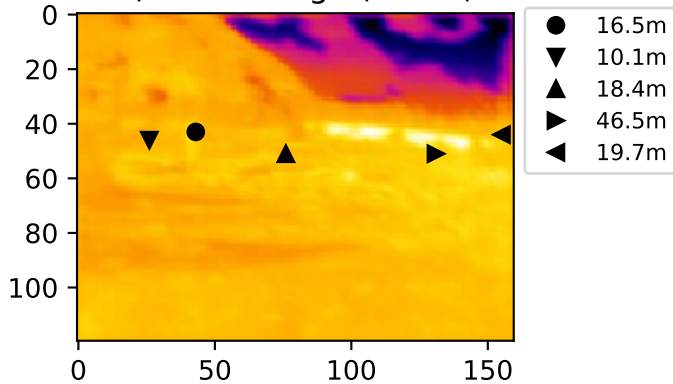
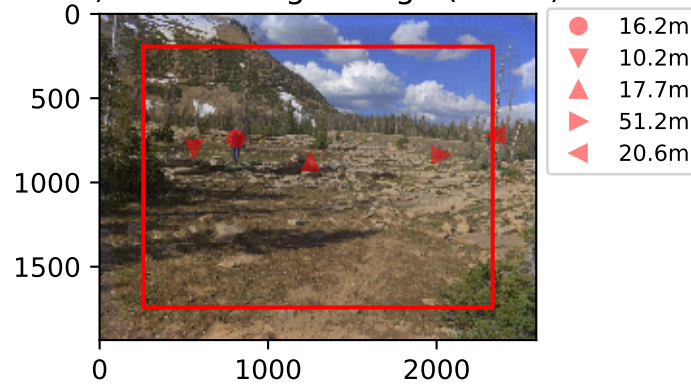


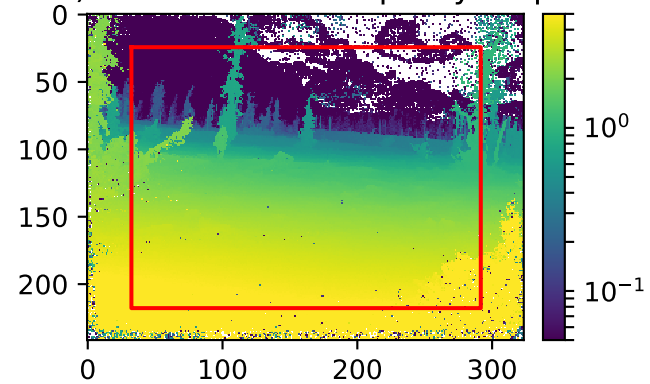
a) LWIR image (1 of 4)



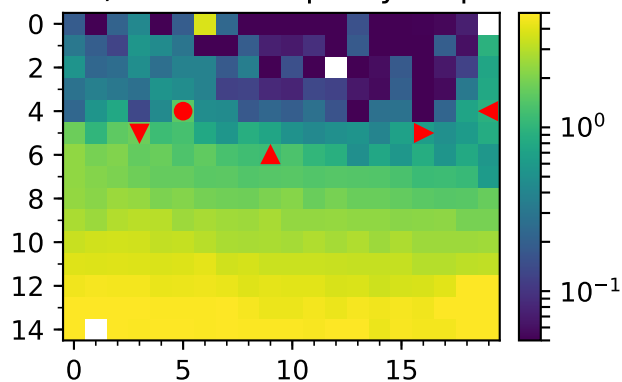
b) Visible range image (1 of 4)



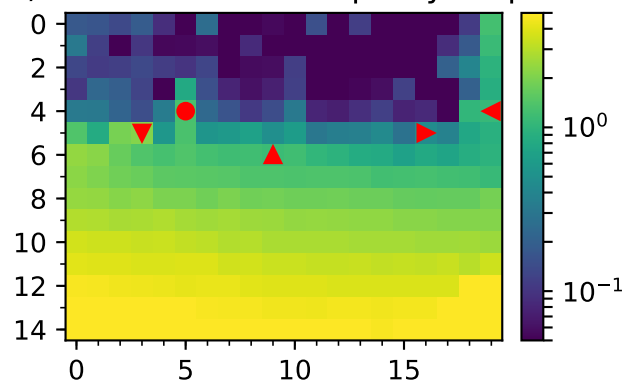
c) Hi-res camera disparity map



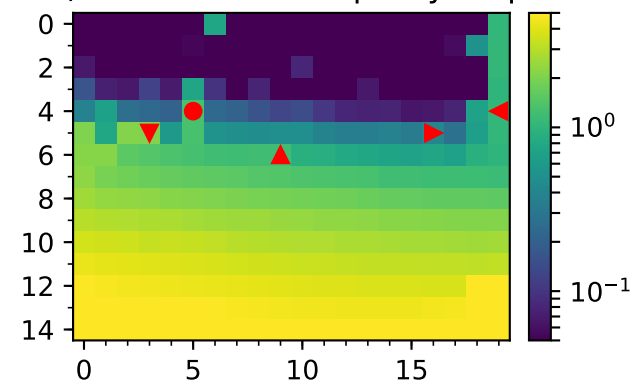
d) Non-NN disparity map



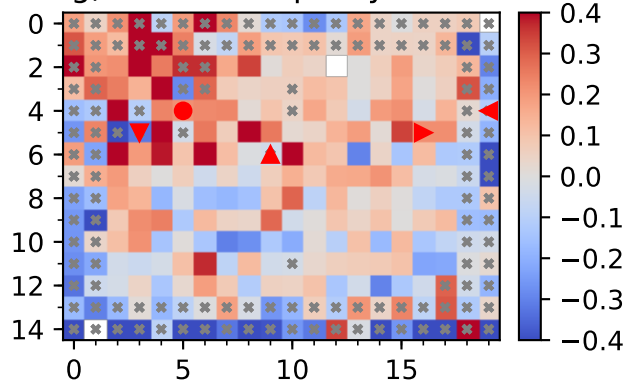
e) Neural network disparity output



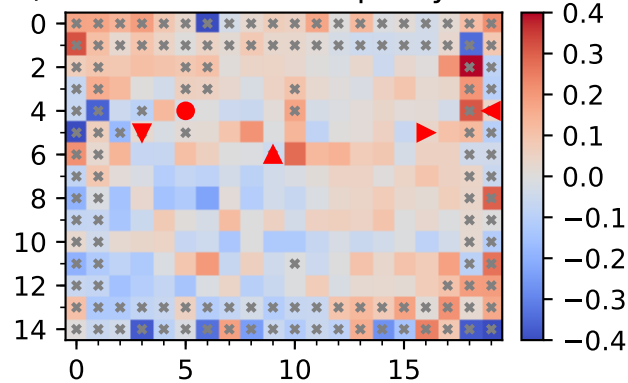
f) Ground truth disparity map



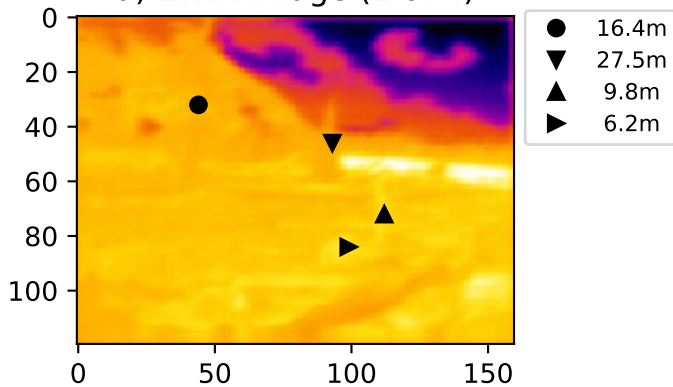
g) Non-NN disparity errors



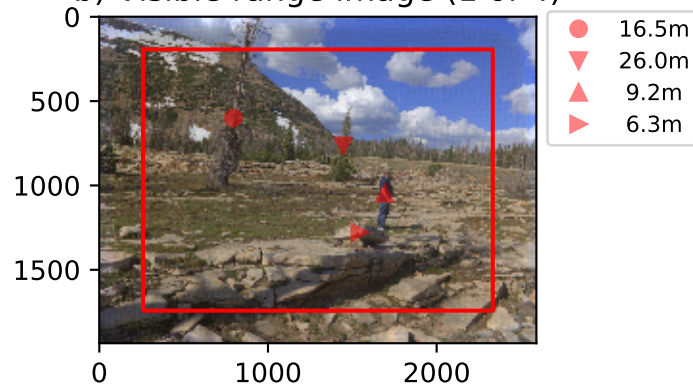
h) Neural network disparity errors



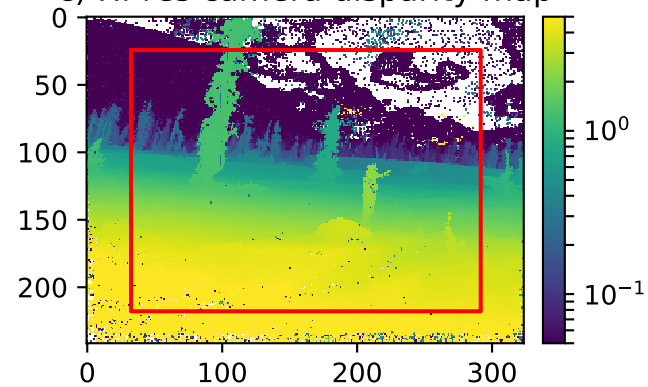
a) LWIR image (1 of 4)



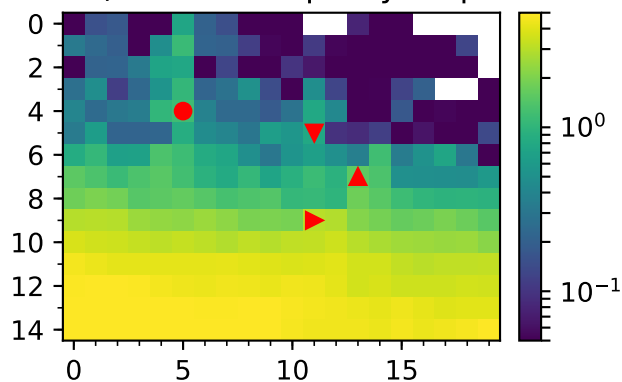
b) Visible range image (1 of 4)



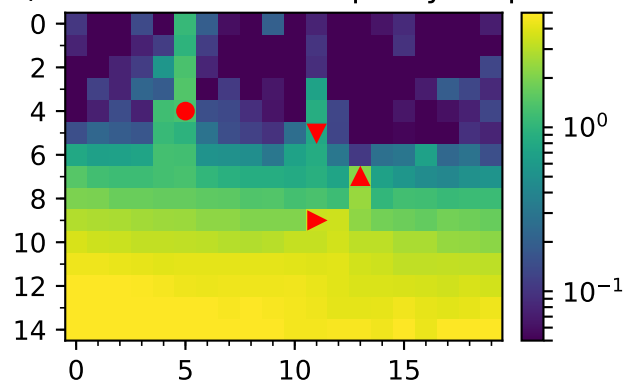
c) Hi-res camera disparity map



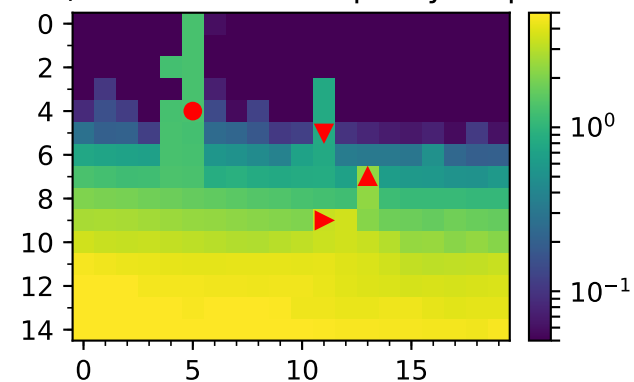
d) Non-NN disparity map



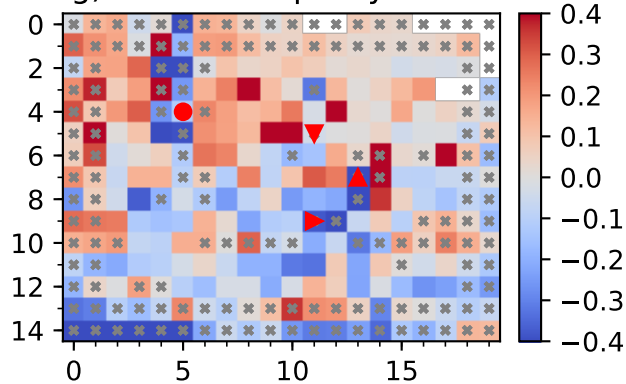
e) Neural network disparity output



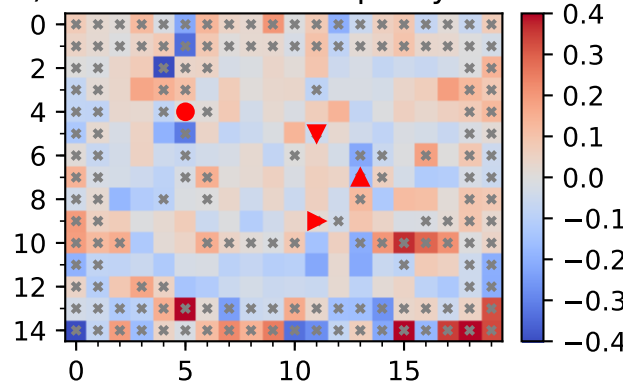
f) Ground truth disparity map



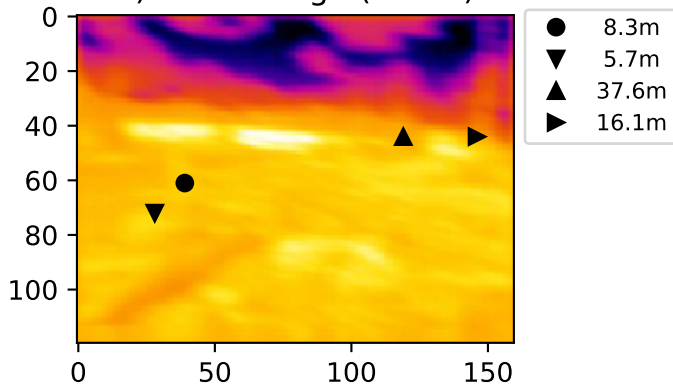
g) Non-NN disparity errors



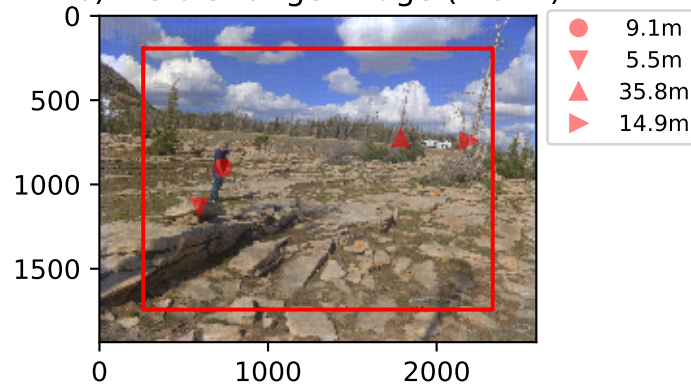
h) Neural network disparity errors



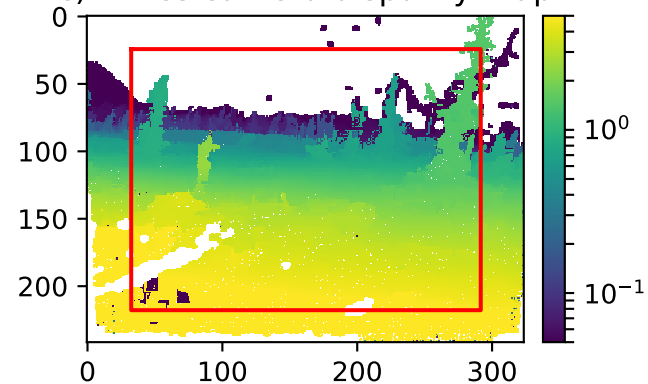
a) LWIR image (1 of 4)



