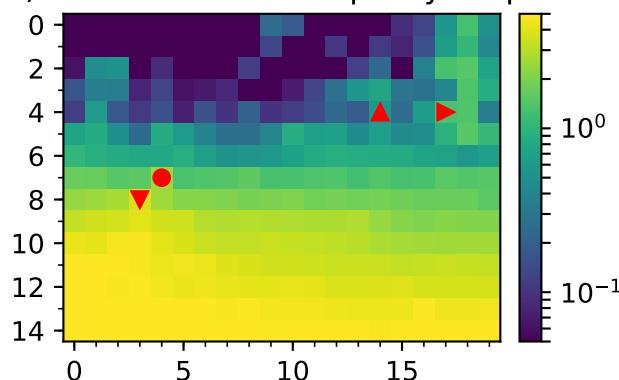
c) Hi-res camera disparity map



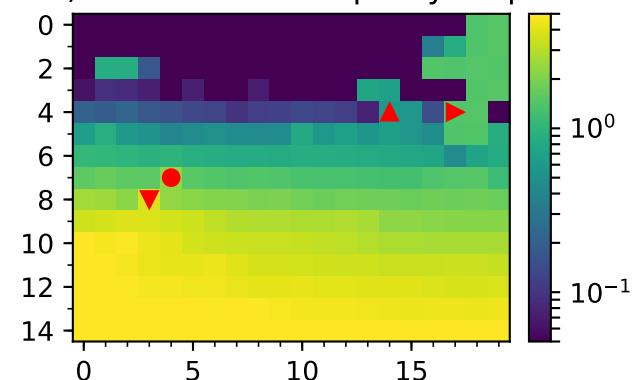
d) Non-NN disparity map



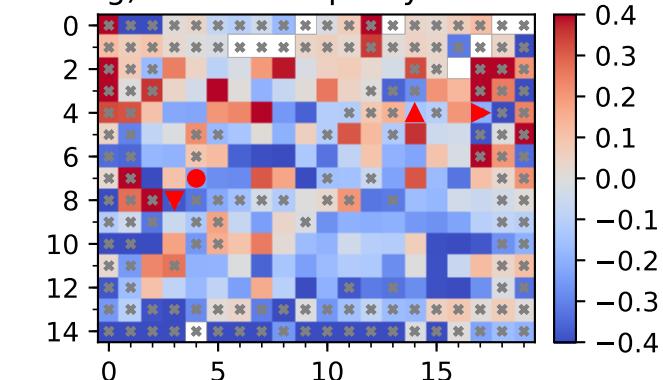
e) Neural network disparity output



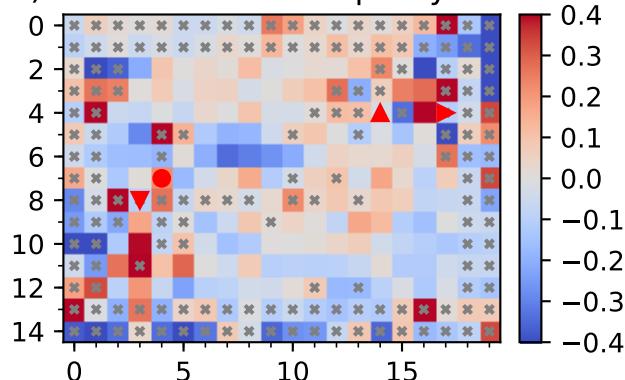
f) Ground truth disparity map



g) Non-NN disparity errors

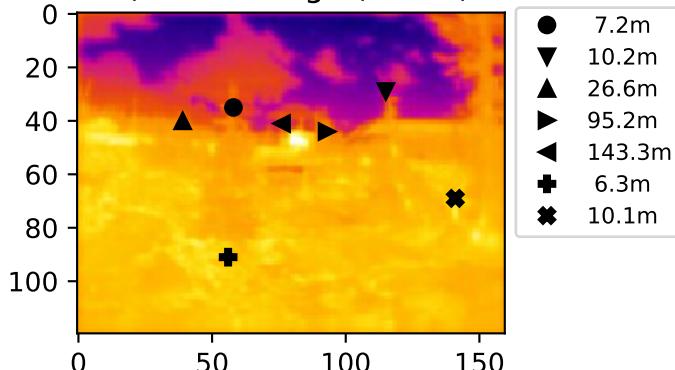


h) Neural network disparity errors

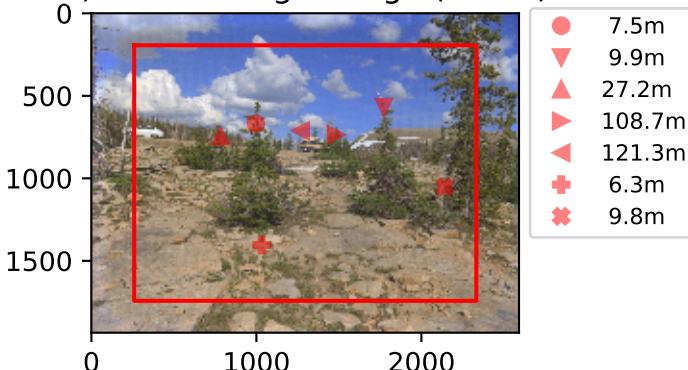


1562390243\_047919: No people, trees.

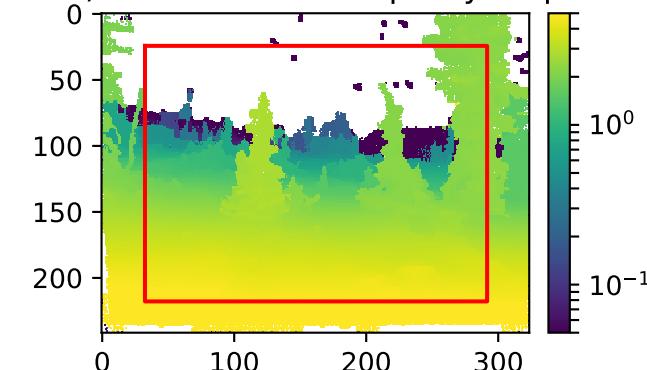
a) LWIR image (1 of 4)



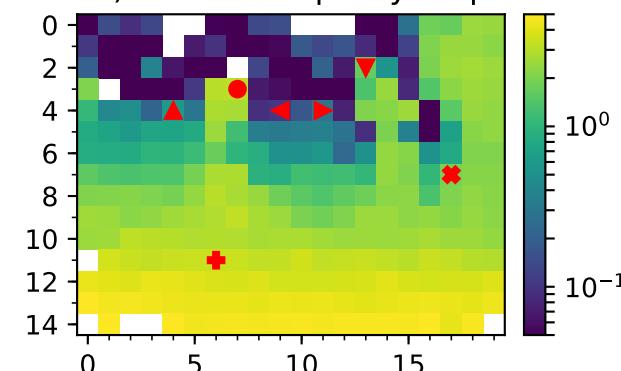
b) Visible range image (1 of 4)



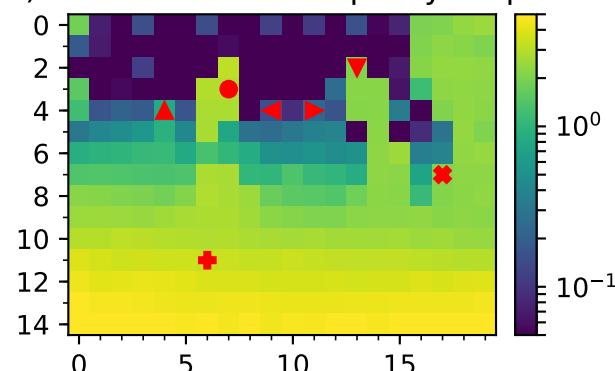
c) Hi-res camera disparity map



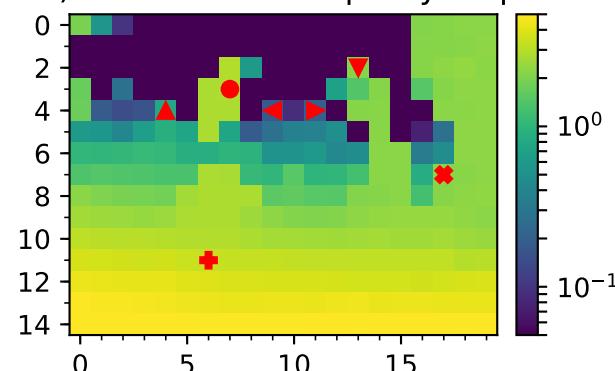
d) Non-NN disparity map



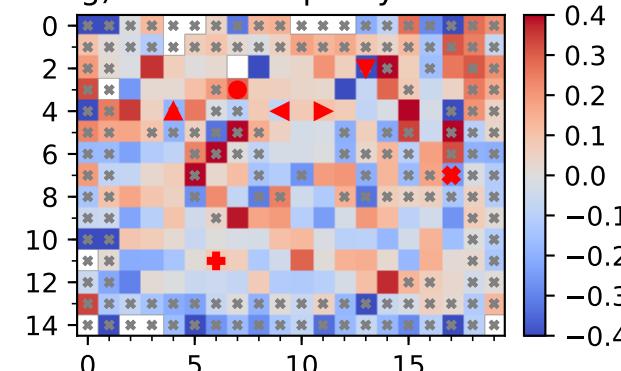
e) Neural network disparity output



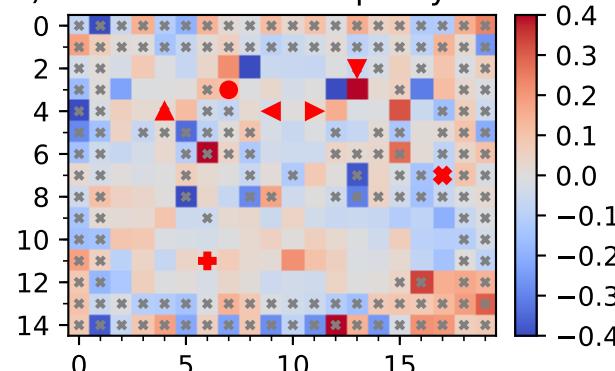
f) Ground truth disparity map



g) Non-NN disparity errors

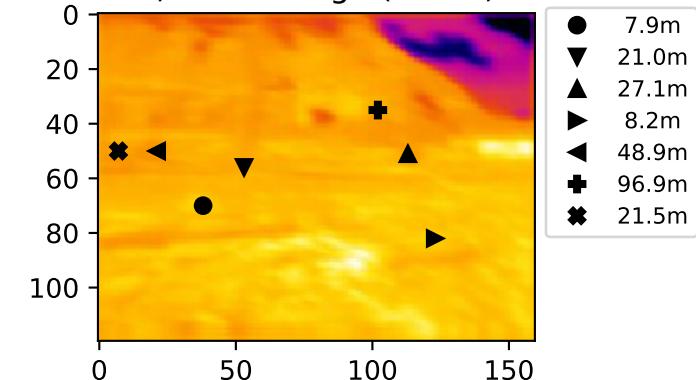


h) Neural network disparity errors

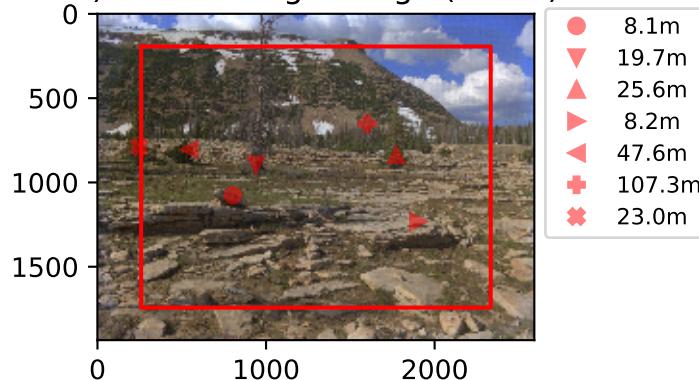


1562390251\_025390: Open space. Horizontal motion blur.