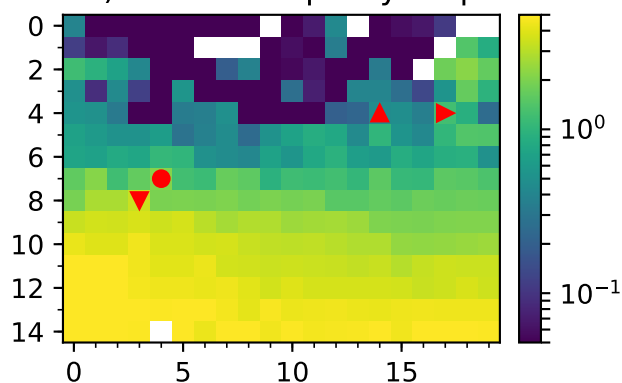
b) Visible range image (1 of 4)



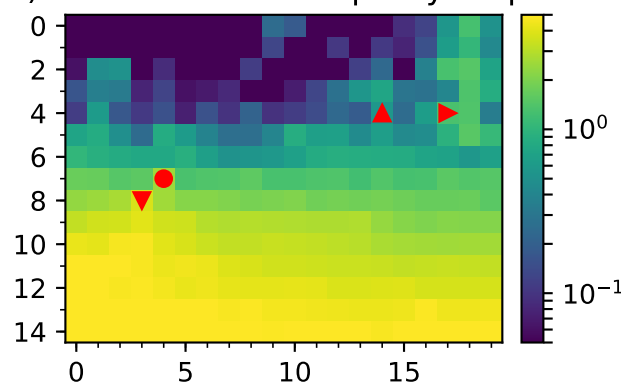
c) Hi-res camera disparity map



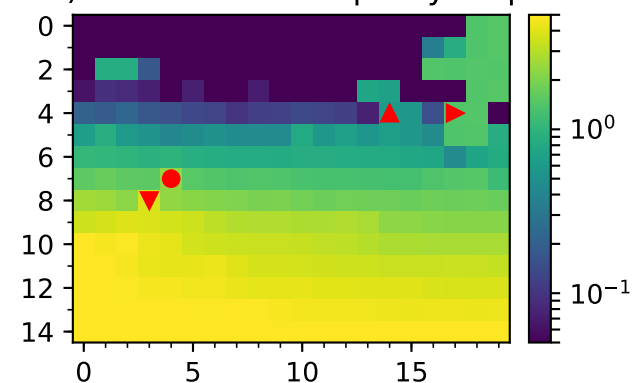
d) Non-NN disparity map



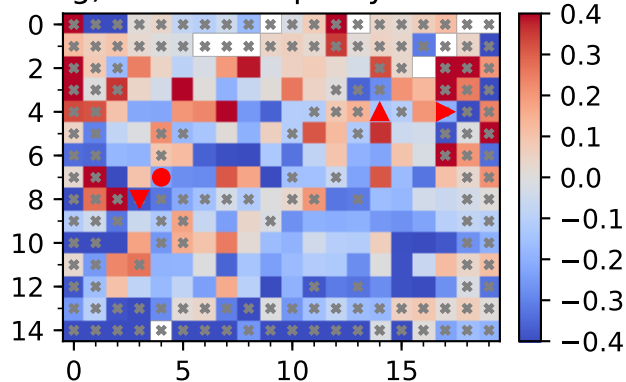
e) Neural network disparity output



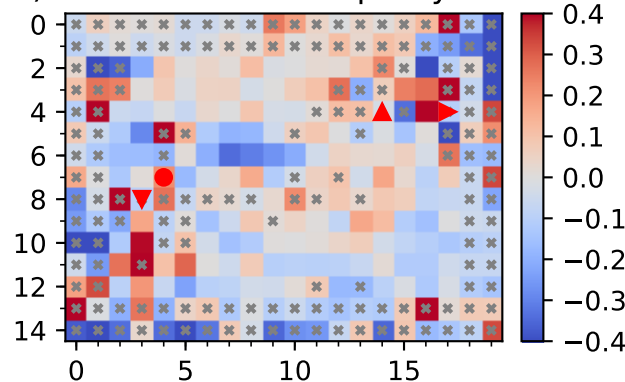
f) Ground truth disparity map



g) Non-NN disparity errors

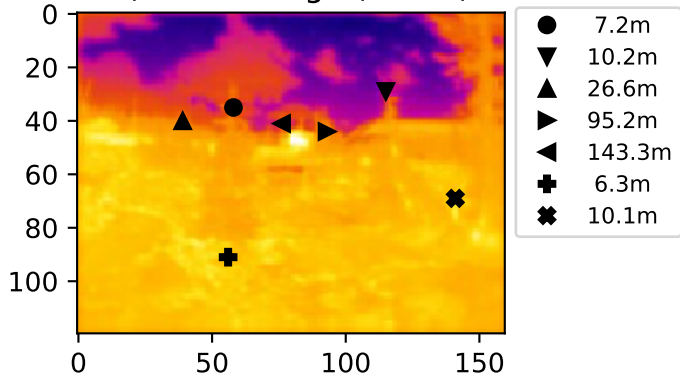


h) Neural network disparity errors

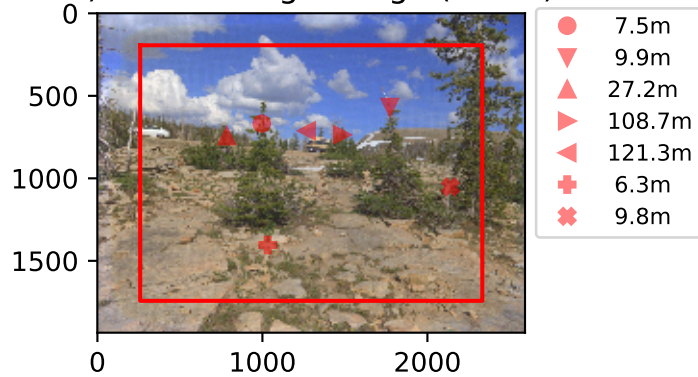


1562390243_047919: No people, trees.

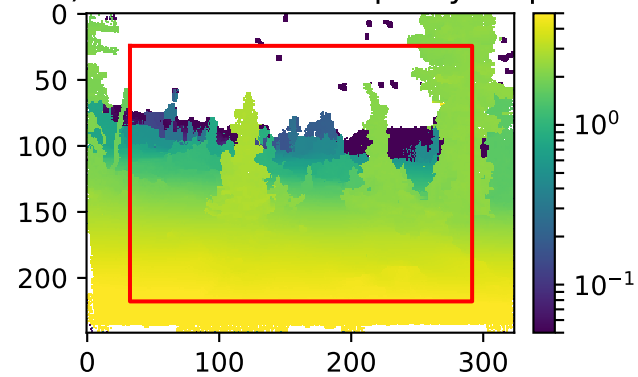
a) LWIR image (1 of 4)



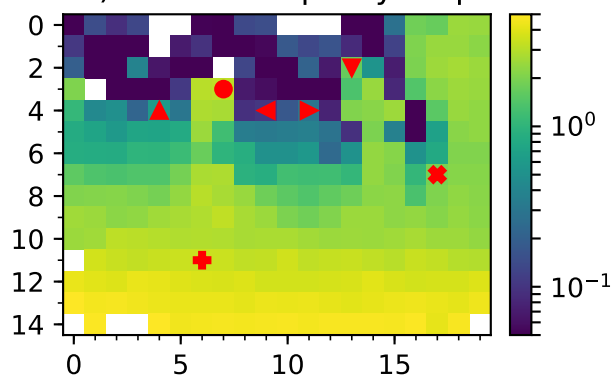
b) Visible range image (1 of 4)



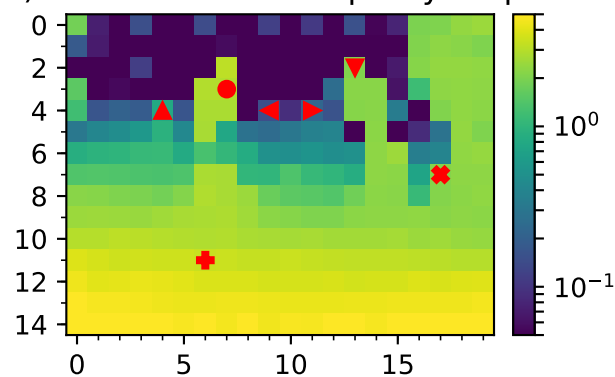
c) Hi-res camera disparity map



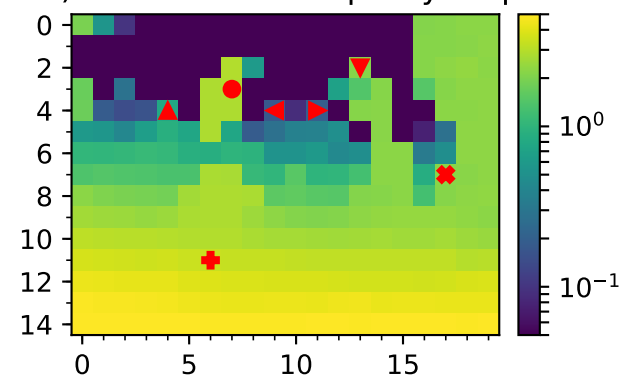
d) Non-NN disparity map



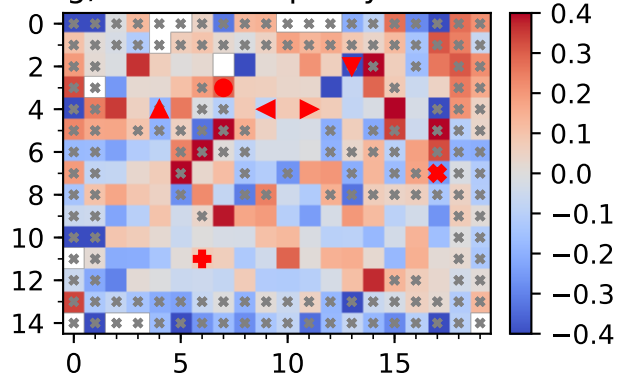
e) Neural network disparity output



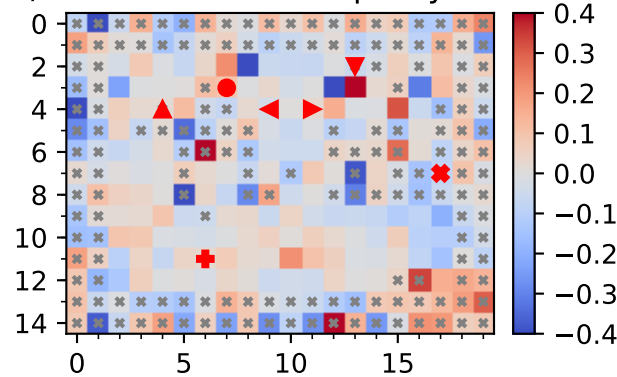
f) Ground truth disparity map



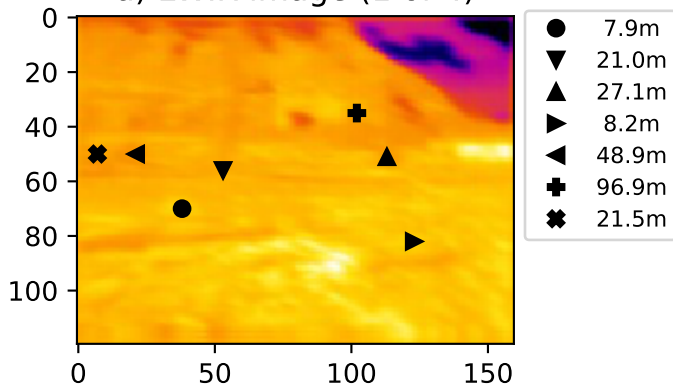
g) Non-NN disparity errors



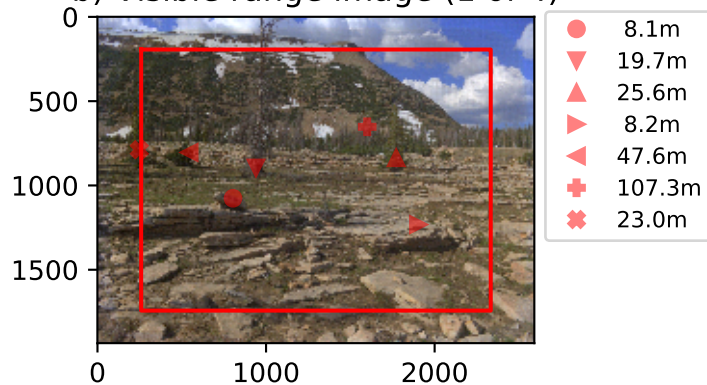
h) Neural network disparity errors



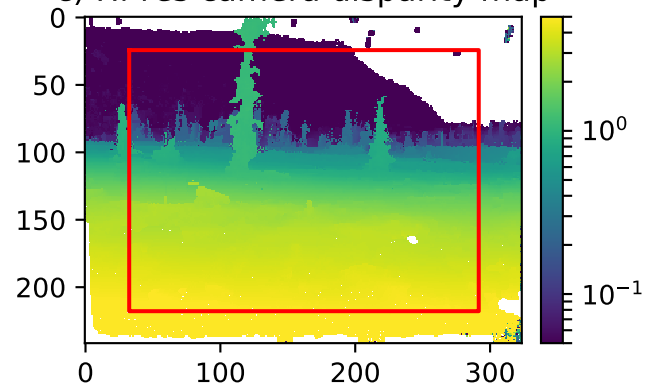
a) LWIR image (1 of 4)



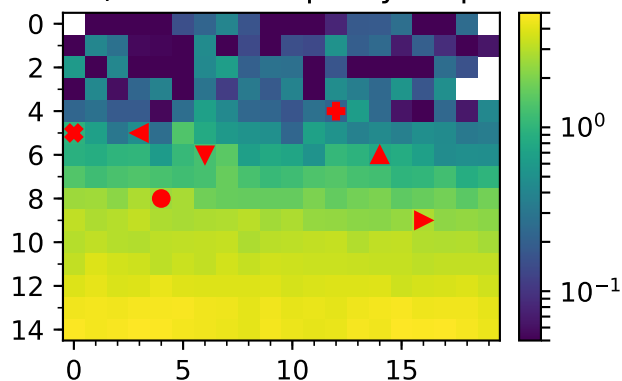
b) Visible range image (1 of 4)



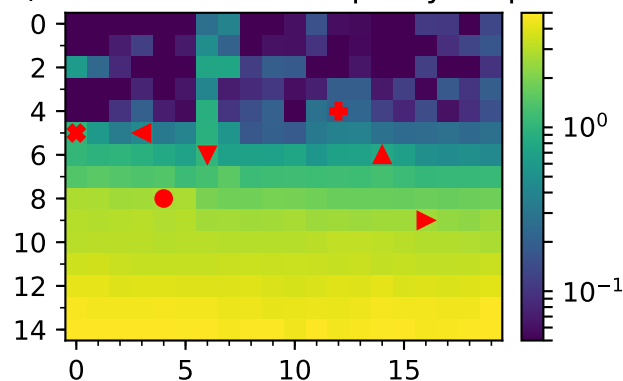
c) Hi-res camera disparity map



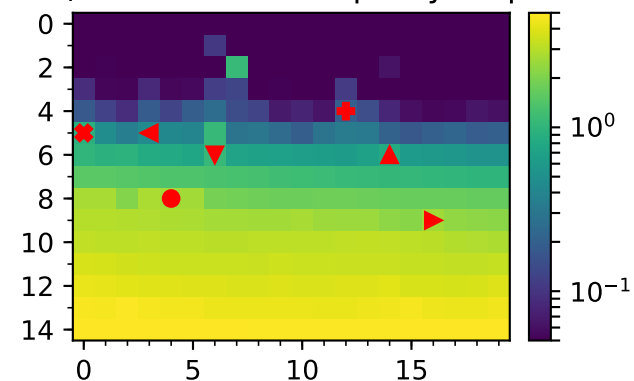
d) Non-NN disparity map



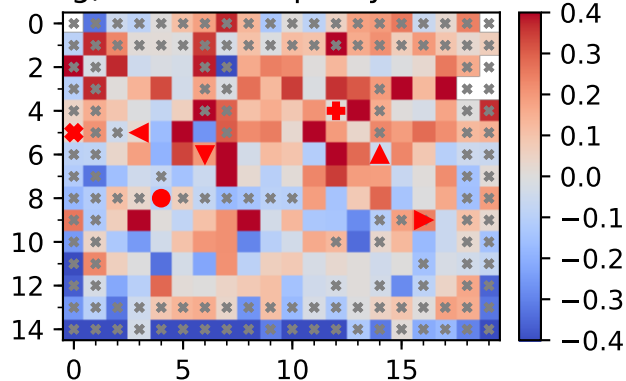
e) Neural network disparity output



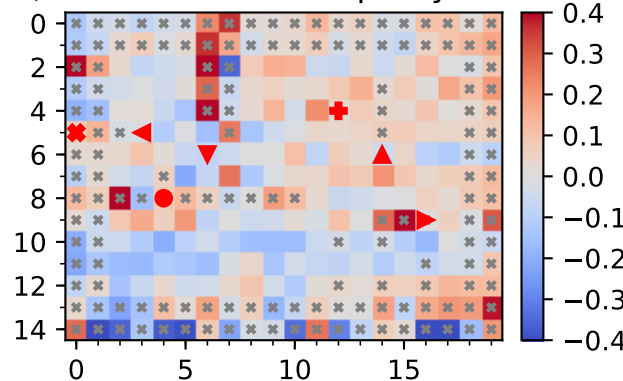
f) Ground truth disparity map



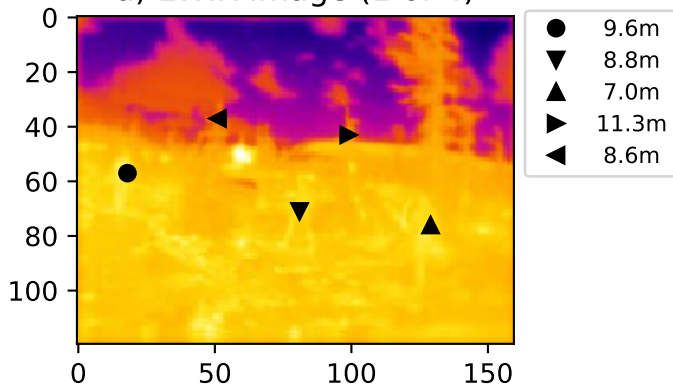
g) Non-NN disparity errors



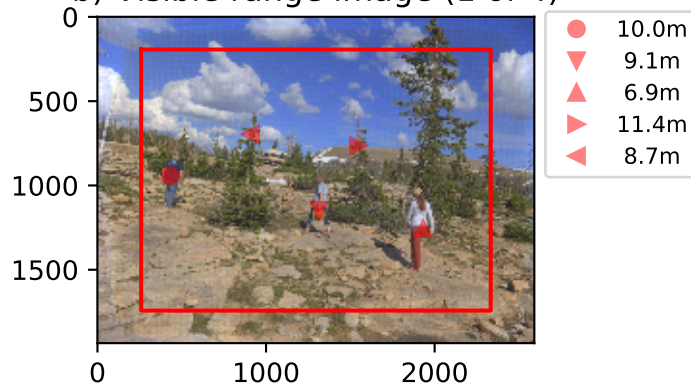
h) Neural network disparity errors



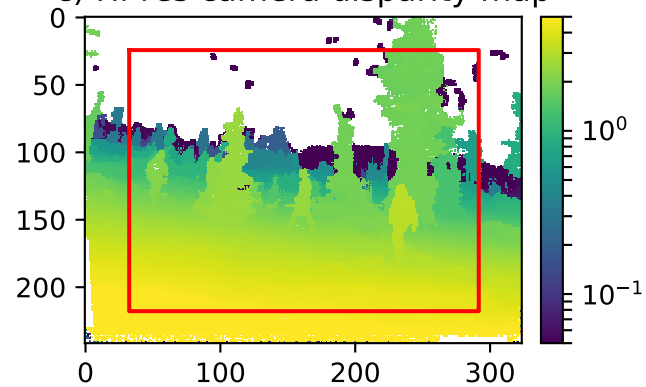
a) LWIR image (1 of 4)



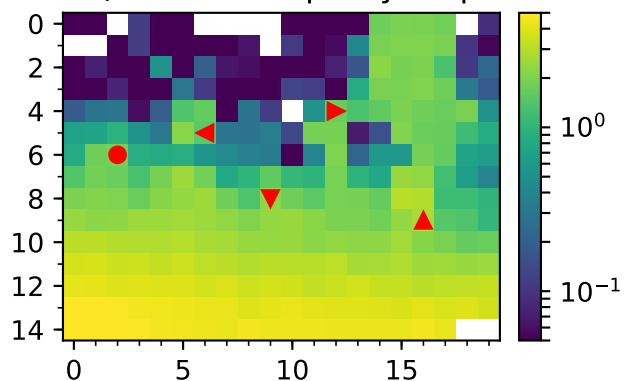
b) Visible range image (1 of 4)



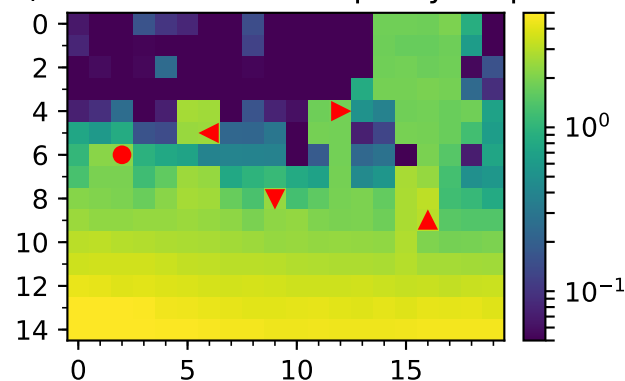
c) Hi-res camera disparity map



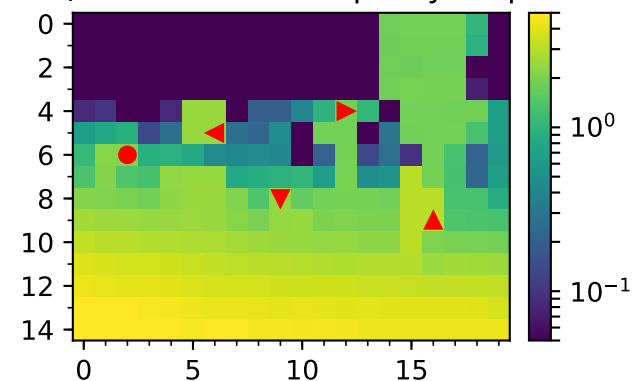
d) Non-NN disparity map



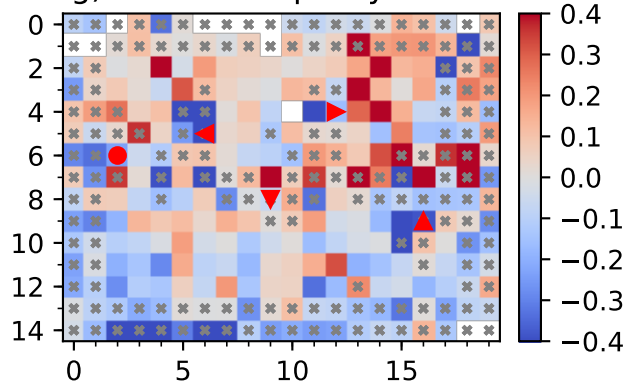
e) Neural network disparity output



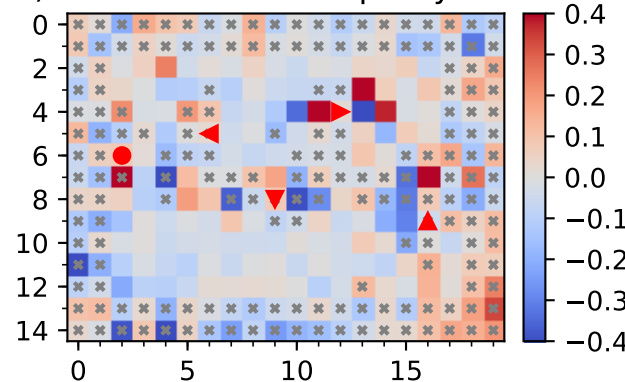
f) Ground truth disparity map



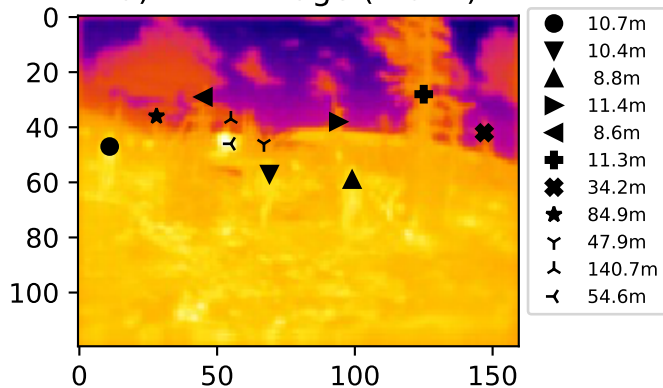
g) Non-NN disparity errors



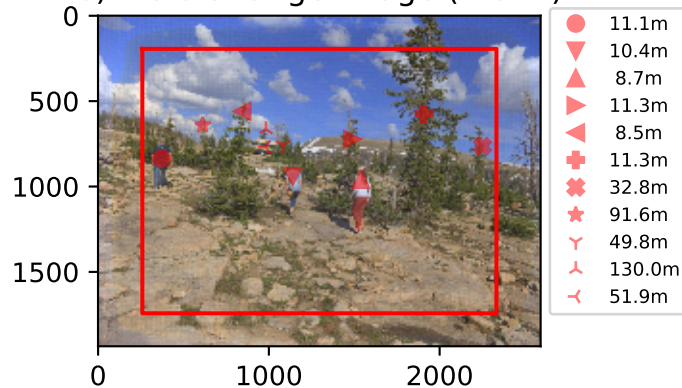
h) Neural network disparity errors



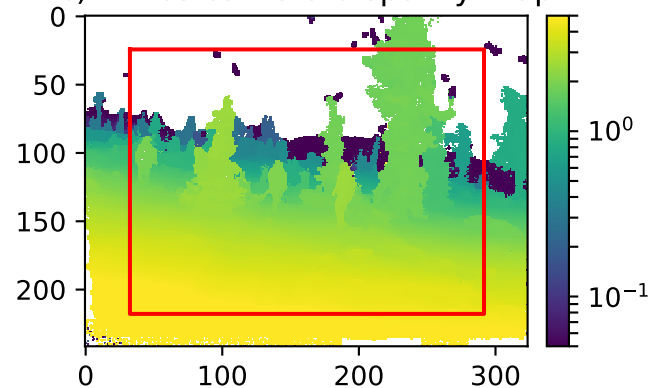
a) LWIR image (1 of 4)