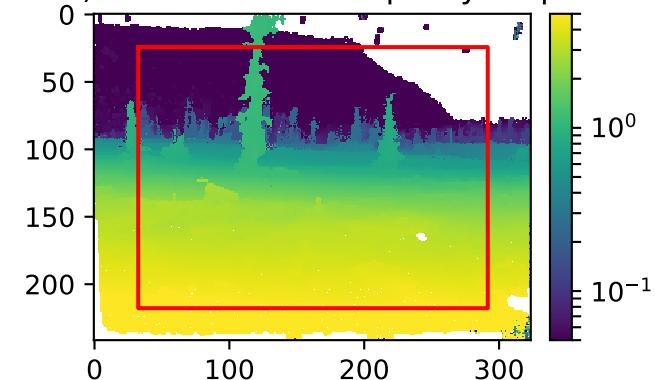
a) LWIR image (1 of 4)



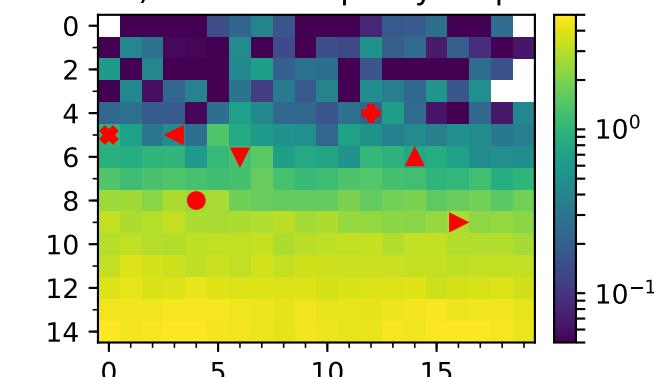
b) Visible range image (1 of 4)



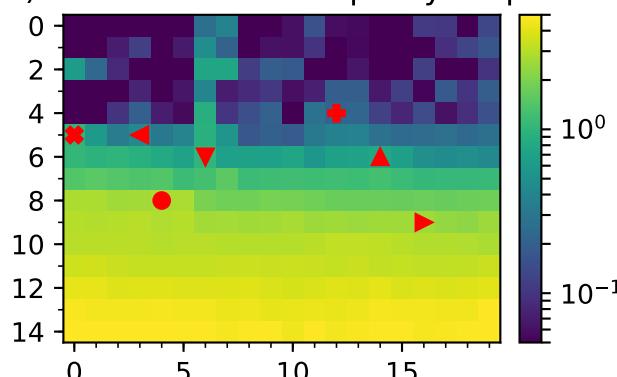
c) Hi-res camera disparity map



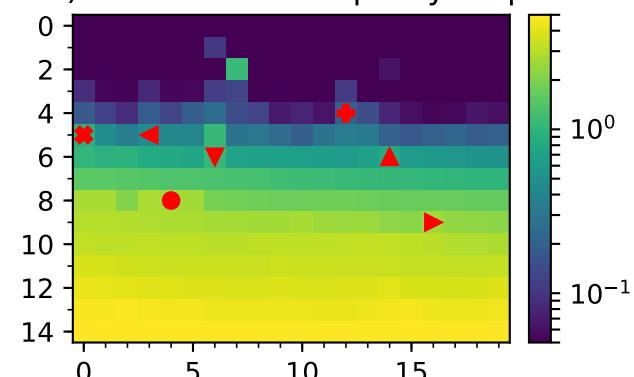
d) Non-NN disparity map



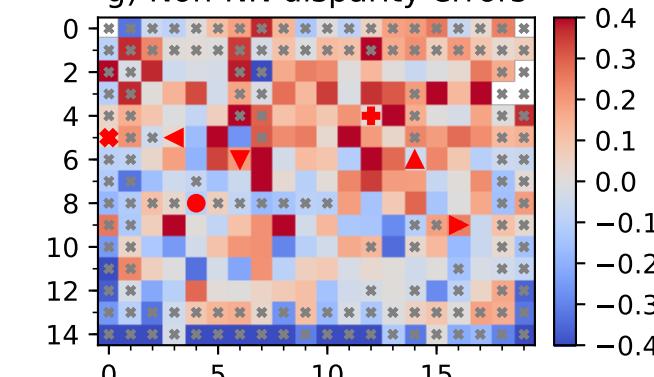
e) Neural network disparity output



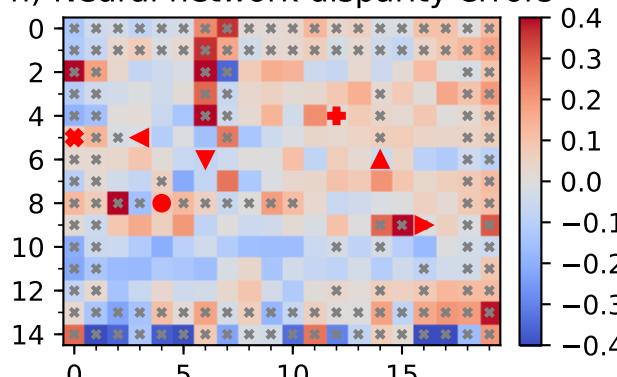
f) Ground truth disparity map



g) Non-NN disparity errors

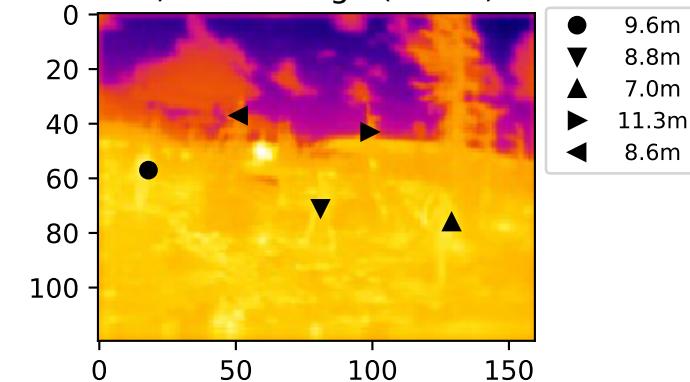


h) Neural network disparity errors

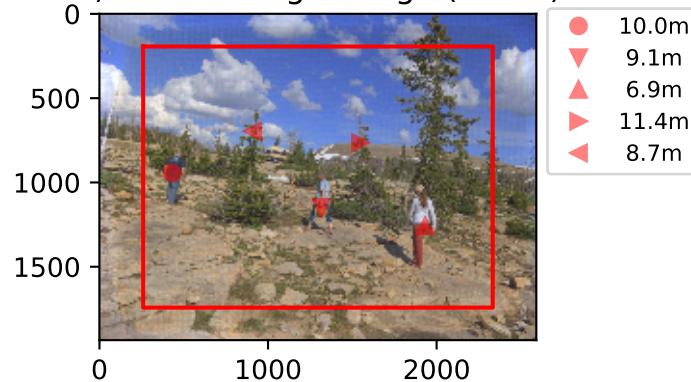


1562390257\_977146: Three persons, trees.

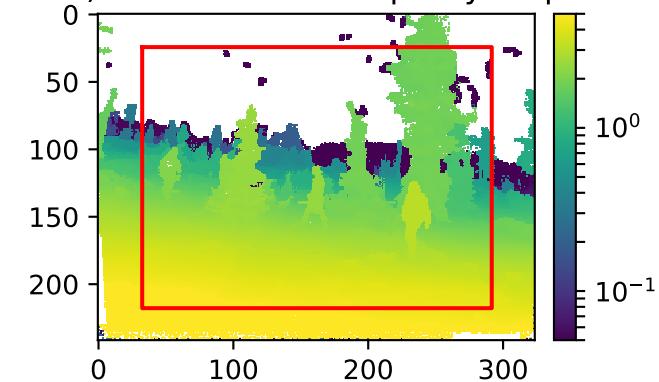
a) LWIR image (1 of 4)



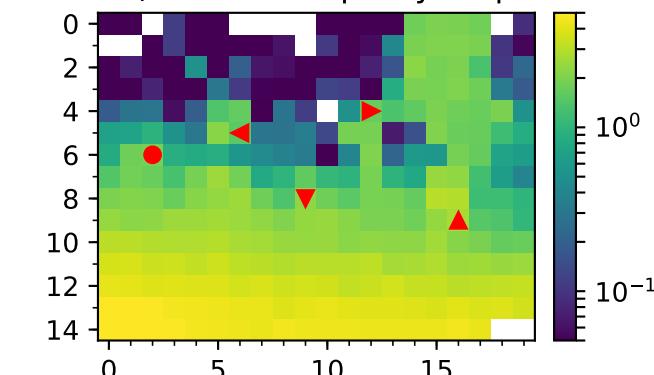
b) Visible range image (1 of 4)



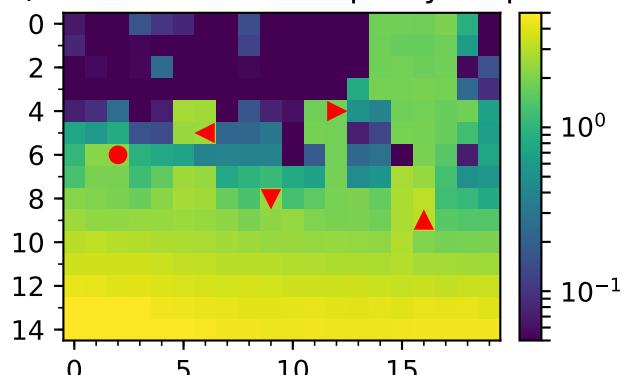
c) Hi-res camera disparity map



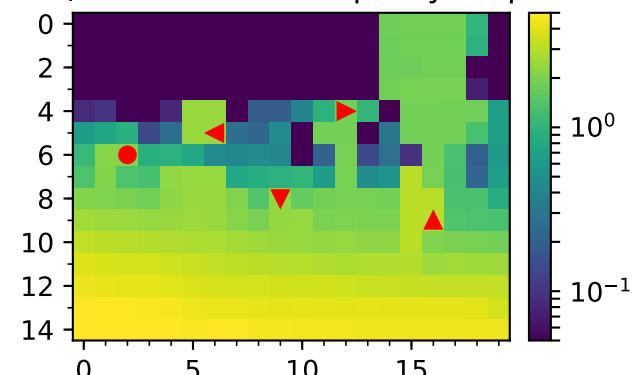
d) Non-NN disparity map



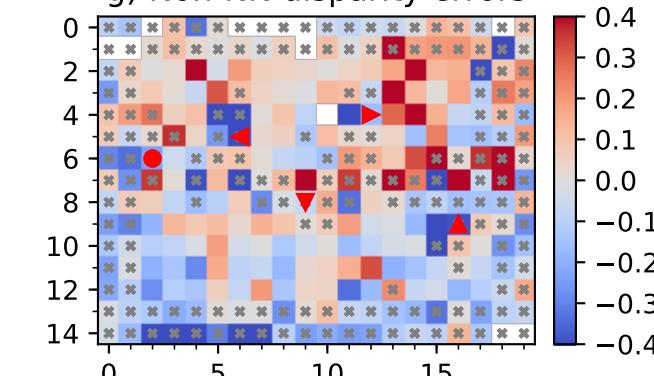
e) Neural network disparity output



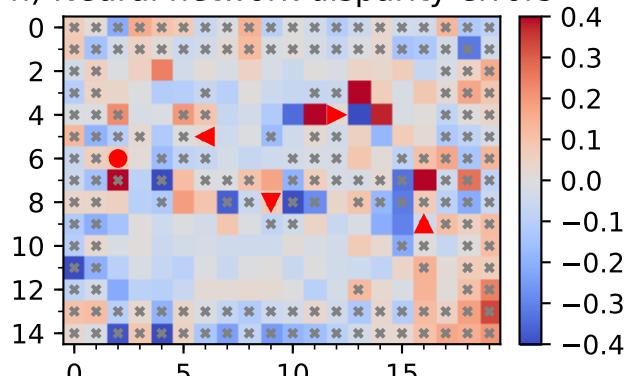
f) Ground truth disparity map



g) Non-NN disparity errors

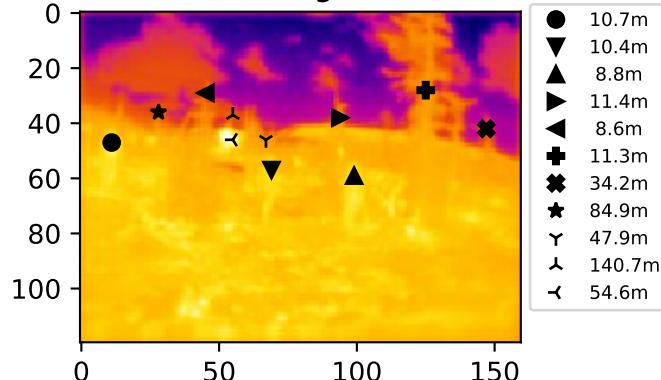


h) Neural network disparity errors

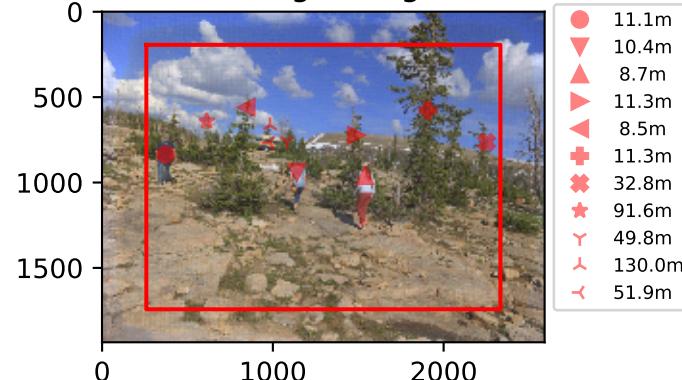


1562390260\_370347: Three persons, near and far trees, minivan.

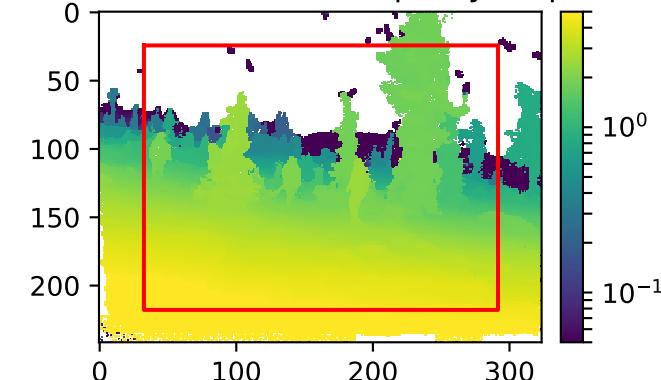
a) LWIR image (1 of 4)



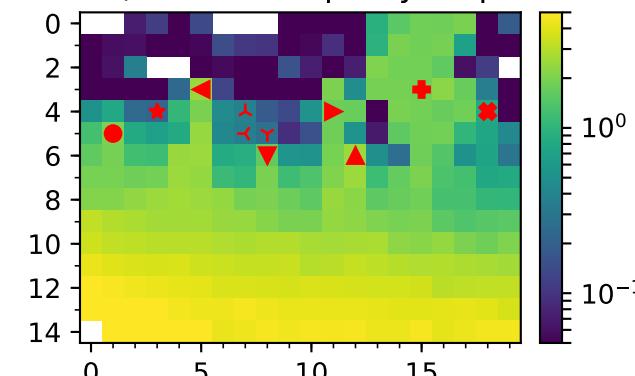
b) Visible range image (1 of 4)