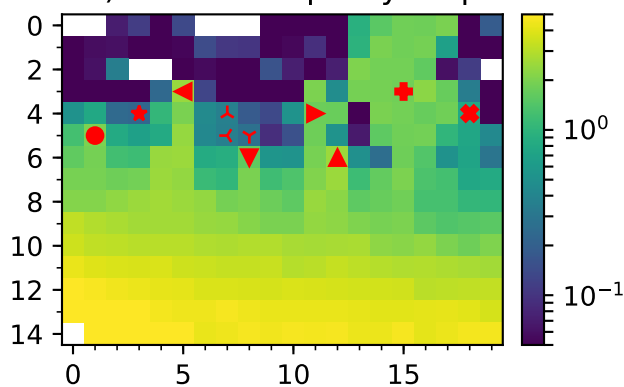
b) Visible range image (1 of 4)



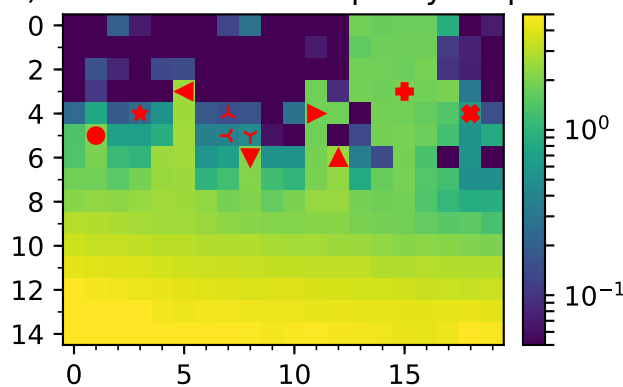
c) Hi-res camera disparity map



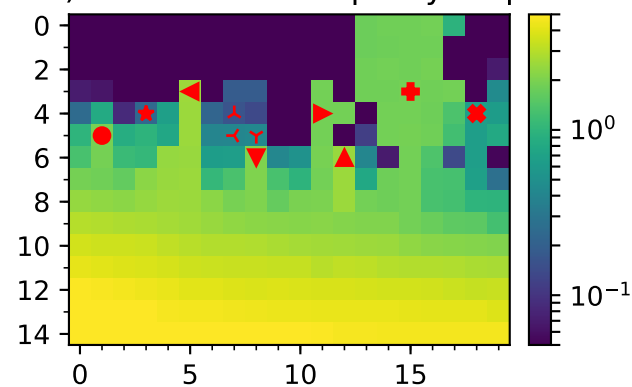
d) Non-NN disparity map



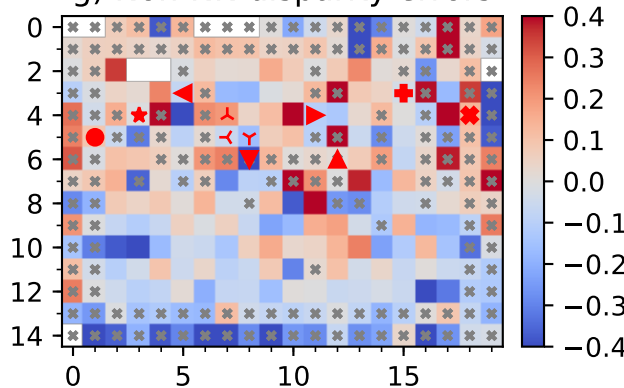
e) Neural network disparity output



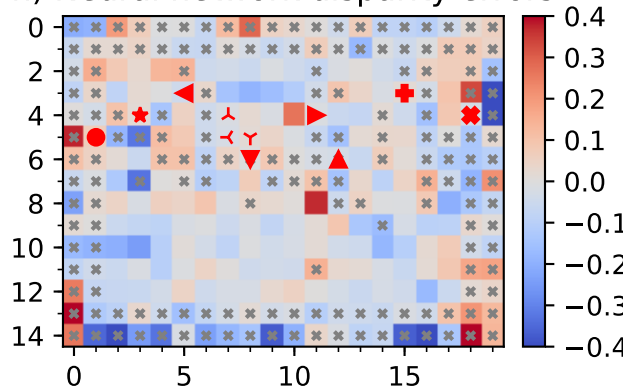
f) Ground truth disparity map



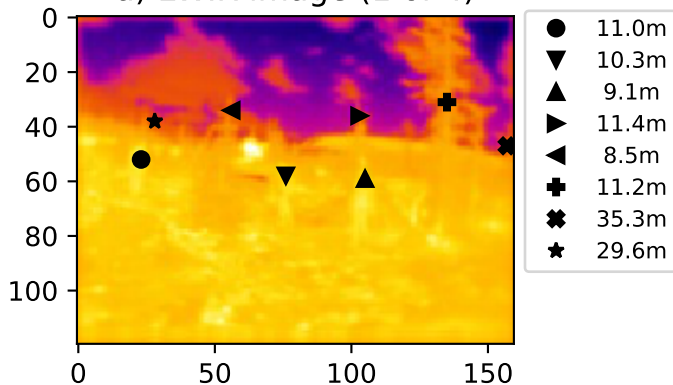
g) Non-NN disparity errors



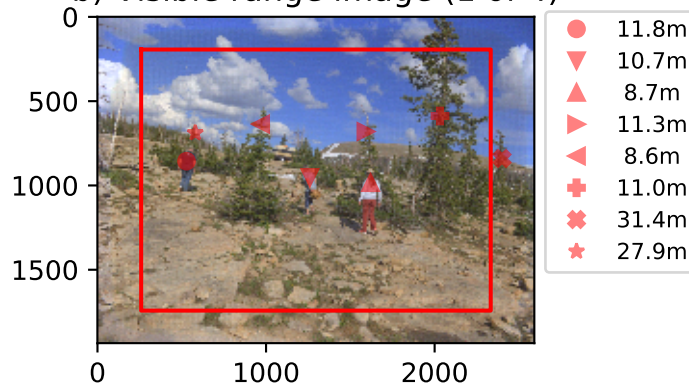
h) Neural network disparity errors



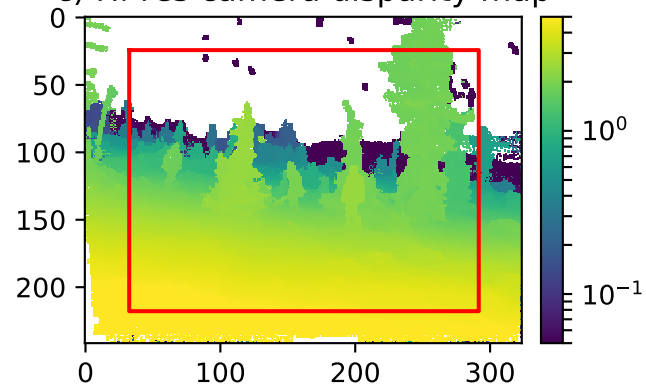
a) LWIR image (1 of 4)



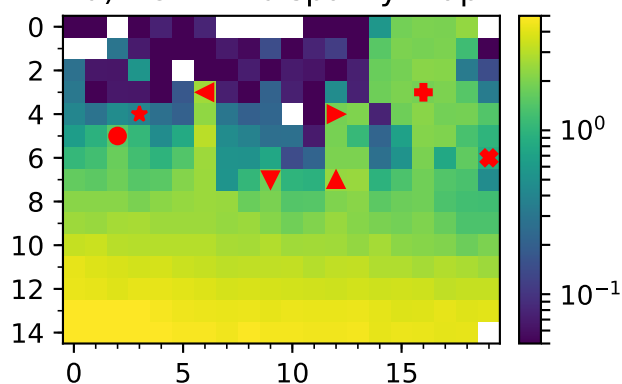
b) Visible range image (1 of 4)



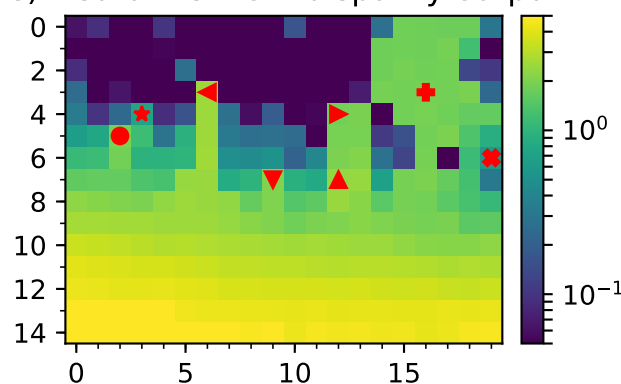
c) Hi-res camera disparity map



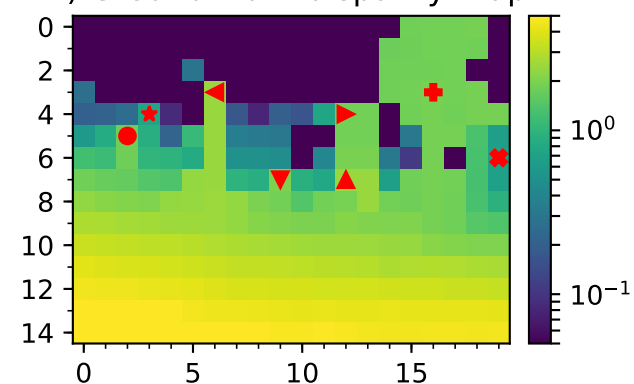
d) Non-NN disparity map



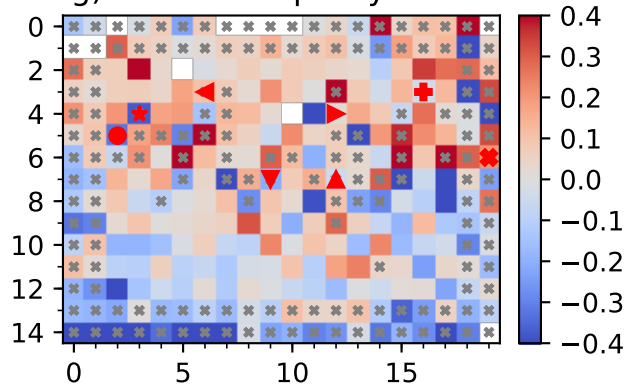
e) Neural network disparity output



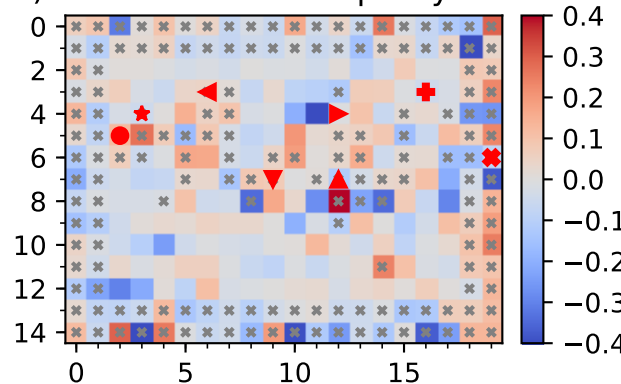
f) Ground truth disparity map



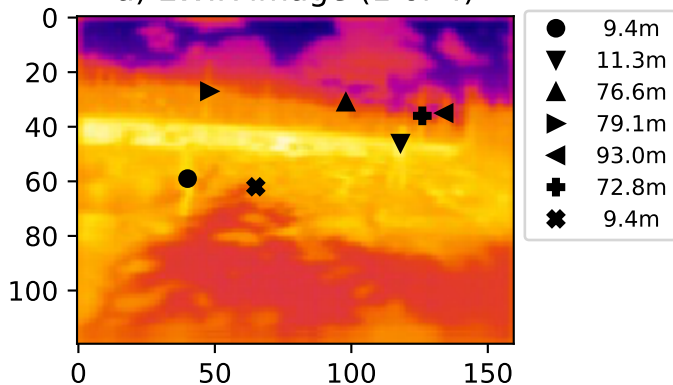
g) Non-NN disparity errors



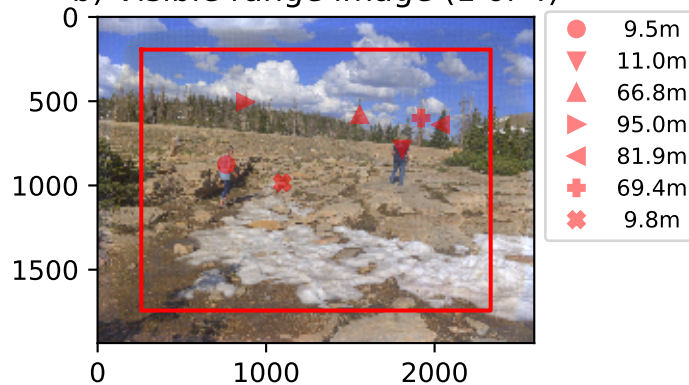
h) Neural network disparity errors



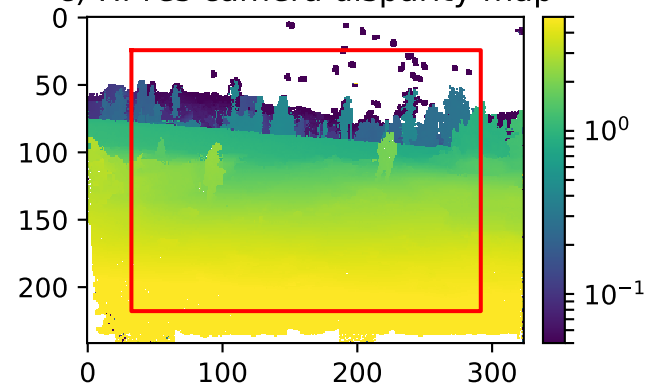
a) LWIR image (1 of 4)



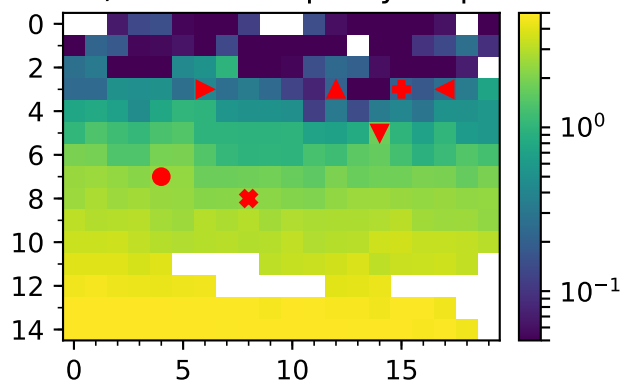
b) Visible range image (1 of 4)