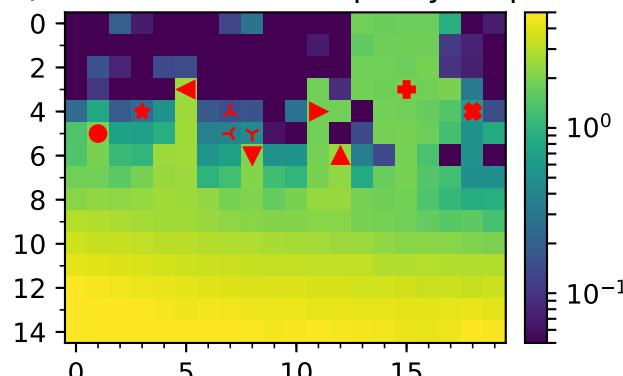
c) Hi-res camera disparity map



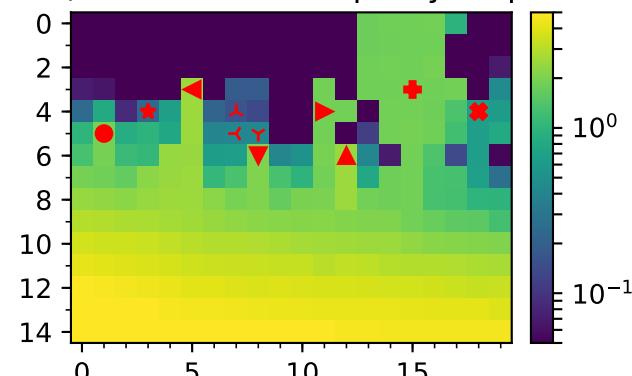
d) Non-NN disparity map



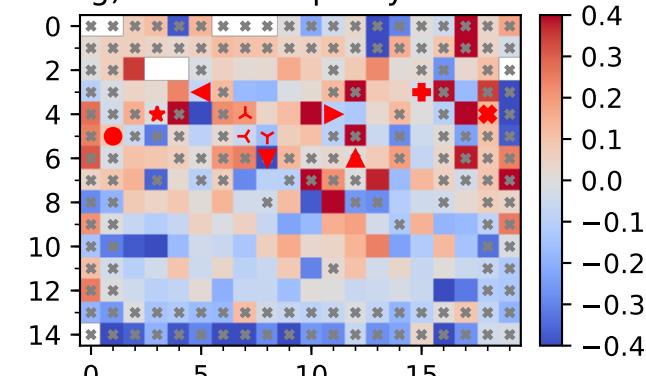
e) Neural network disparity output



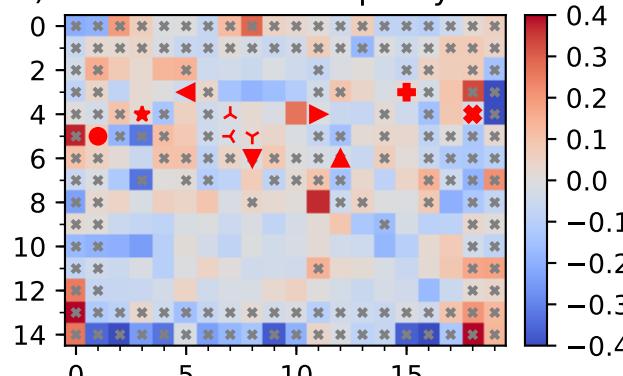
f) Ground truth disparity map



g) Non-NN disparity errors

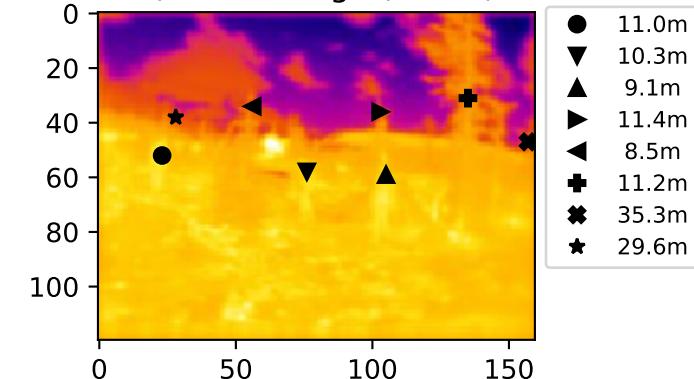


h) Neural network disparity errors

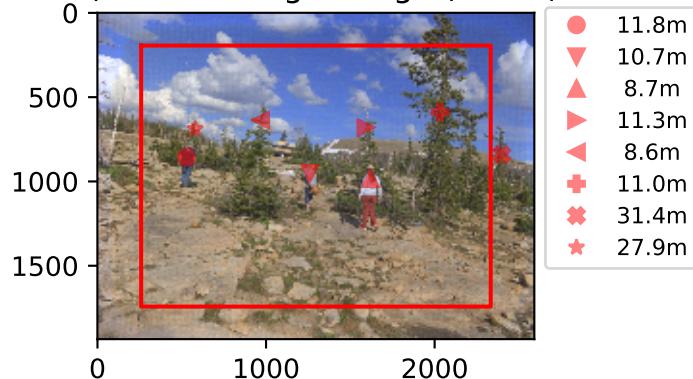


1562390260\_940102: Three persons, trees.

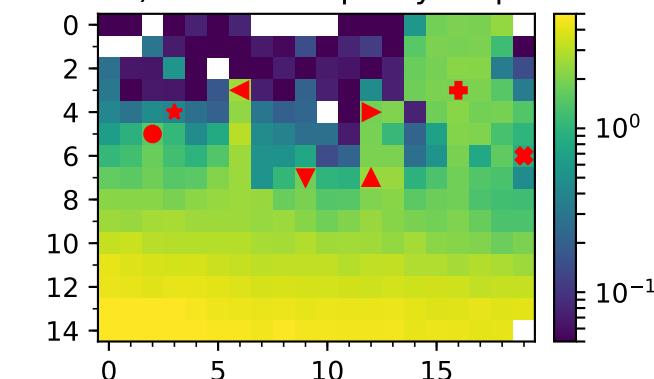
a) LWIR image (1 of 4)



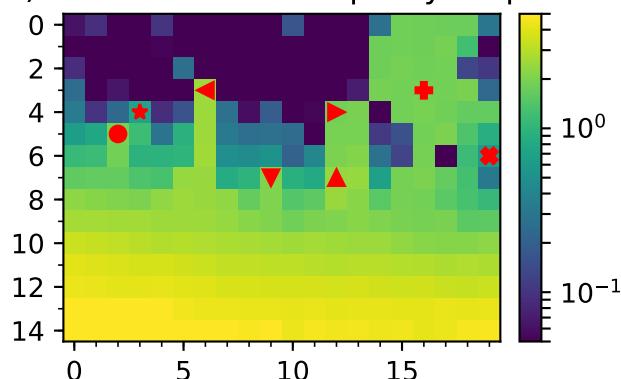
b) Visible range image (1 of 4)



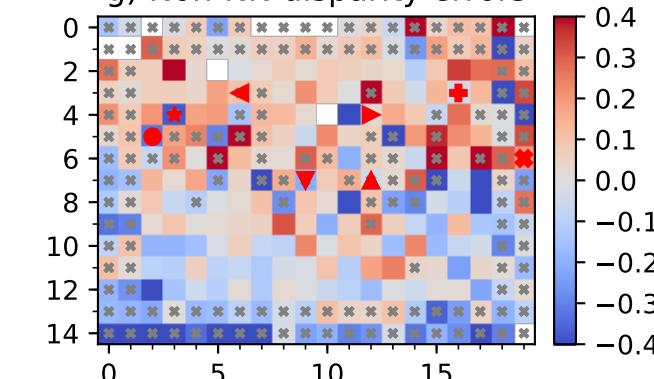
d) Non-NN disparity map



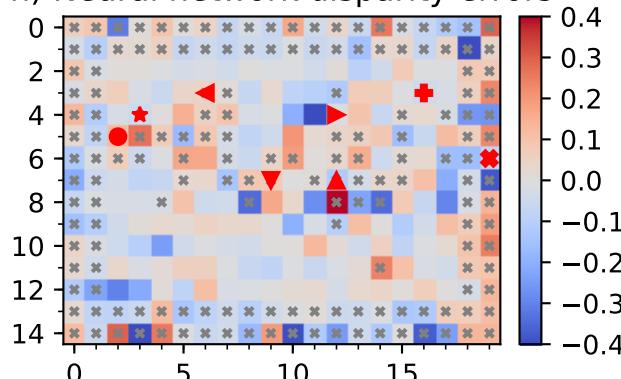
e) Neural network disparity output



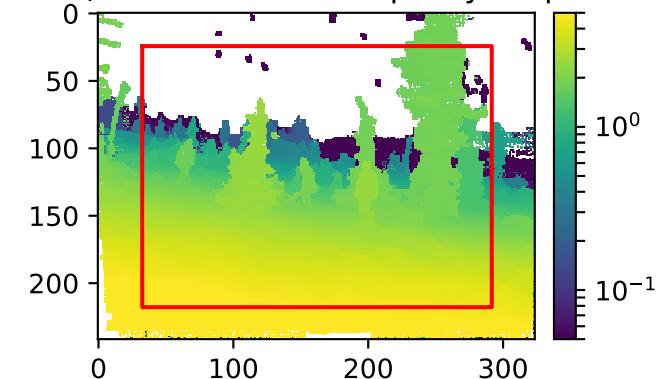
g) Non-NN disparity errors



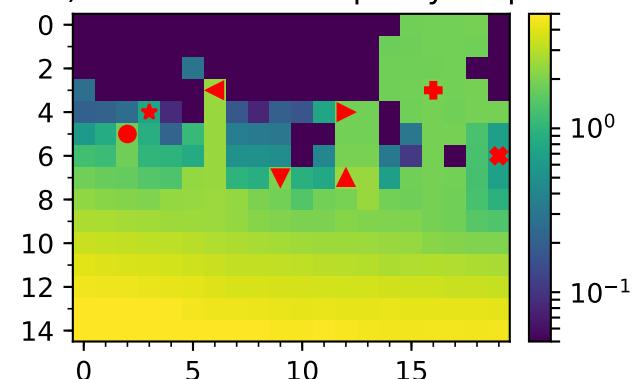
h) Neural network disparity errors



c) Hi-res camera disparity map

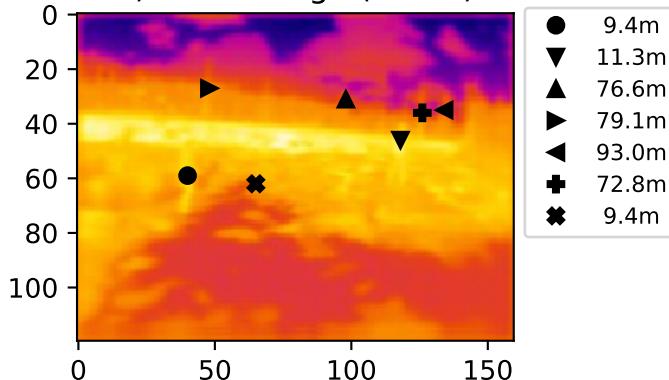


f) Ground truth disparity map

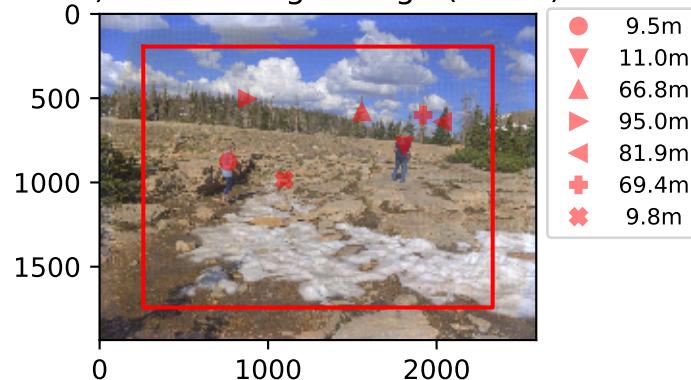


1562390317\_693673: Two persons, far trees.

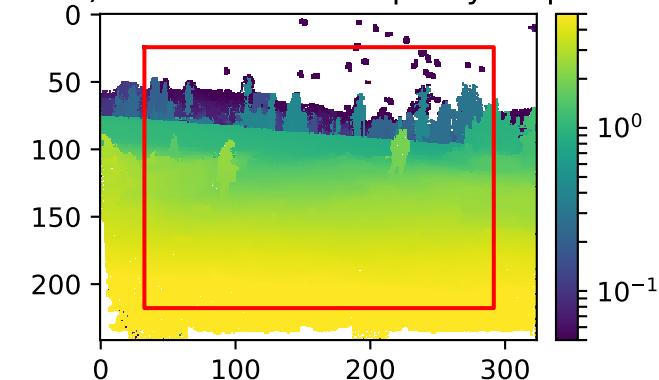
a) LWIR image (1 of 4)



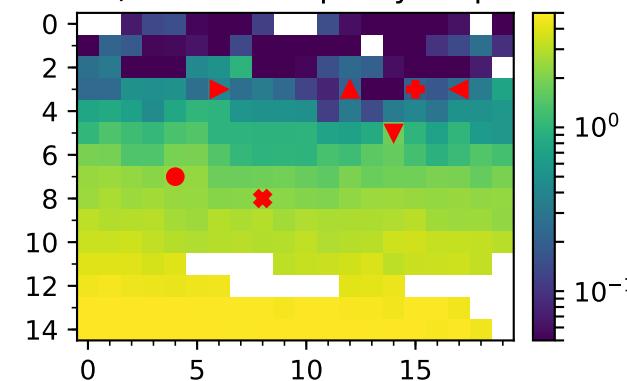
b) Visible range image (1 of 4)