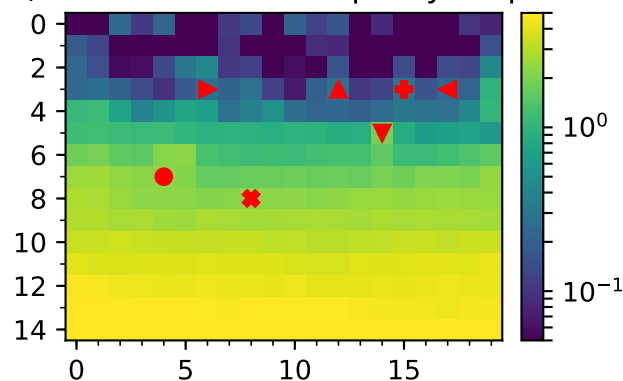
c) Hi-res camera disparity map



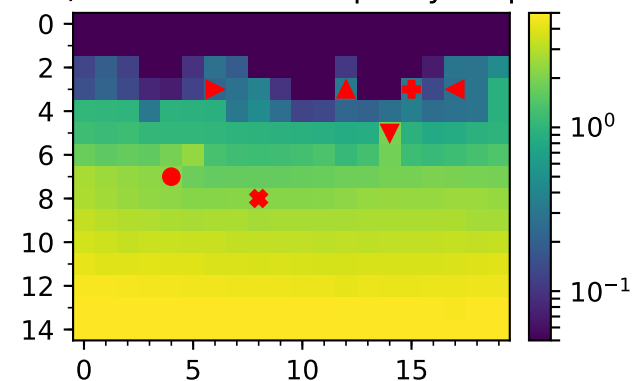
d) Non-NN disparity map



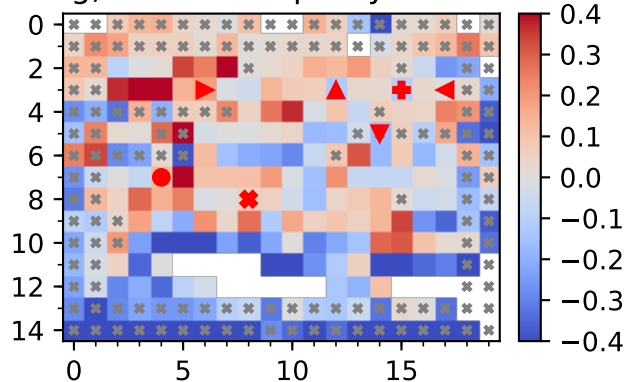
e) Neural network disparity output



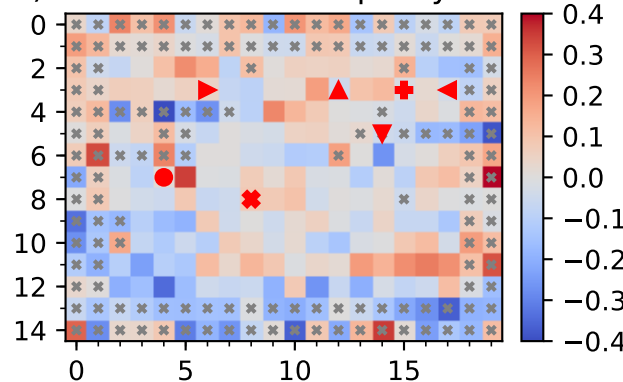
f) Ground truth disparity map



g) Non-NN disparity errors

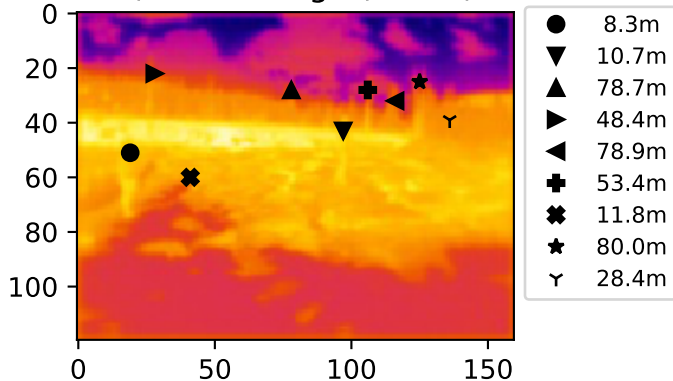


h) Neural network disparity errors

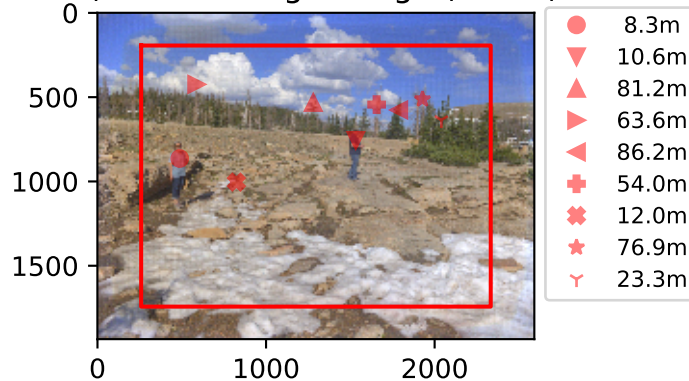


1562390318_833313: Two persons, trees.

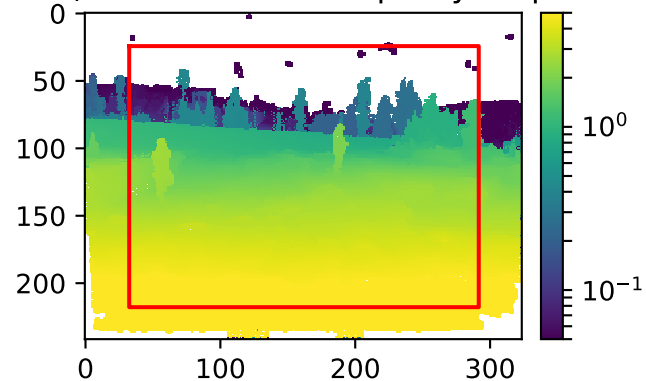
a) LWIR image (1 of 4)



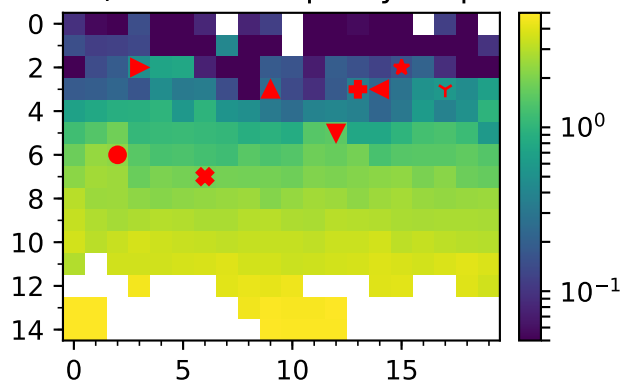
b) Visible range image (1 of 4)



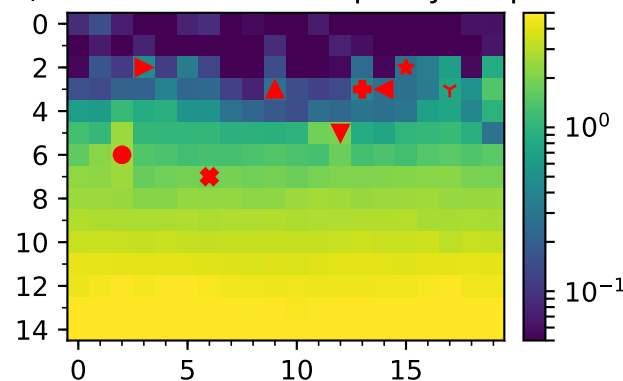
c) Hi-res camera disparity map



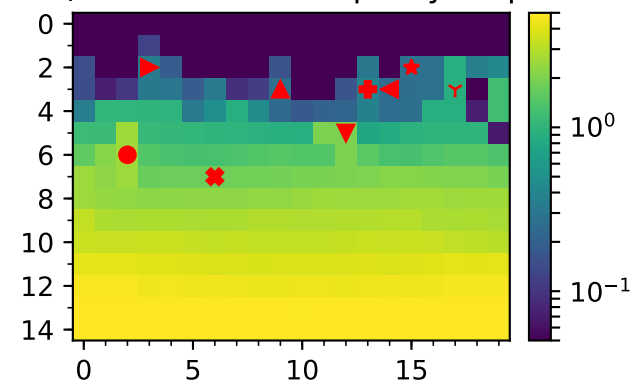
d) Non-NN disparity map



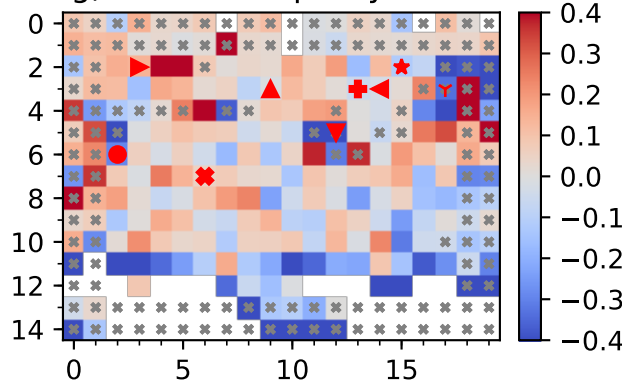
e) Neural network disparity output



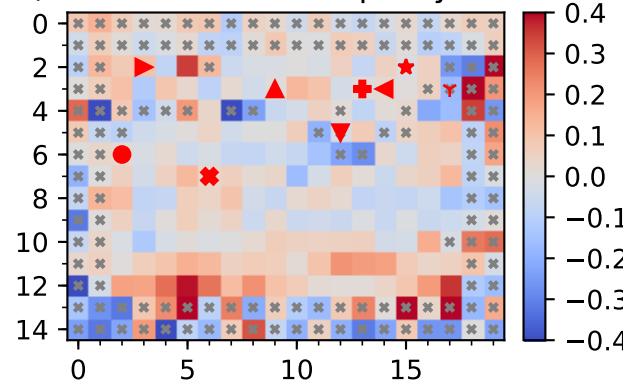
f) Ground truth disparity map



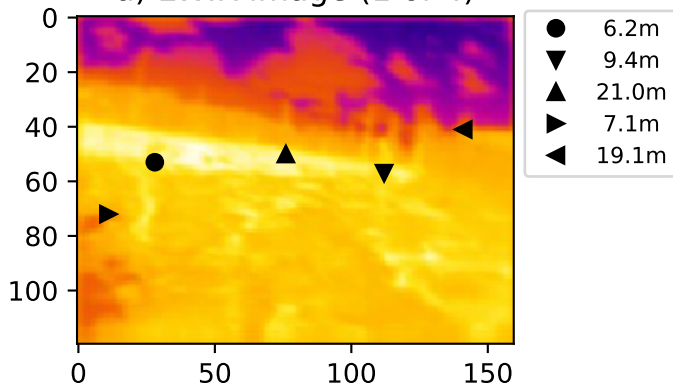
g) Non-NN disparity errors



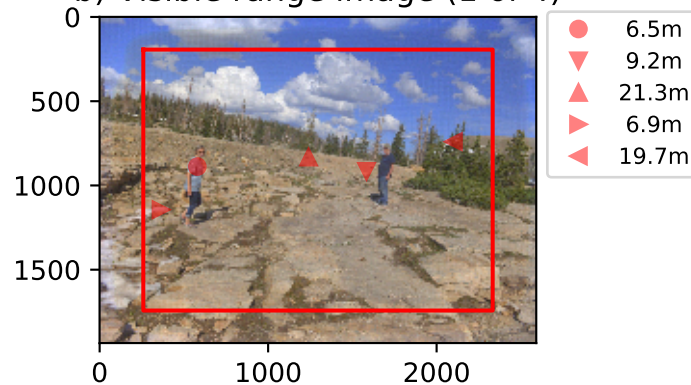
h) Neural network disparity errors



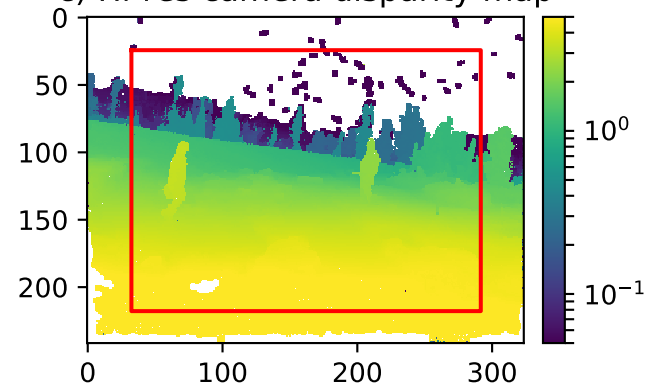
a) LWIR image (1 of 4)



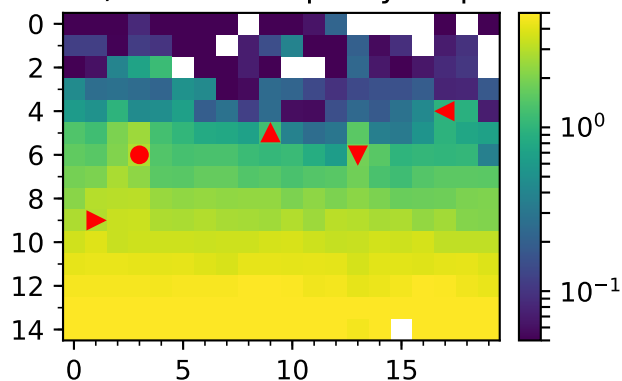
b) Visible range image (1 of 4)