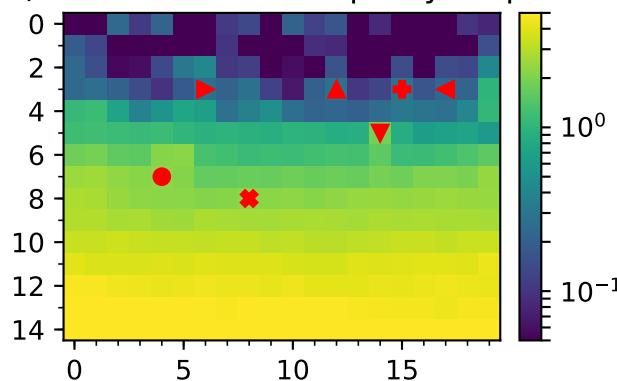
c) Hi-res camera disparity map



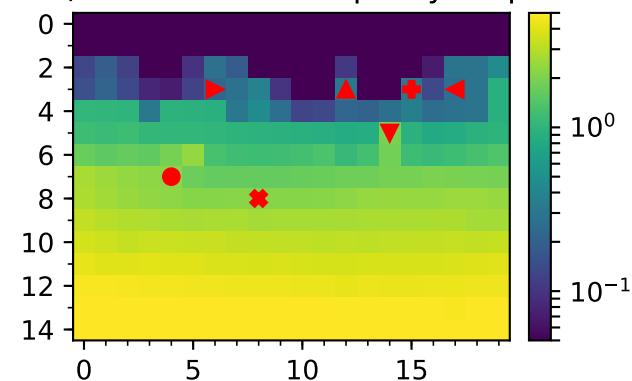
d) Non-NN disparity map



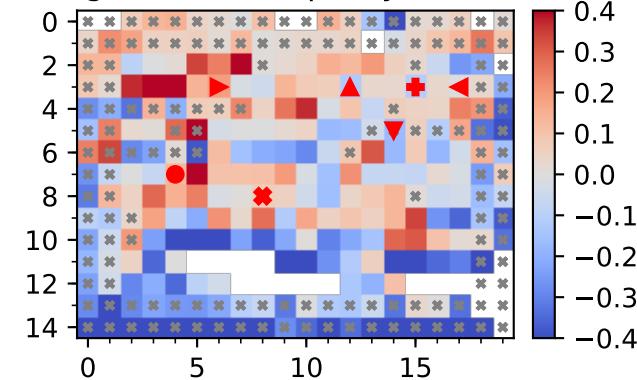
e) Neural network disparity output



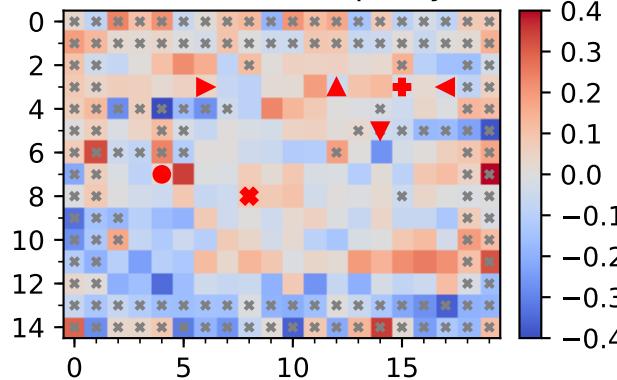
f) Ground truth disparity map



g) Non-NN disparity errors

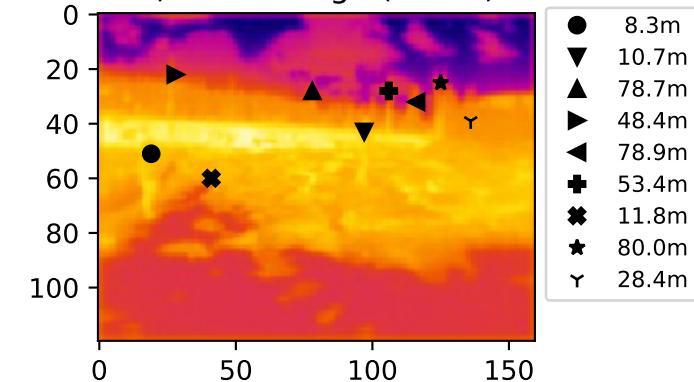


h) Neural network disparity errors

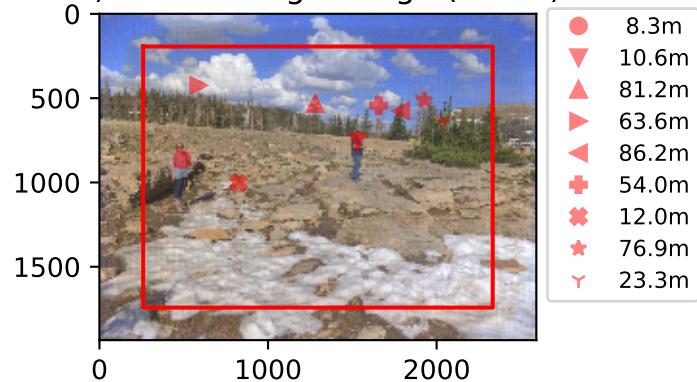


1562390318\_833313: Two persons, trees.

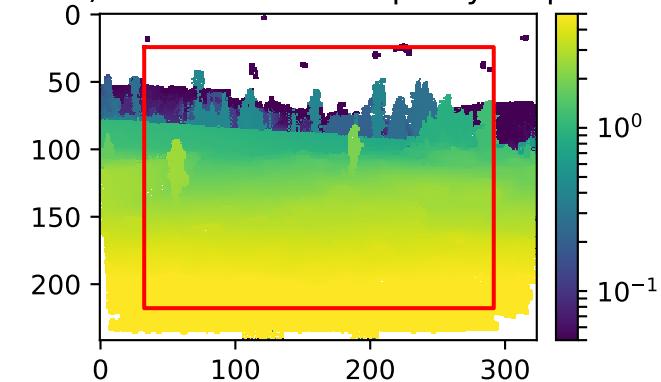
a) LWIR image (1 of 4)



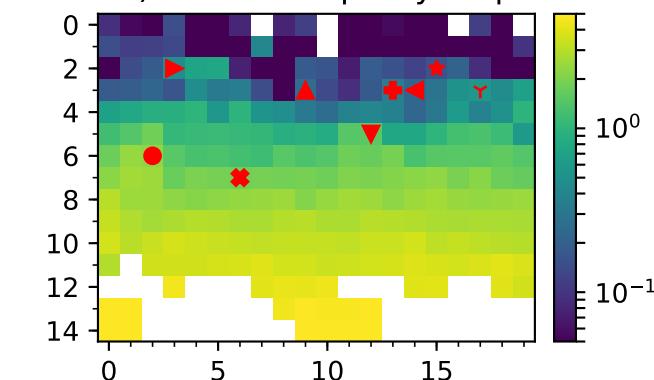
b) Visible range image (1 of 4)



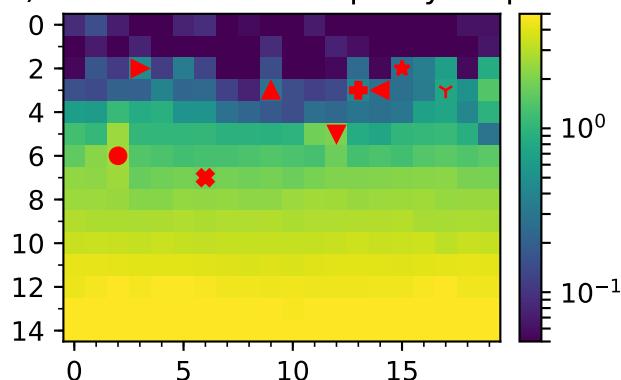
c) Hi-res camera disparity map



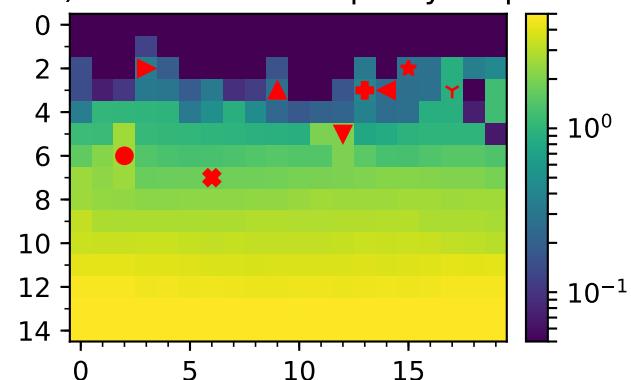
d) Non-NN disparity map



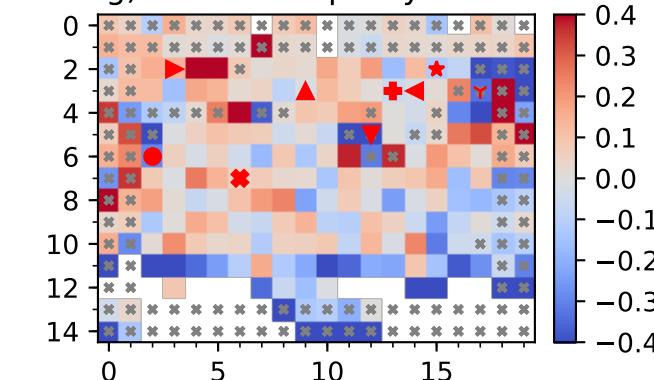
e) Neural network disparity output



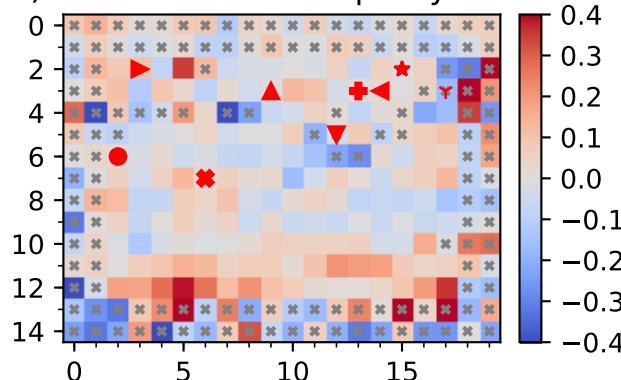
f) Ground truth disparity map



g) Non-NN disparity errors

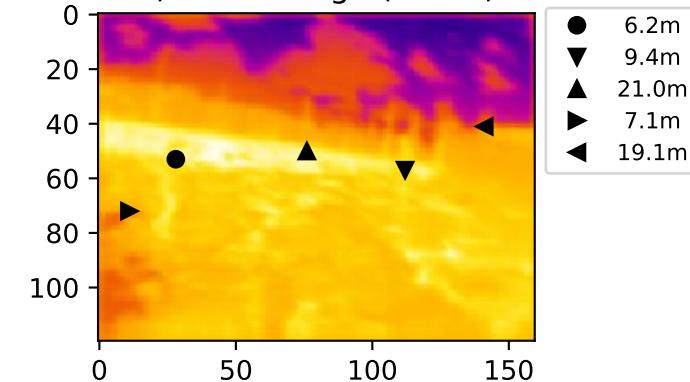


h) Neural network disparity errors

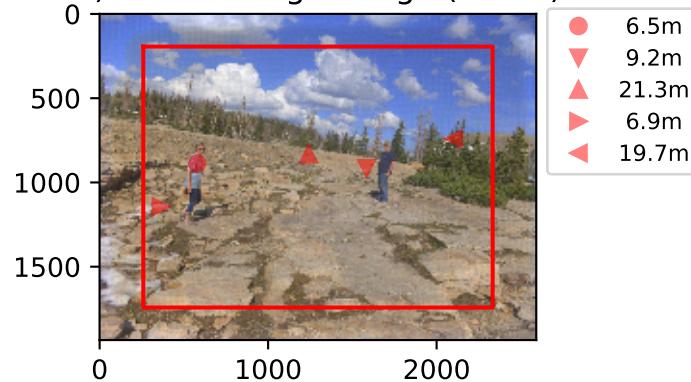


1562390326\_354823: Two persons, trees.

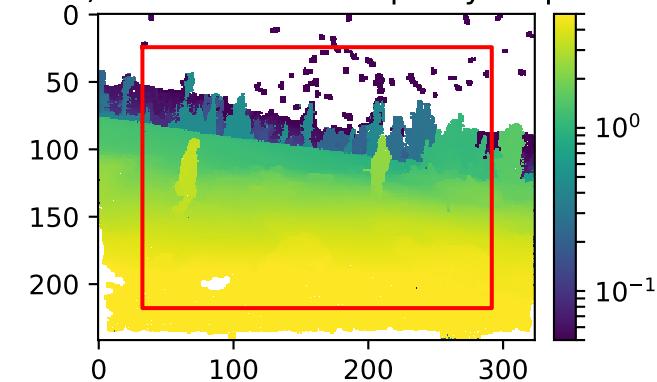
a) LWIR image (1 of 4)



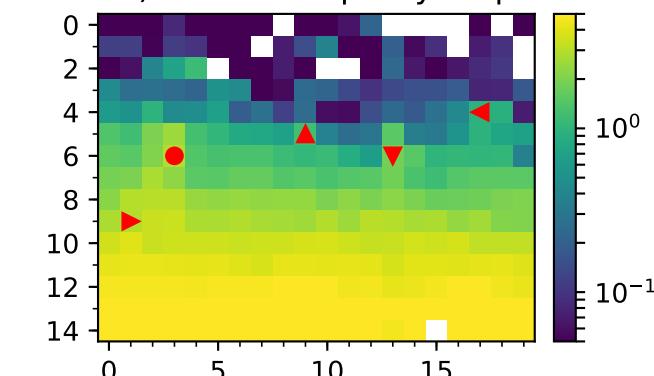
b) Visible range image (1 of 4)