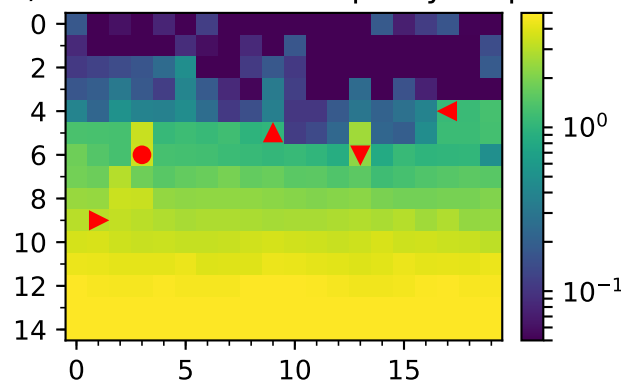
c) Hi-res camera disparity map



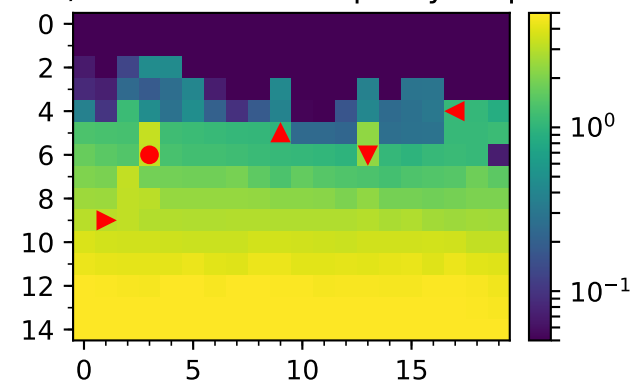
d) Non-NN disparity map



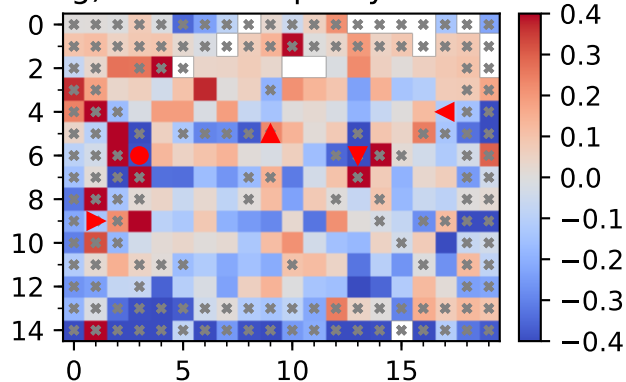
e) Neural network disparity output



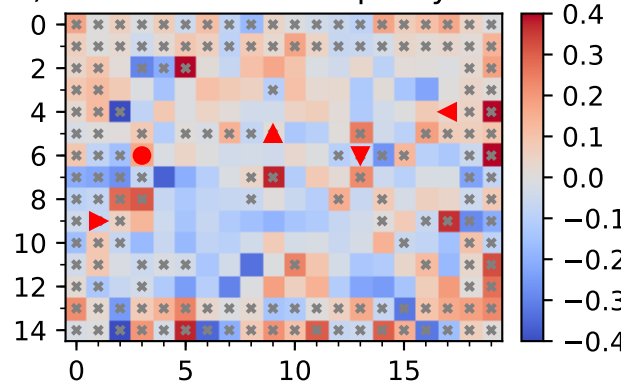
f) Ground truth disparity map



g) Non-NN disparity errors

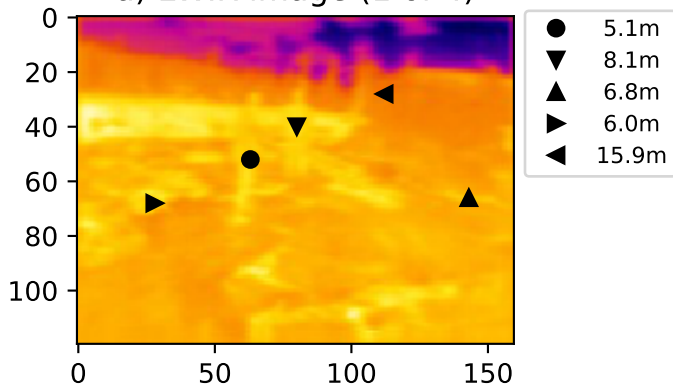


h) Neural network disparity errors

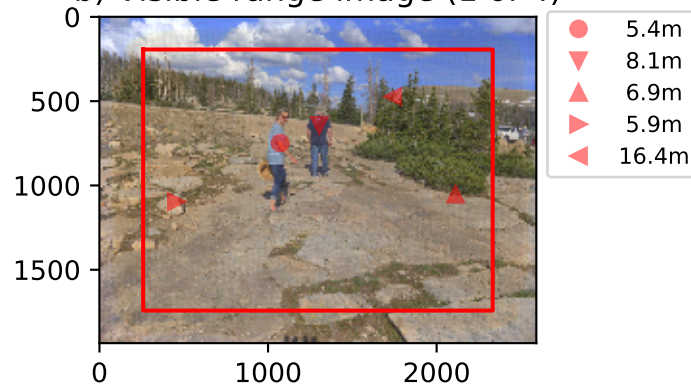


1562390331_483132: Two persons, trees.

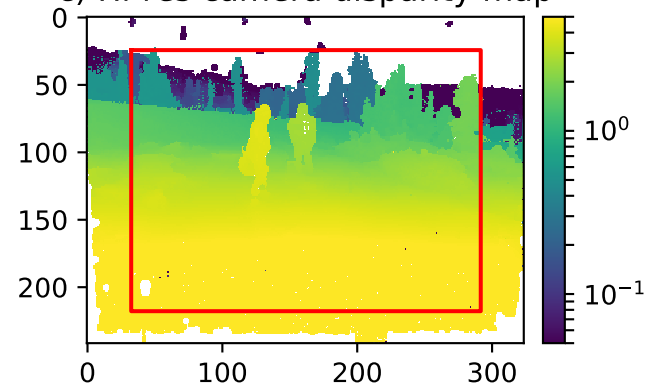
a) LWIR image (1 of 4)



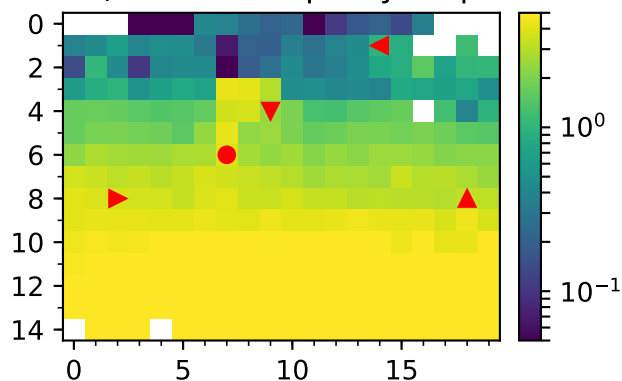
b) Visible range image (1 of 4)