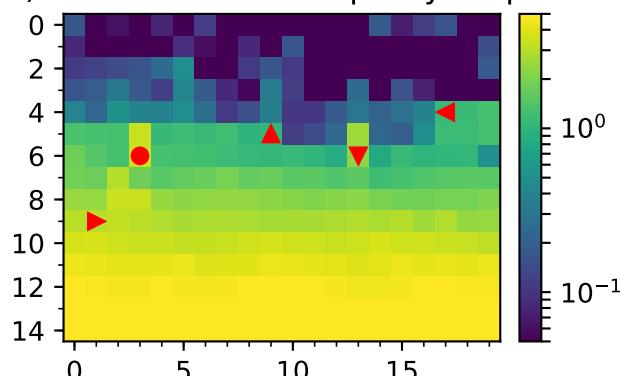
c) Hi-res camera disparity map



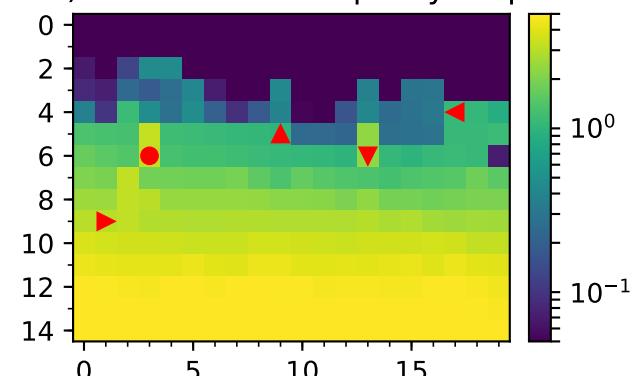
d) Non-NN disparity map



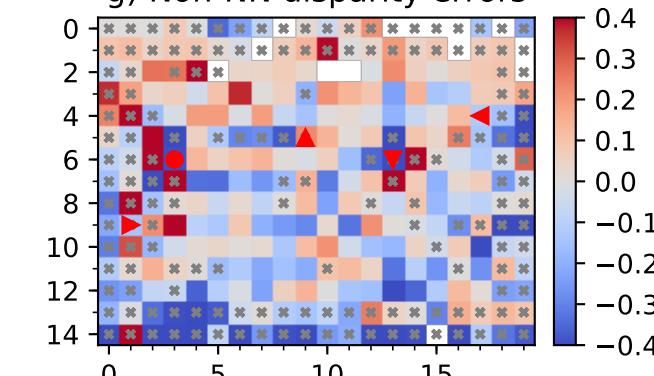
e) Neural network disparity output



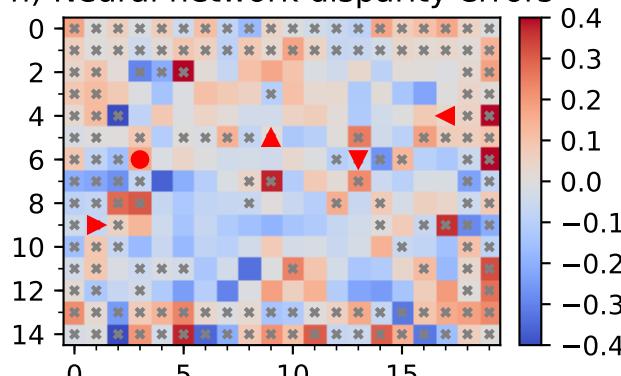
f) Ground truth disparity map



g) Non-NN disparity errors

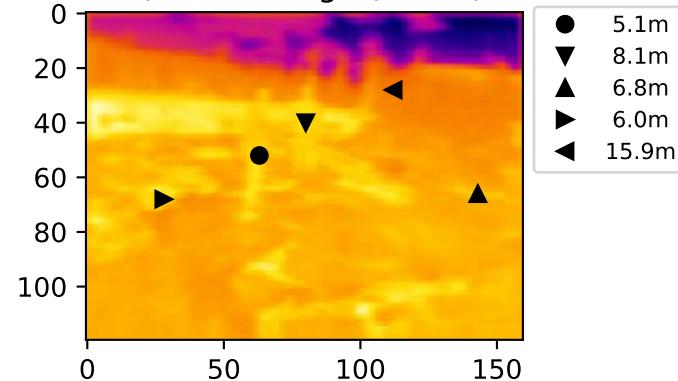


h) Neural network disparity errors

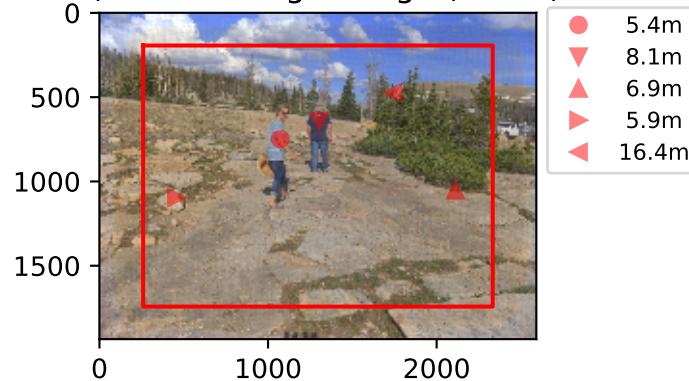


1562390331\_483132: Two persons, trees.

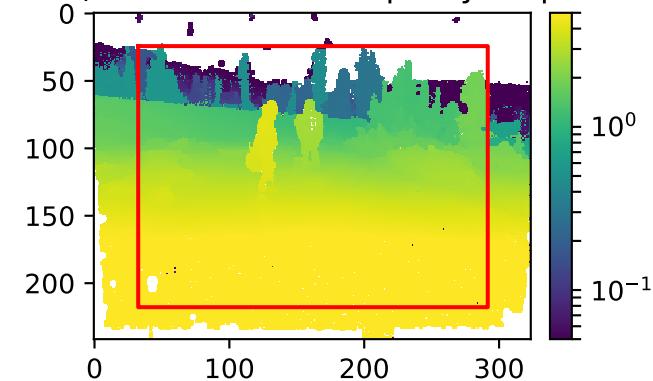
a) LWIR image (1 of 4)



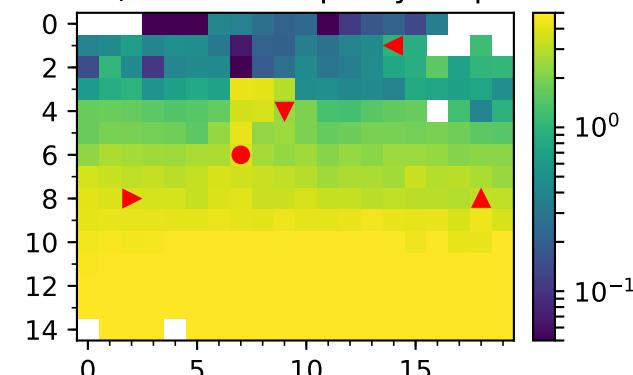
b) Visible range image (1 of 4)



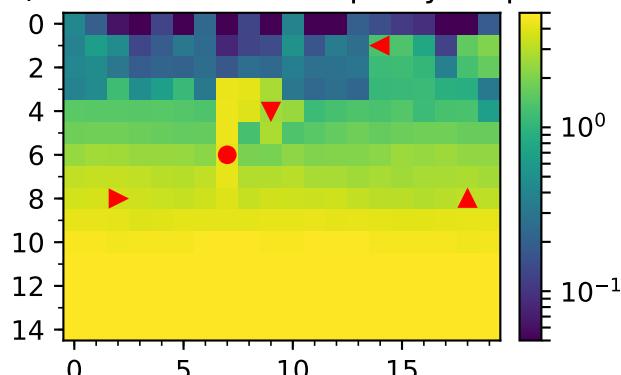
c) Hi-res camera disparity map



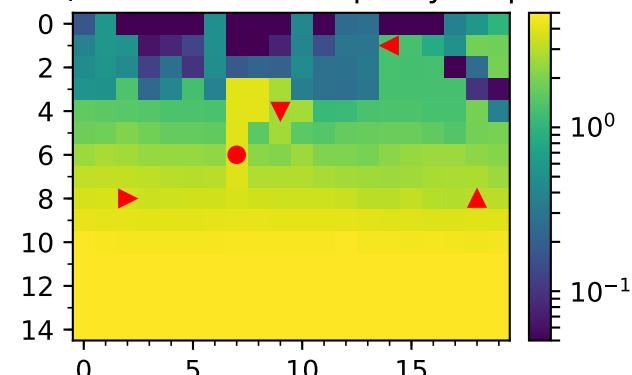
d) Non-NN disparity map



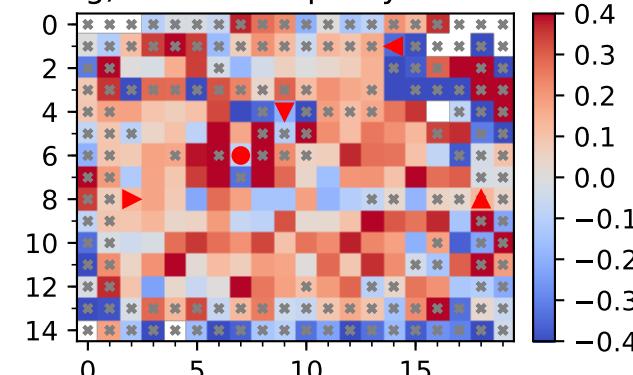
e) Neural network disparity output



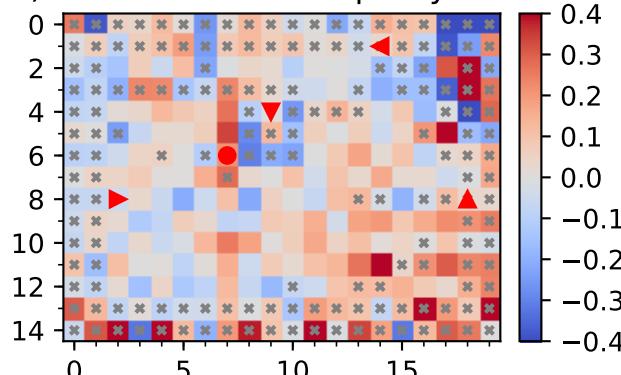
f) Ground truth disparity map



g) Non-NN disparity errors

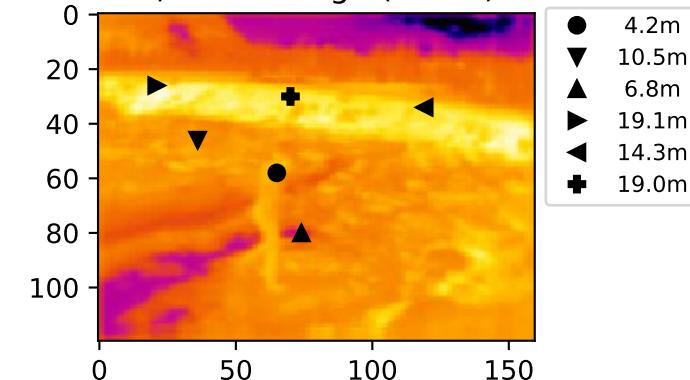


h) Neural network disparity errors

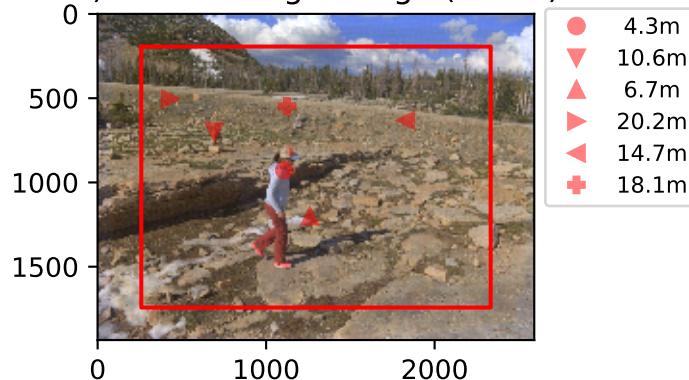


1562390333\_192523: Single person, sun-heated highway fill.

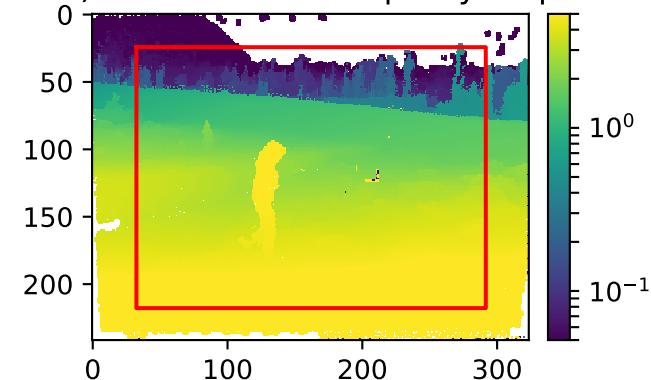
a) LWIR image (1 of 4)



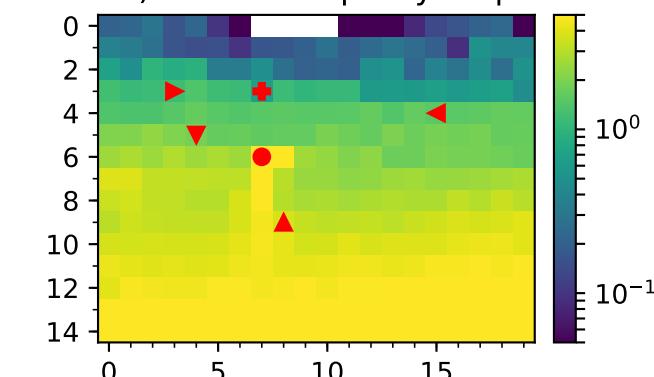
b) Visible range image (1 of 4)



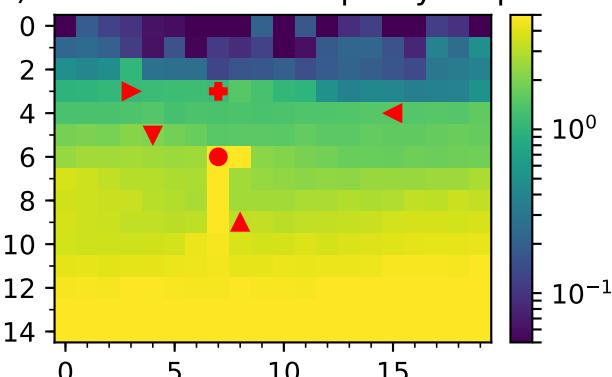
c) Hi-res camera disparity map



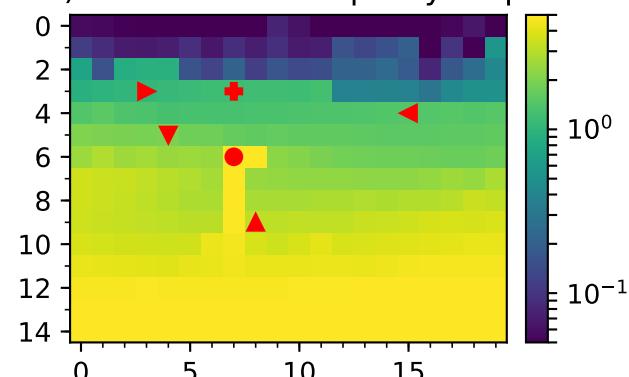
d) Non-NN disparity map



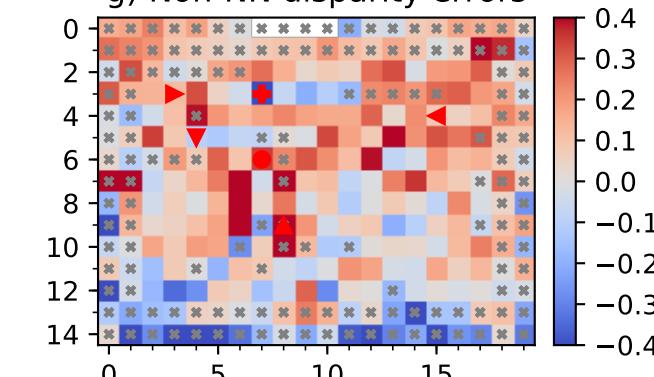
e) Neural network disparity output



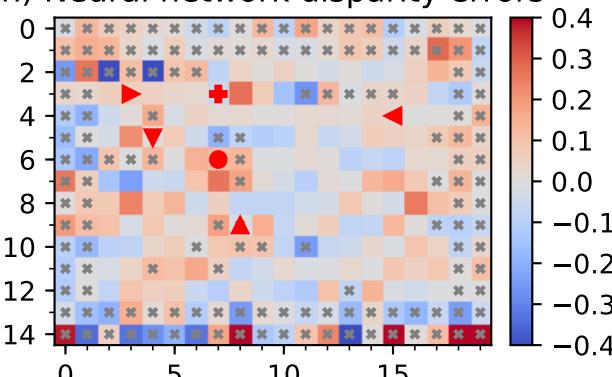
f) Ground truth disparity map



g) Non-NN disparity errors

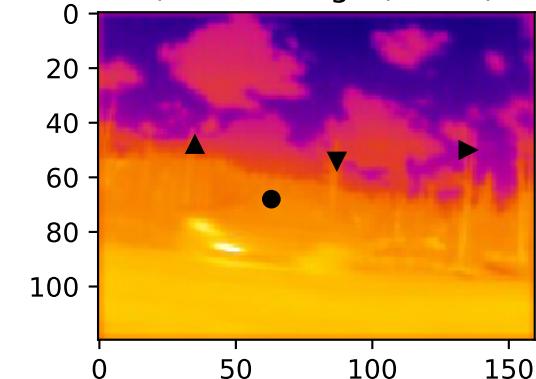


h) Neural network disparity errors

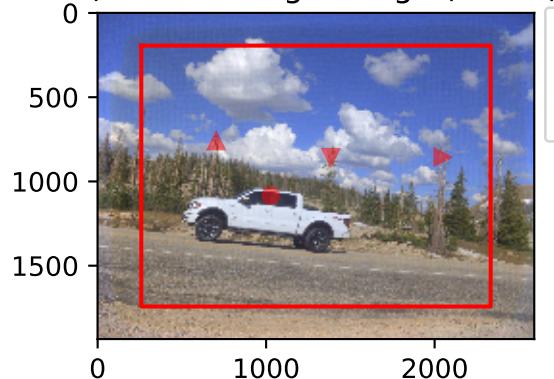


1562390402\_254007: Car on a highway, background trees.

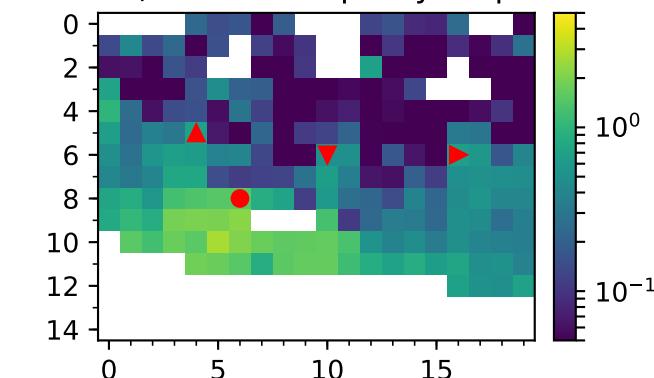
a) LWIR image (1 of 4)



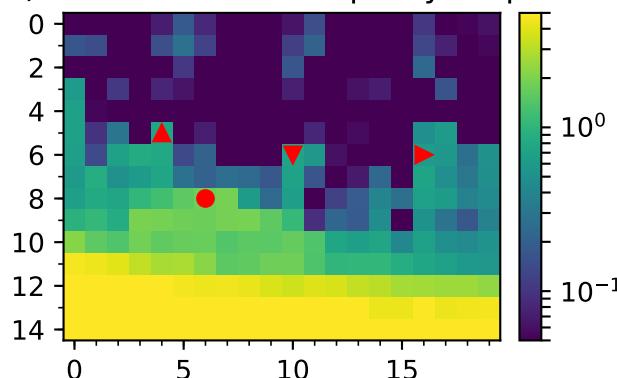
b) Visible range image (1 of 4)



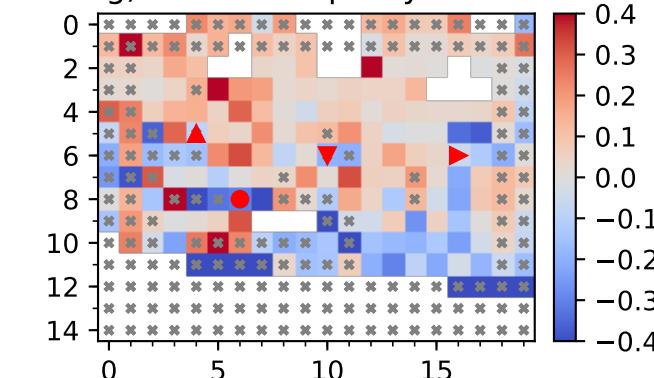
d) Non-NN disparity map



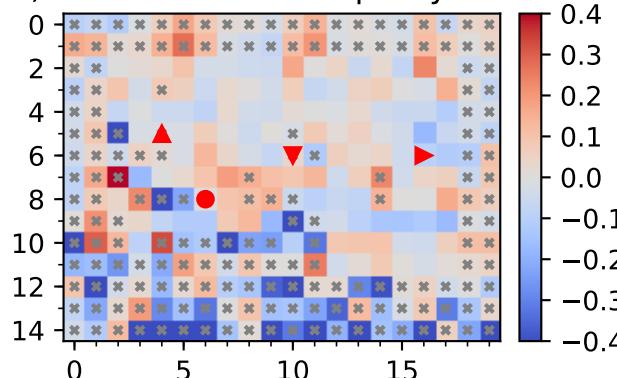
e) Neural network disparity output



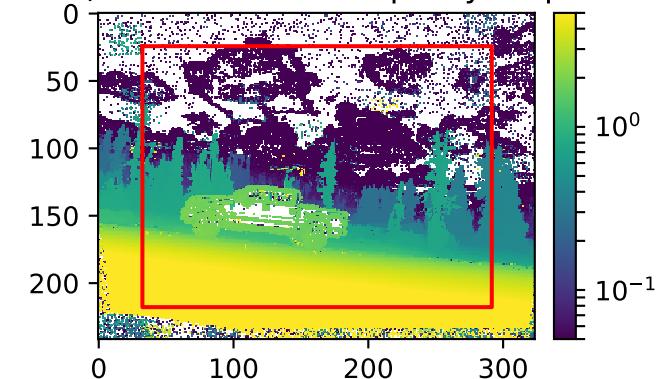
g) Non-NN disparity errors



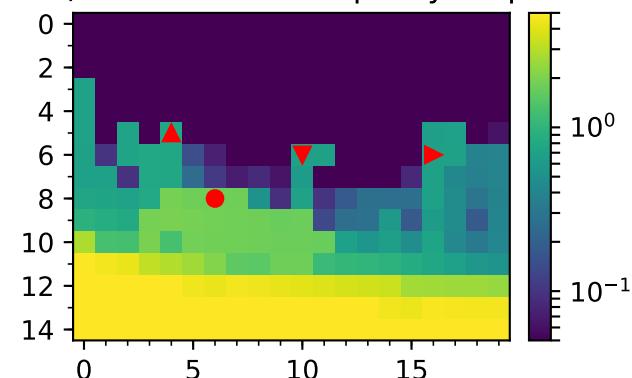
h) Neural network disparity errors



c) Hi-res camera disparity map

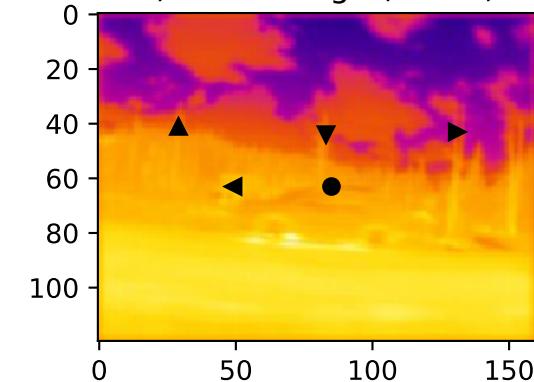


f) Ground truth disparity map

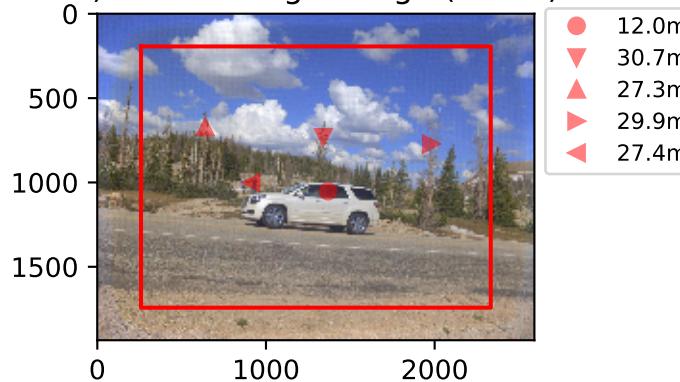


1562390407\_382326: Car on a highway, background trees.

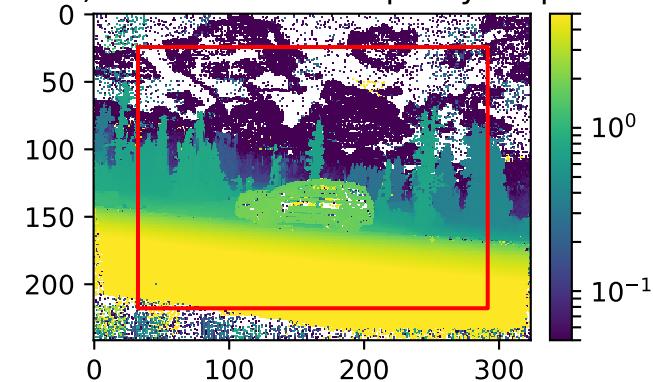
a) LWIR image (1 of 4)



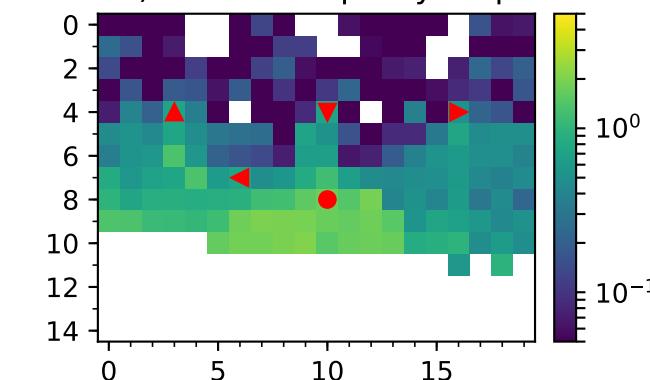
b) Visible range image (1 of 4)