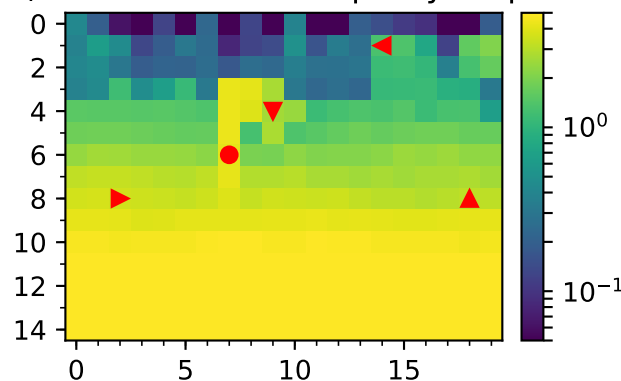
c) Hi-res camera disparity map



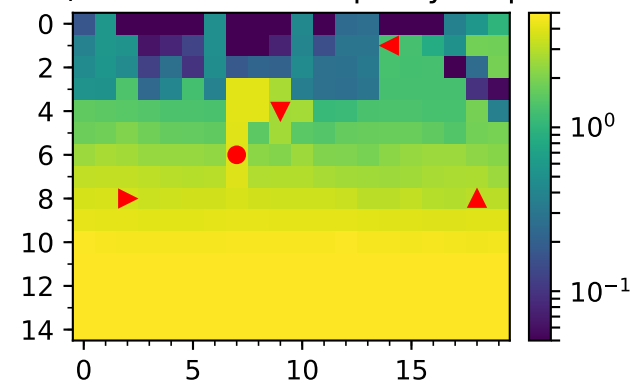
d) Non-NN disparity map



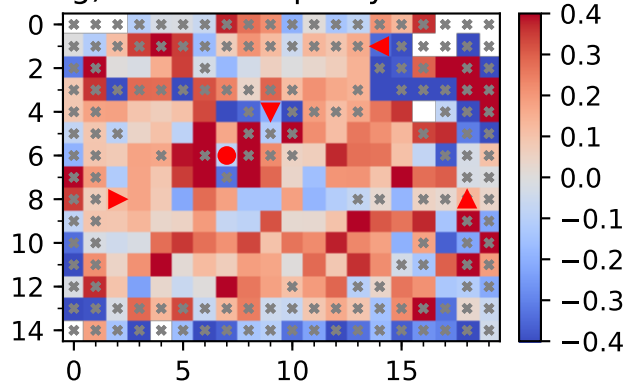
e) Neural network disparity output



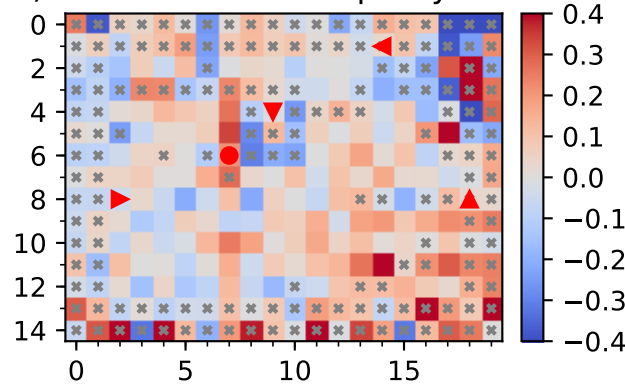
f) Ground truth disparity map

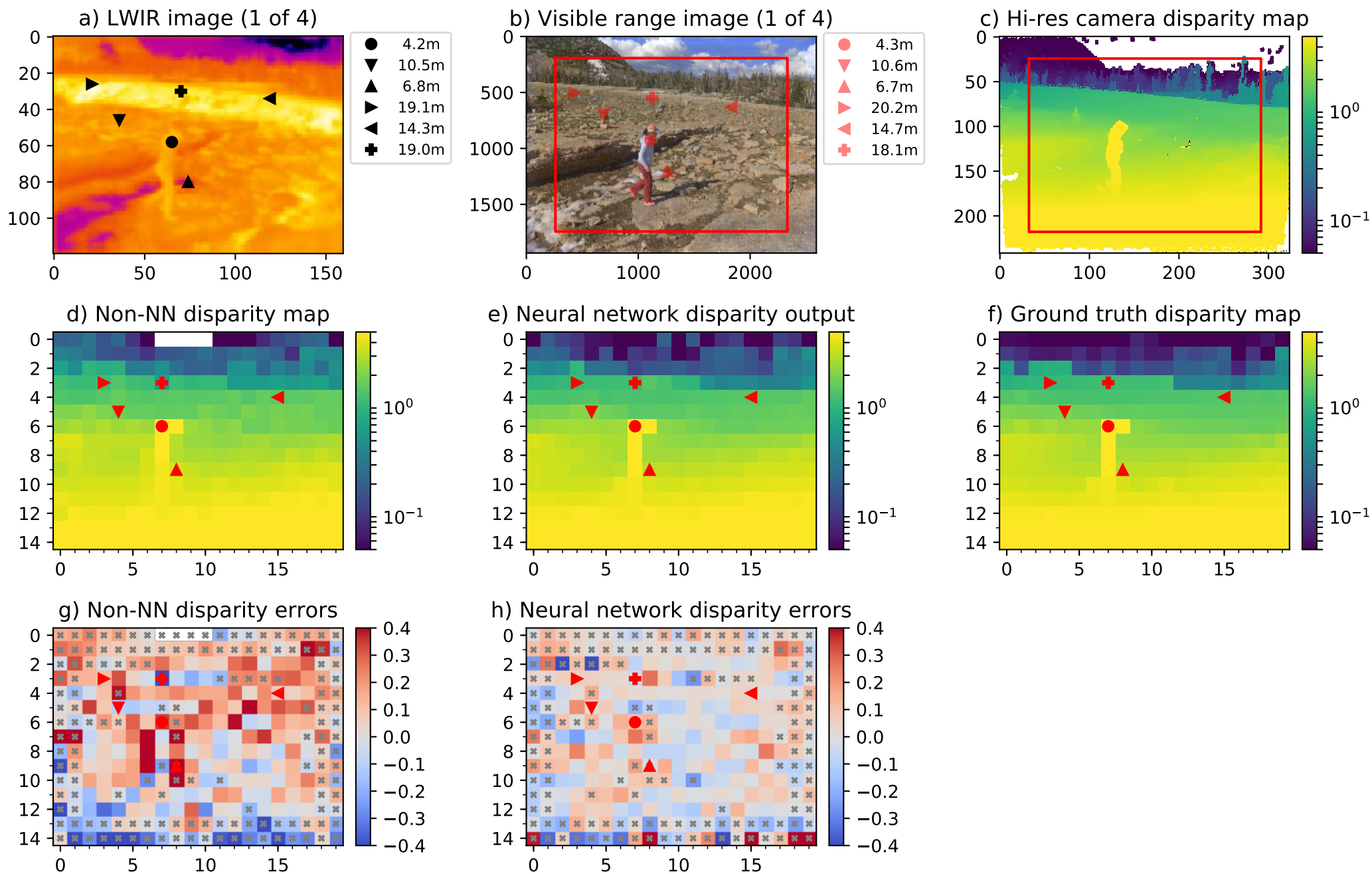


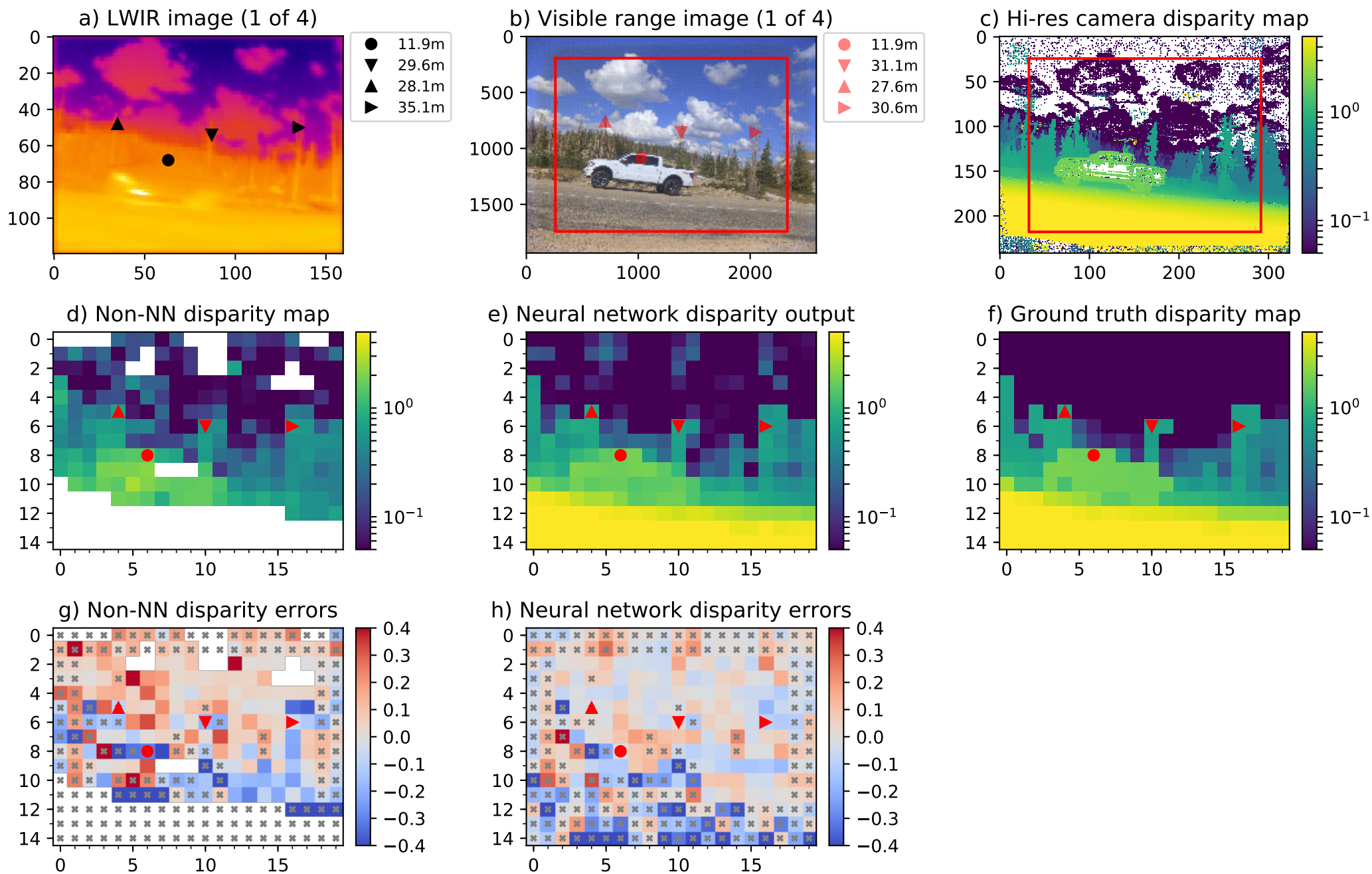
g) Non-NN disparity errors

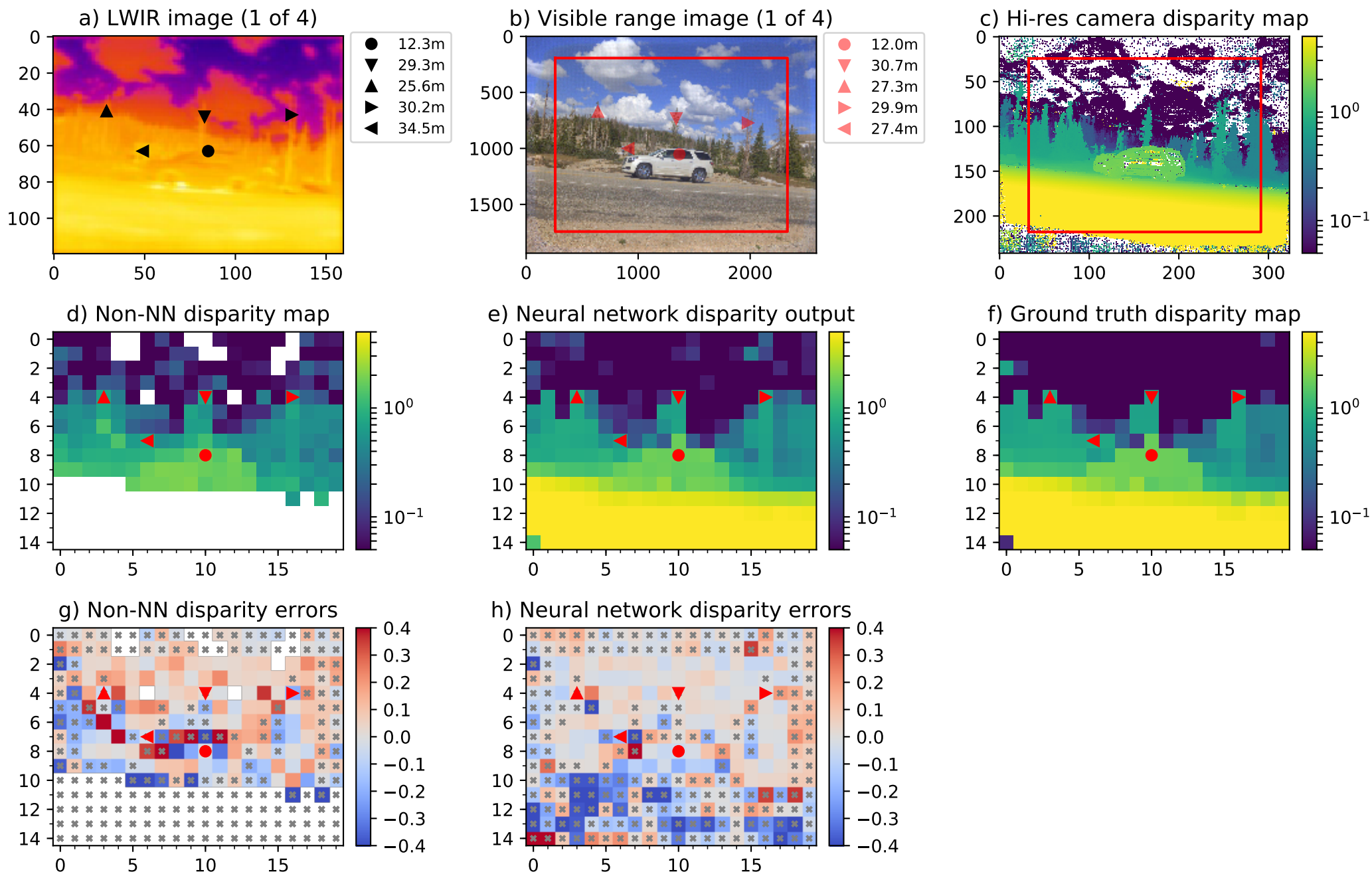


h) Neural network disparity errors

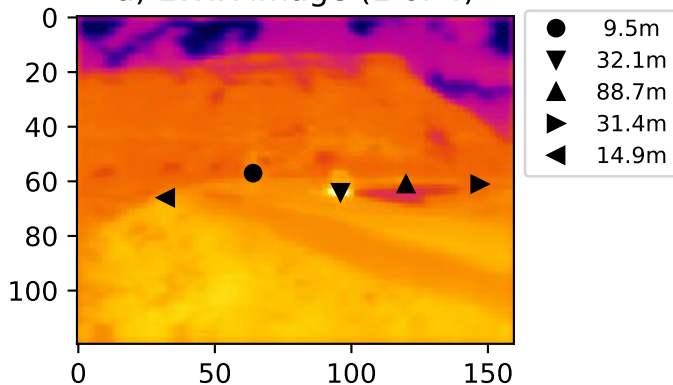




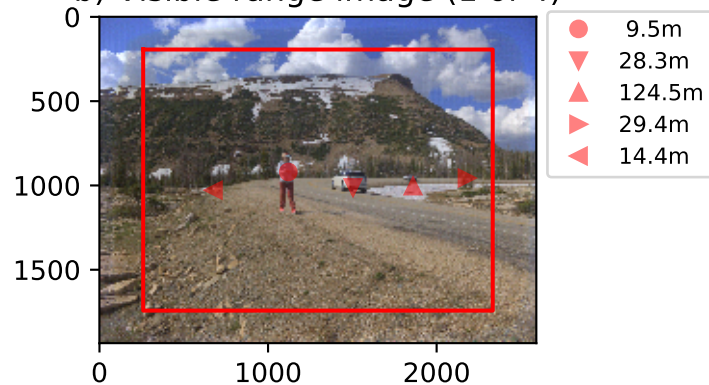




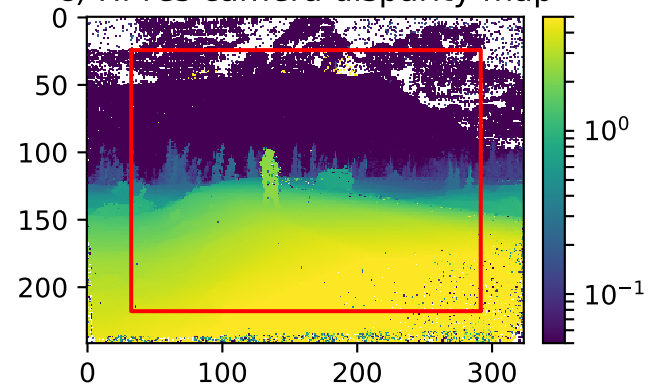
a) LWIR image (1 of 4)



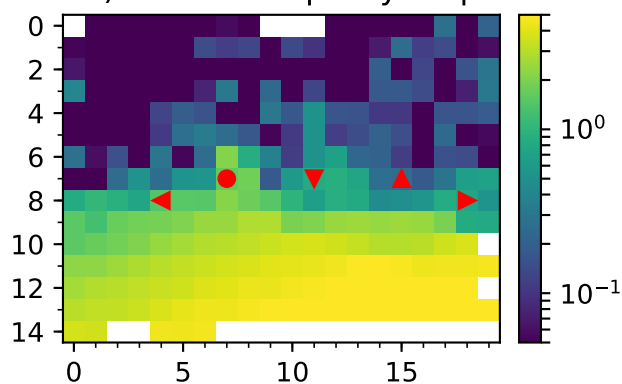
b) Visible range image (1 of 4)



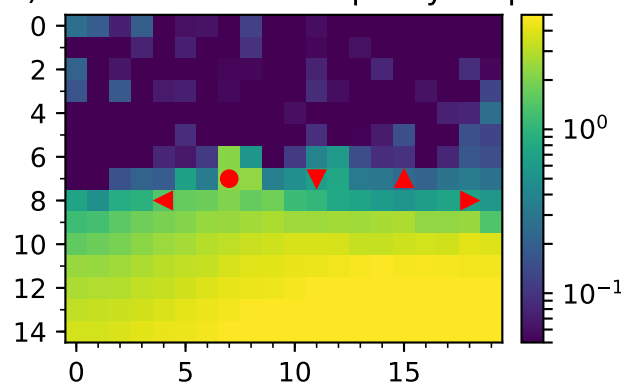
c) Hi-res camera disparity map



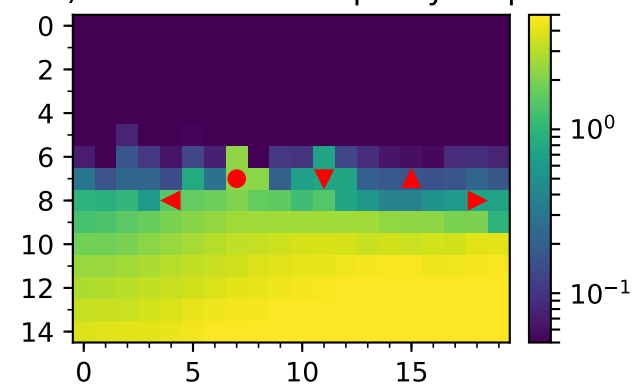
d) Non-NN disparity map



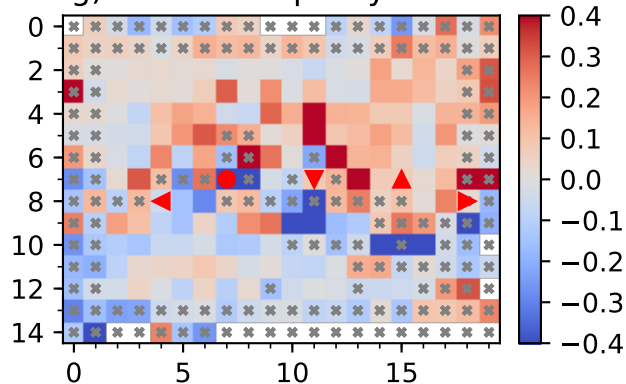
e) Neural network disparity output



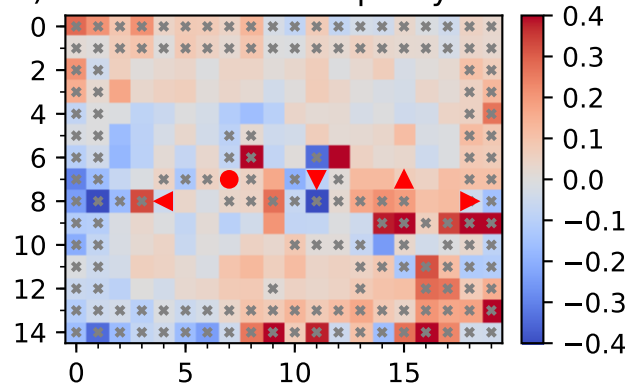
f) Ground truth disparity map



g) Non-NN disparity errors

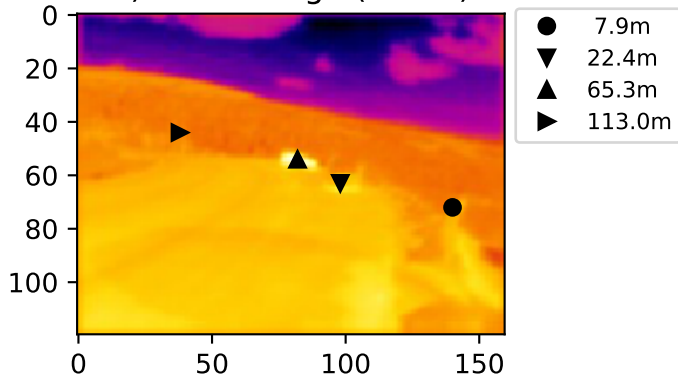


h) Neural network disparity errors

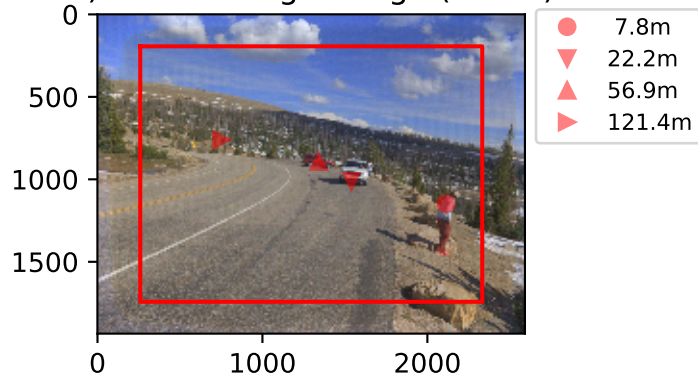


1562390435_873048: Single person, two parked cars.