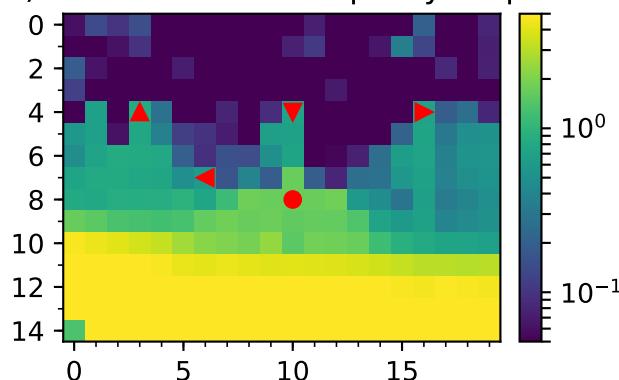
c) Hi-res camera disparity map



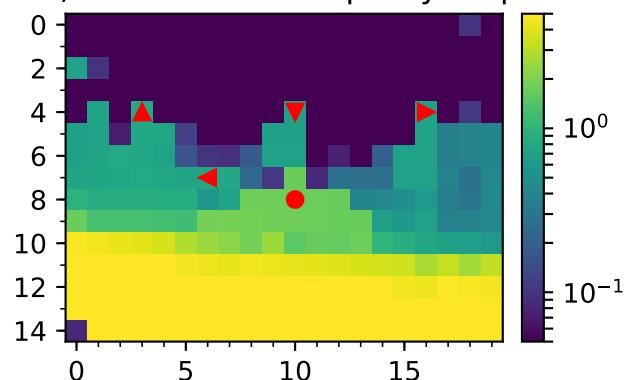
d) Non-NN disparity map



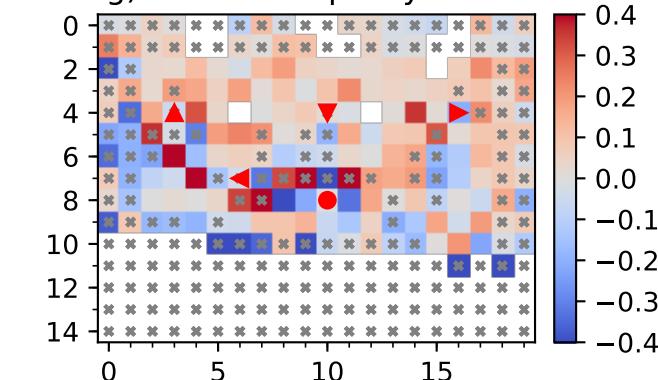
e) Neural network disparity output



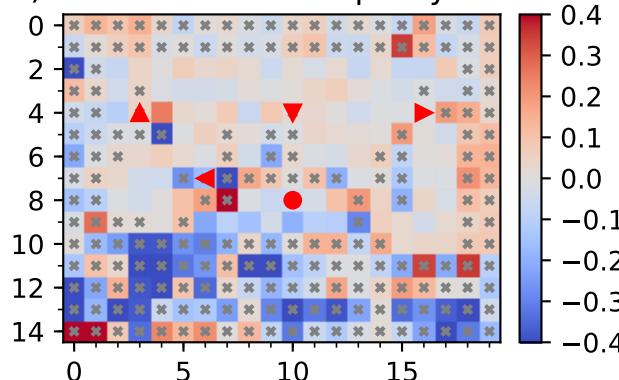
f) Ground truth disparity map



g) Non-NN disparity errors

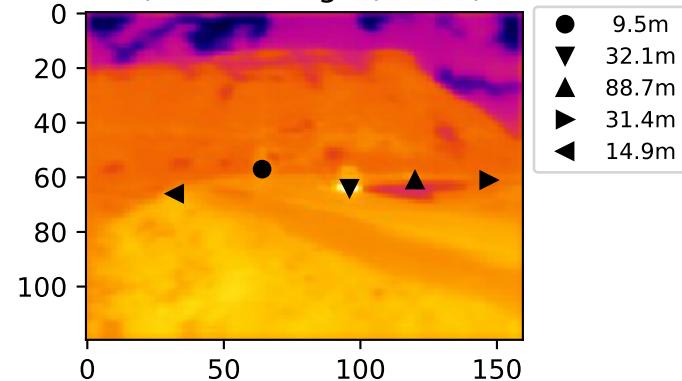


h) Neural network disparity errors

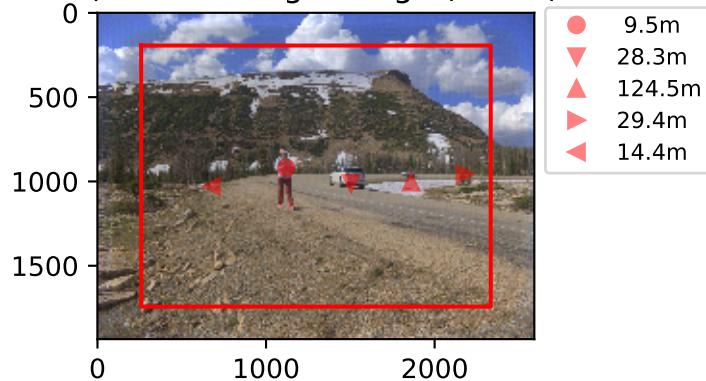


1562390409\_661607: Single person, a car on a highway.

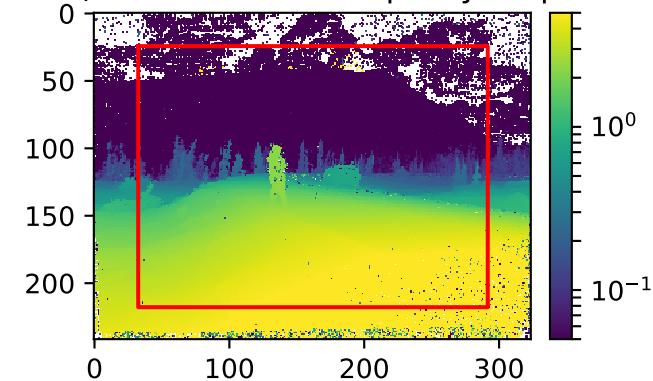
a) LWIR image (1 of 4)



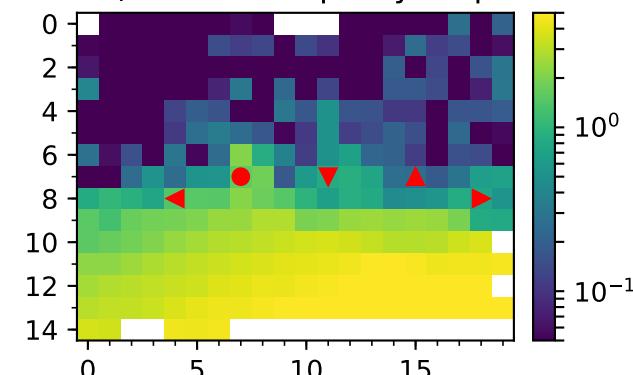
b) Visible range image (1 of 4)



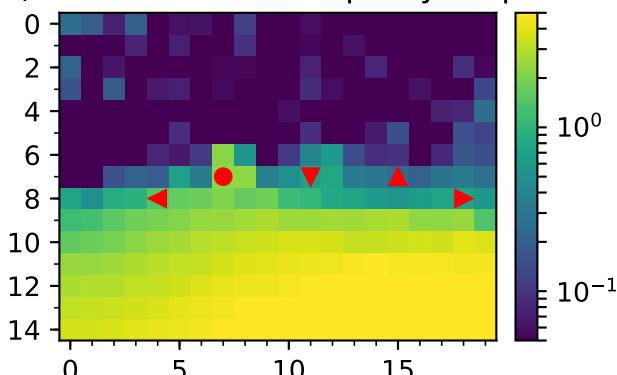
c) Hi-res camera disparity map



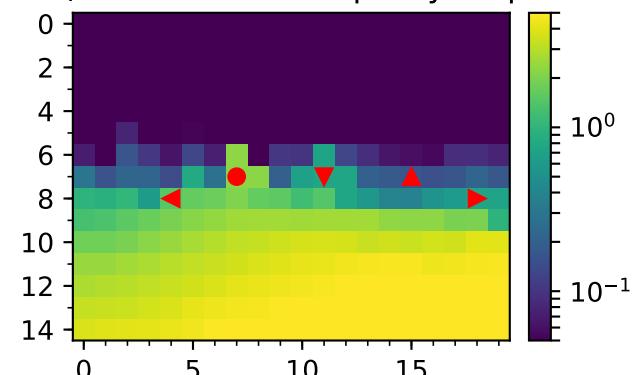
d) Non-NN disparity map



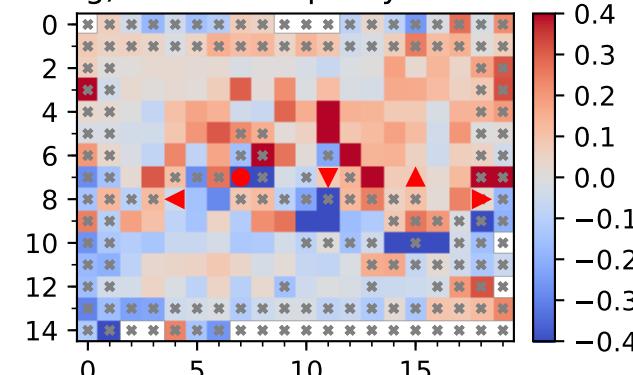
e) Neural network disparity output



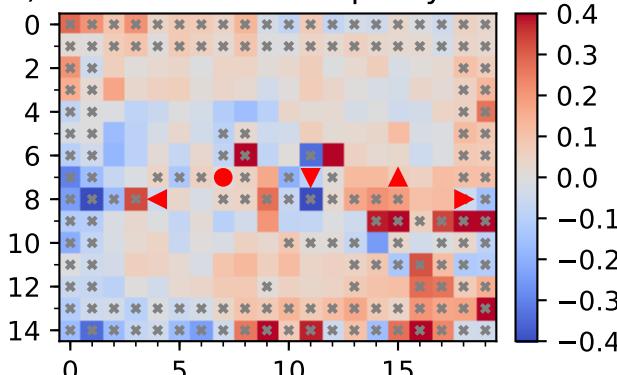
f) Ground truth disparity map



g) Non-NN disparity errors

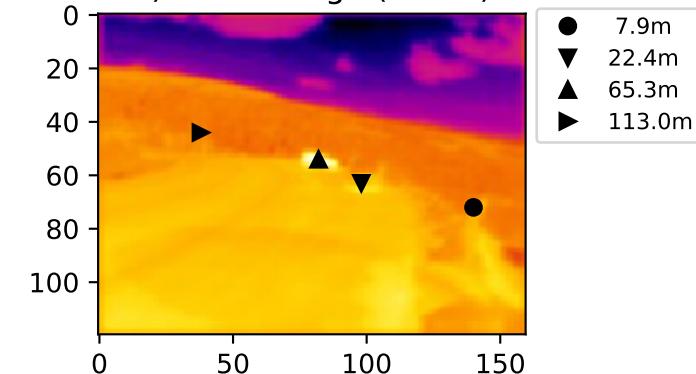


h) Neural network disparity errors

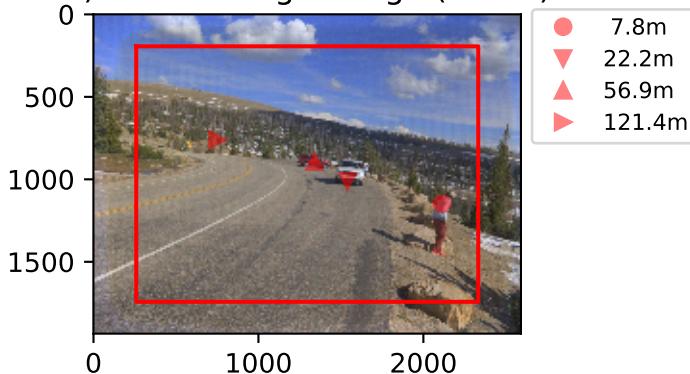


1562390435\_873048: Single person, two parked cars.

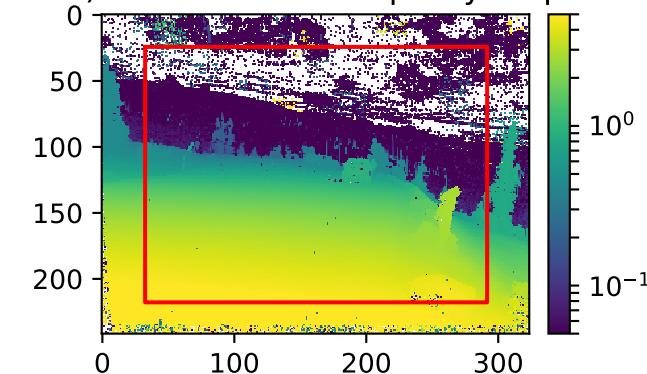
a) LWIR image (1 of 4)



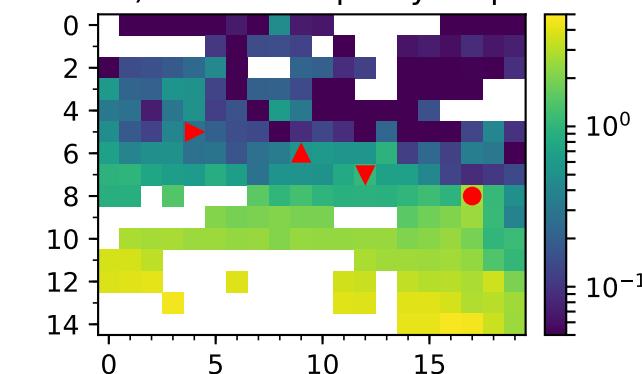
b) Visible range image (1 of 4)