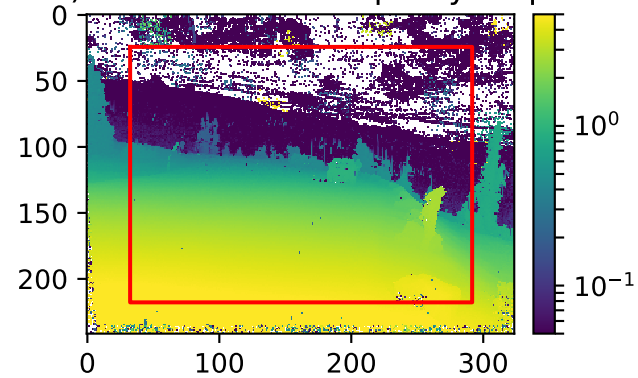
a) LWIR image (1 of 4)



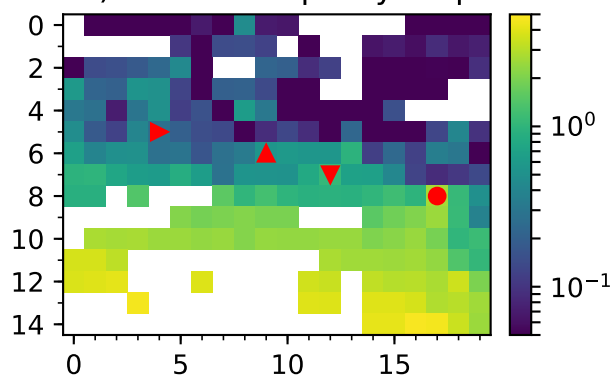
b) Visible range image (1 of 4)



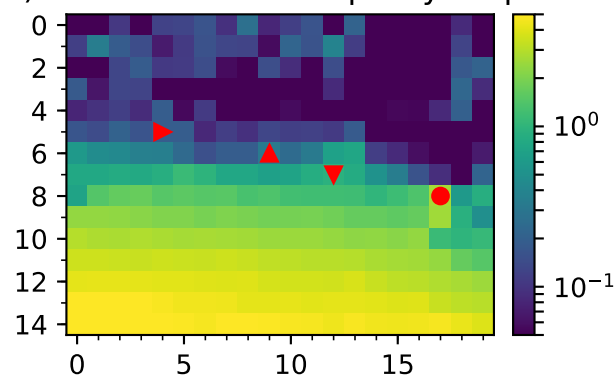
c) Hi-res camera disparity map



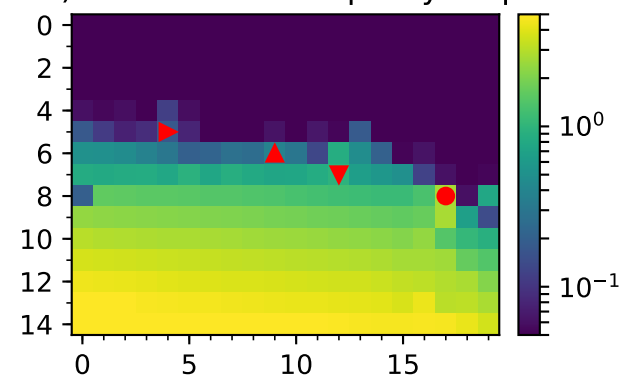
d) Non-NN disparity map



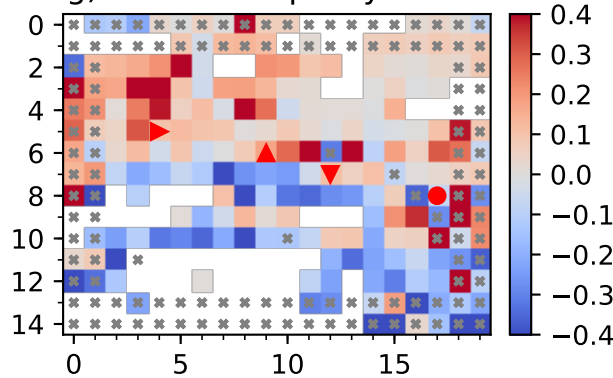
e) Neural network disparity output



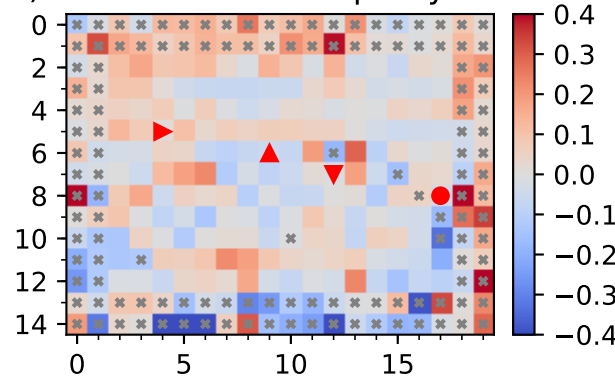
f) Ground truth disparity map



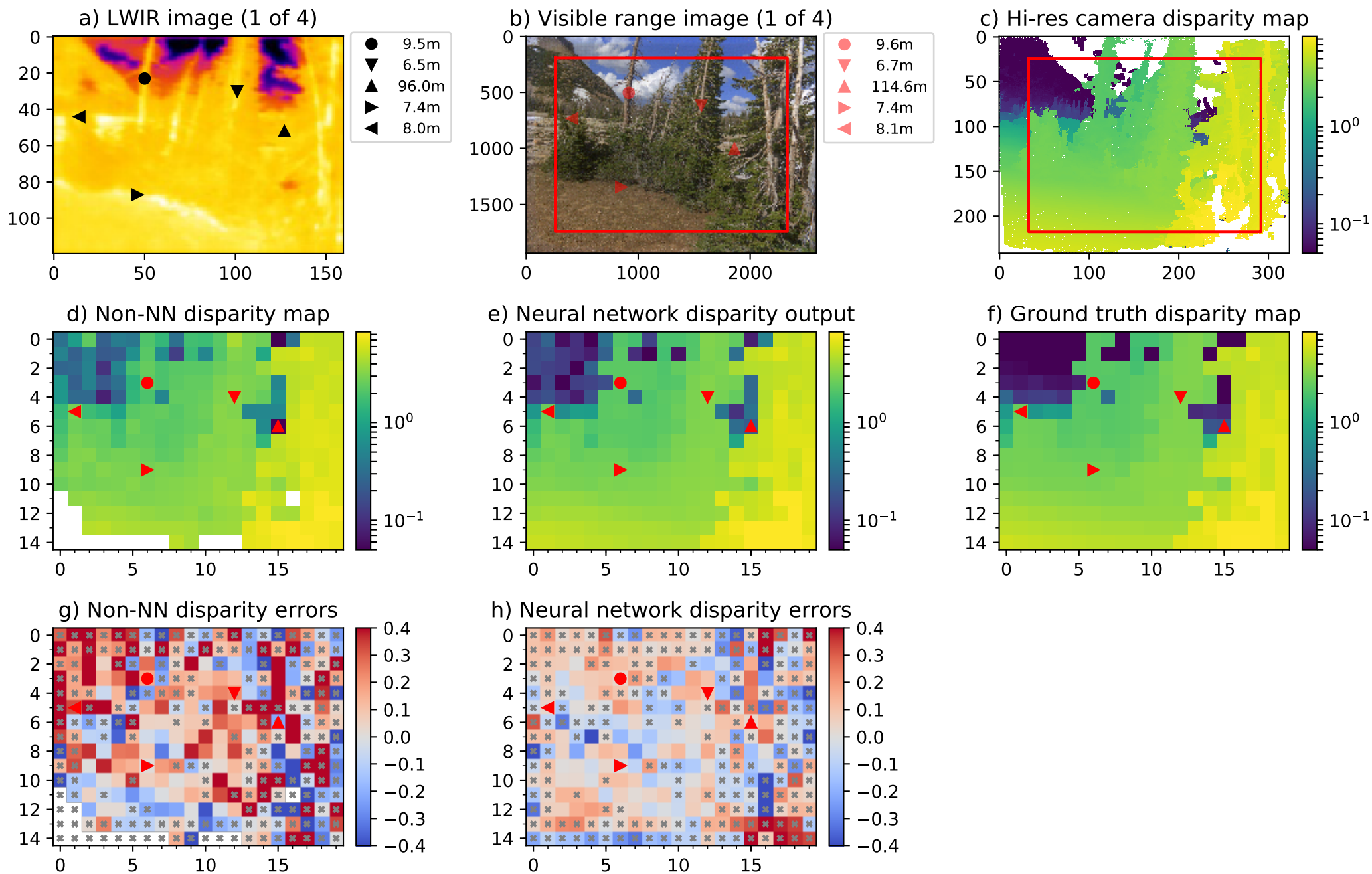
g) Non-NN disparity errors



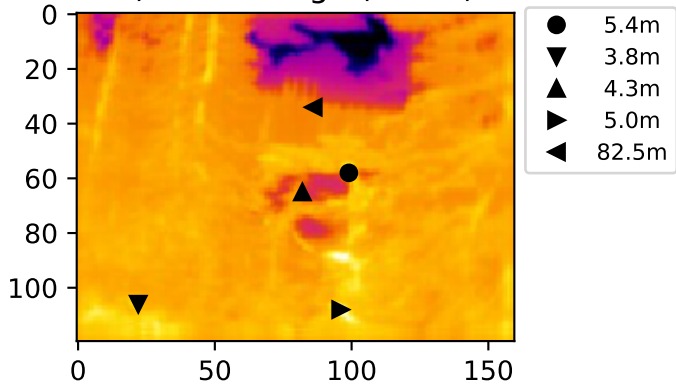
h) Neural network disparity errors



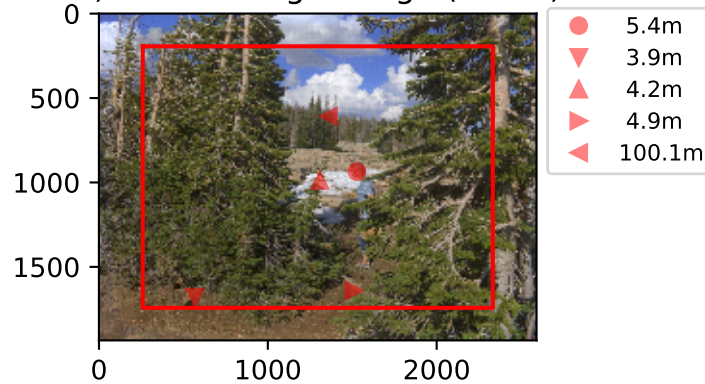
1562390456_842237: Close trees.



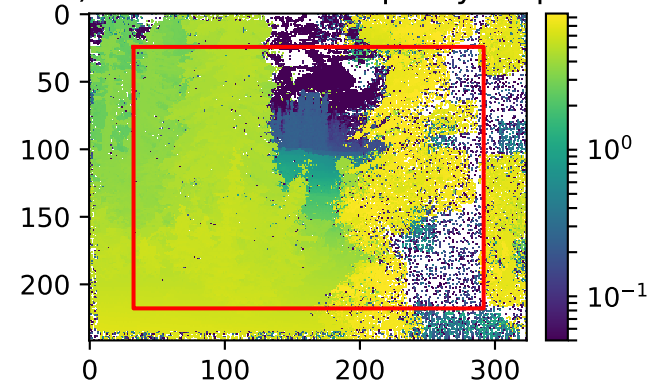
a) LWIR image (1 of 4)



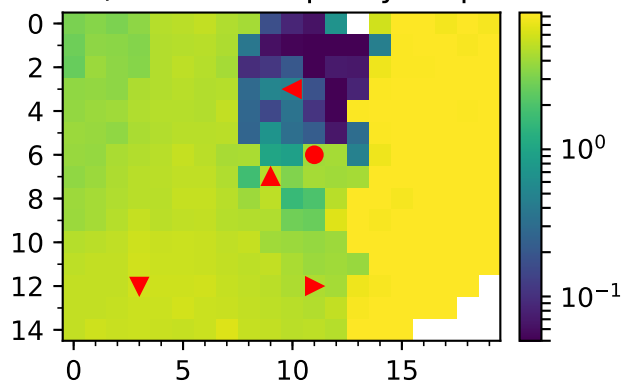
b) Visible range image (1 of 4)



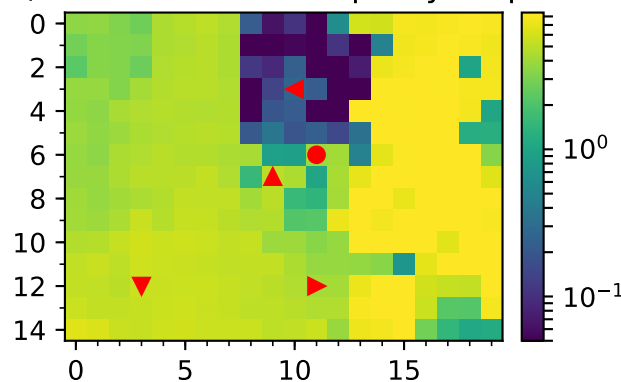
c) Hi-res camera disparity map



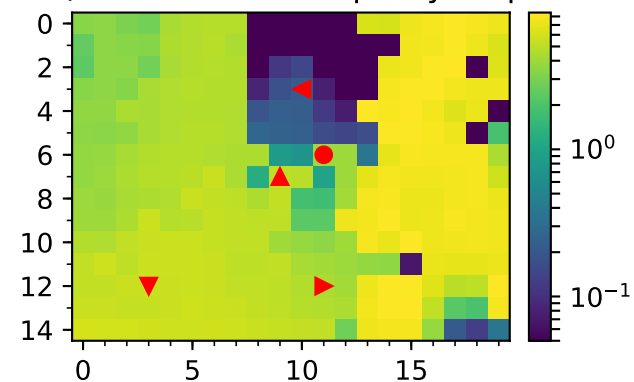
d) Non-NN disparity map



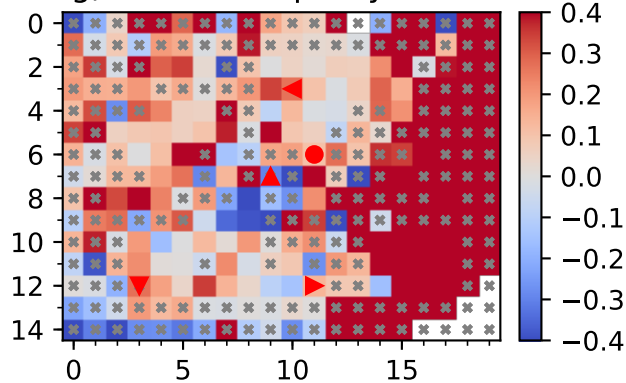
e) Neural network disparity output



f) Ground truth disparity map



g) Non-NN disparity errors



h) Neural network disparity errors