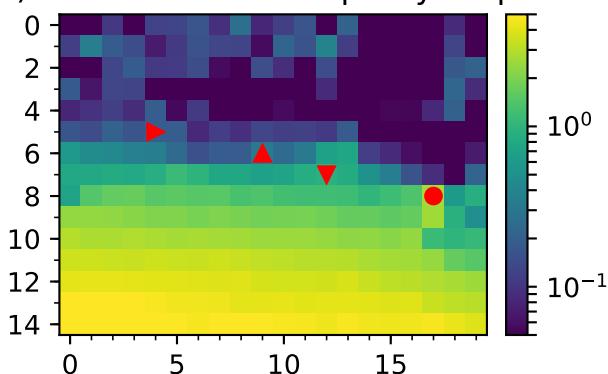
c) Hi-res camera disparity map



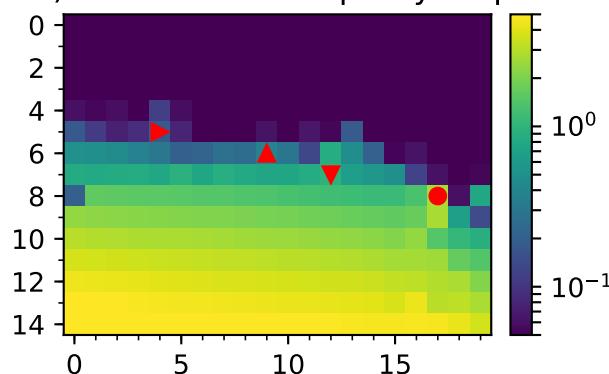
d) Non-NN disparity map



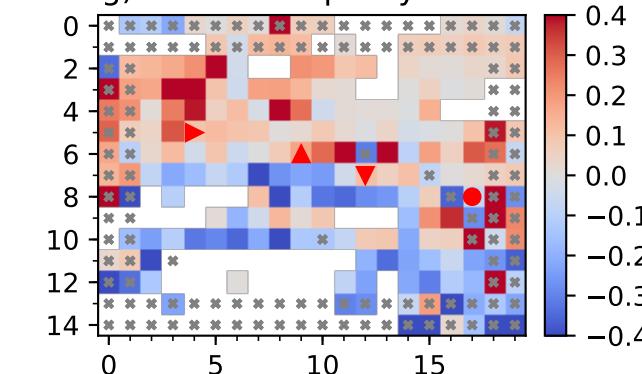
e) Neural network disparity output



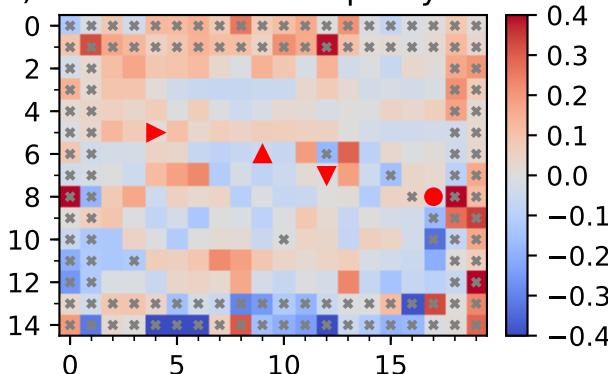
f) Ground truth disparity map



g) Non-NN disparity errors

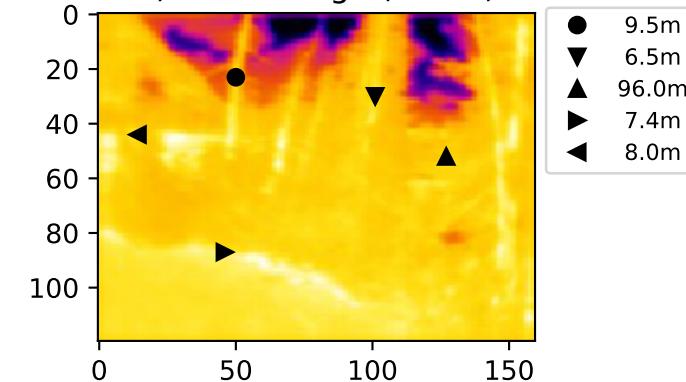


h) Neural network disparity errors

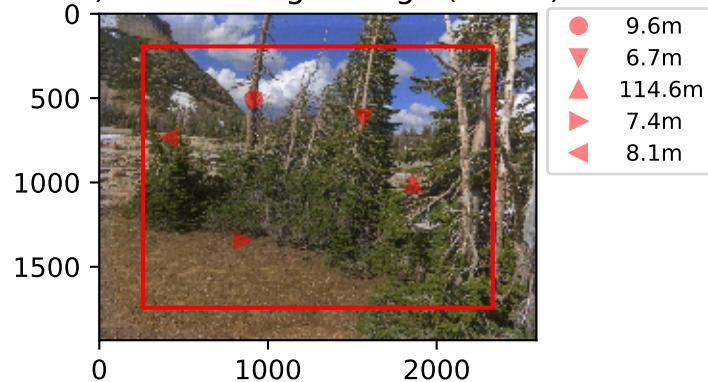


1562390456\_842237: Close trees.

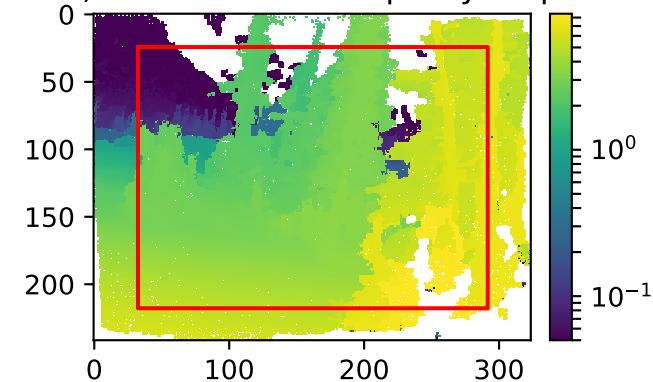
a) LWIR image (1 of 4)



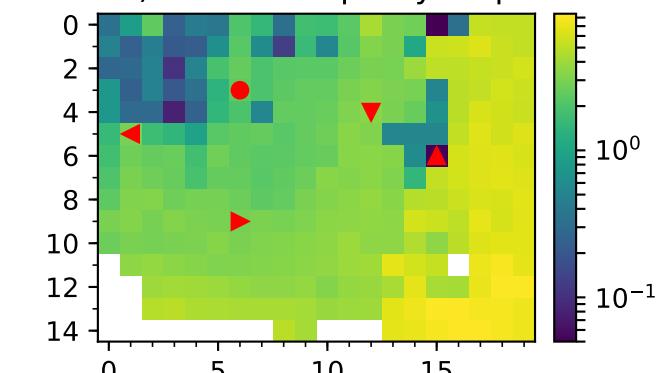
b) Visible range image (1 of 4)



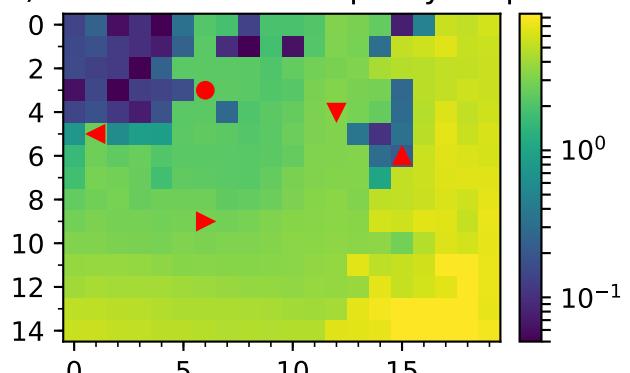
c) Hi-res camera disparity map



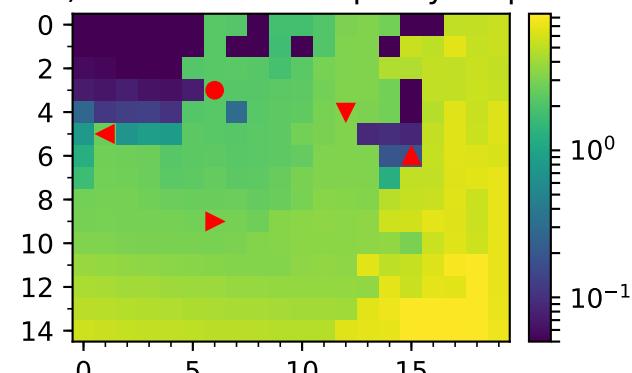
d) Non-NN disparity map



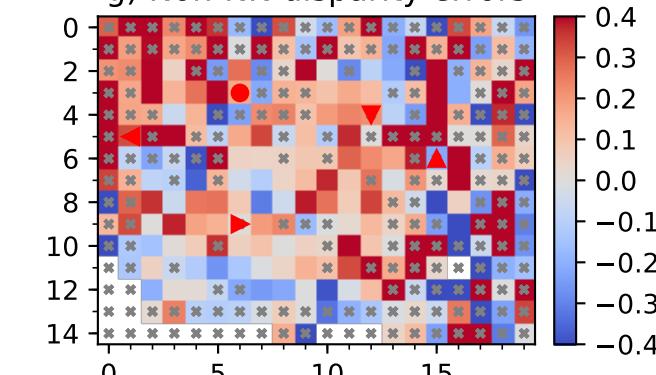
e) Neural network disparity output



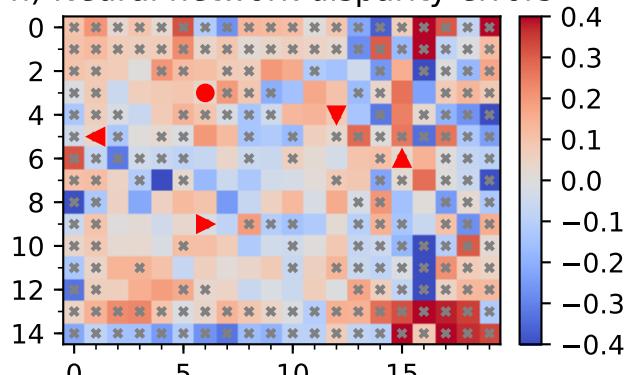
f) Ground truth disparity map



g) Non-NN disparity errors

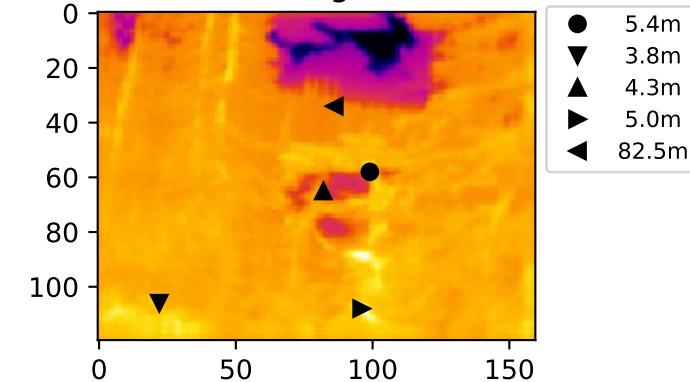


h) Neural network disparity errors

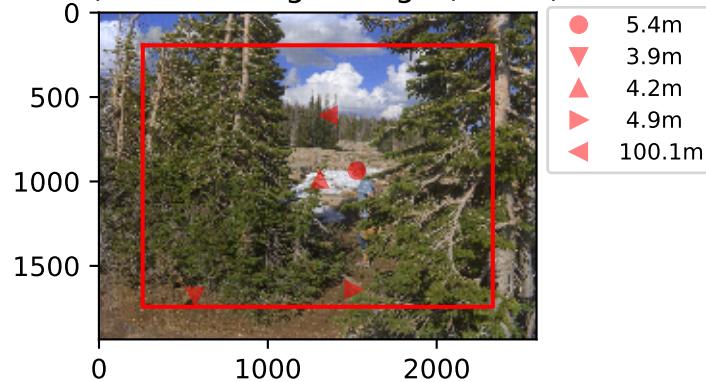


1562390460\_261151: Trees closer than near clipping plane.

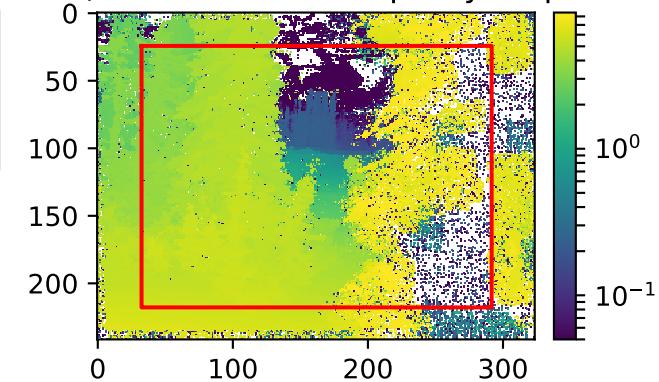
a) LWIR image (1 of 4)



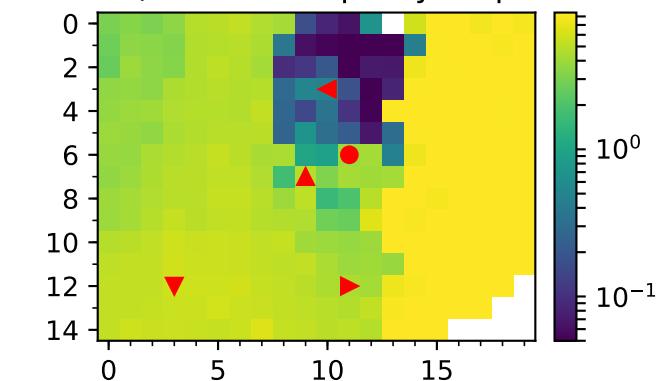
b) Visible range image (1 of 4)



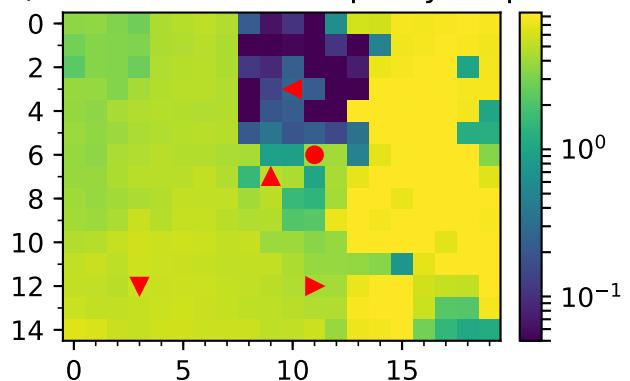
c) Hi-res camera disparity map



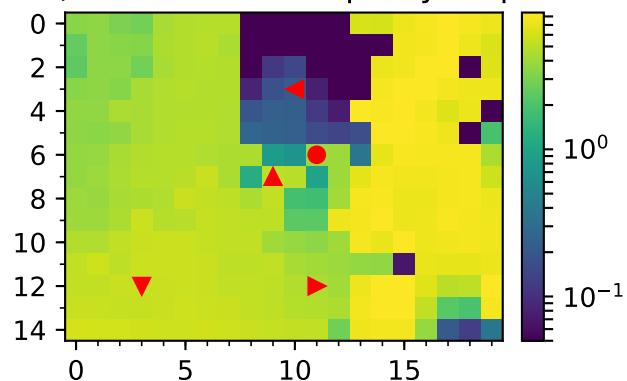
d) Non-NN disparity map



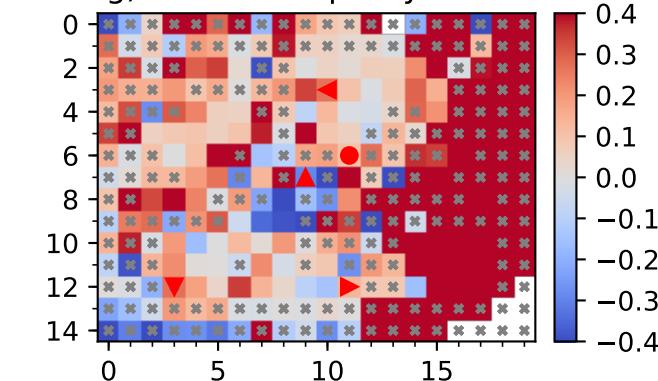
e) Neural network disparity output



f) Ground truth disparity map



g) Non-NN disparity errors



h) Neural network disparity errors

